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1.1 Introduction

WebAssembly (abbreviated Wasm\(^2\)) is a safe, portable, low-level code format designed for efficient execution and compact representation. Its main goal is to enable high performance applications on the Web, but it does not make any Web-specific assumptions or provide Web-specific features, so it can be employed in other environments as well.

WebAssembly is an open standard developed by a W3C Community Group\(^1\).

This document describes version 1.0 of the core WebAssembly standard. It is intended that it will be superseded by new incremental releases with additional features in the future.

1.1.1 Design Goals

The design goals of WebAssembly are the following:

- Fast, safe, and portable semantics:
  - Fast: executes with near native code performance, taking advantage of capabilities common to all contemporary hardware.
  - Safe: code is validated and executes in a memory-safe\(^3\), sandboxed environment preventing data corruption or security breaches.
  - Well-defined: fully and precisely defines valid programs and their behavior in a way that is easy to reason about informally and formally.
  - Hardware-independent: can be compiled on all modern architectures, desktop or mobile devices and embedded systems alike.
  - Language-independent: does not privilege any particular language, programming model, or object model.
  - Platform-independent: can be embedded in browsers, run as a stand-alone VM, or integrated in other environments.

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\(^1\) https://www.w3.org/community/webassembly/

\(^2\) A contraction of “WebAssembly”, not an acronym, hence not using all-caps.

\(^3\) No program can break WebAssembly’s memory model. Of course, it cannot guarantee that an unsafe language compiling to WebAssembly does not corrupt its own memory layout, e.g. inside WebAssembly’s linear memory.
Open: programs can interoperate with their environment in a simple and universal manner.

- Efficient and portable representation:
  - Compact: has a binary format that is fast to transmit by being smaller than typical text or native code formats.
  - Modular: programs can be split up in smaller parts that can be transmitted, cached, and consumed separately.
  - Efficient: can be decoded, validated, and compiled in a fast single pass, equally with either just-in-time (JIT) or ahead-of-time (AOT) compilation.
  - Streamable: allows decoding, validation, and compilation to begin as soon as possible, before all data has been seen.
  - Parallelizable: allows decoding, validation, and compilation to be split into many independent parallel tasks.
  - Portable: makes no architectural assumptions that are not broadly supported across modern hardware.

WebAssembly code is also intended to be easy to inspect and debug, especially in environments like web browsers, but such features are beyond the scope of this specification.

1.1.2 Scope

At its core, WebAssembly is a virtual instruction set architecture (virtual ISA). As such, it has many use cases and can be embedded in many different environments. To encompass their variety and enable maximum reuse, the WebAssembly specification is split and layered into several documents.

This document is concerned with the core ISA layer of WebAssembly. It defines the instruction set, binary encoding, validation, and execution semantics, as well as a textual representation. It does not, however, define how WebAssembly programs can interact with a specific environment they execute in, nor how they are invoked from such an environment.

Instead, this specification is complemented by additional documents defining interfaces to specific embedding environments such as the Web. These will each define a WebAssembly application programming interface (API) suitable for a given environment.

1.1.3 Dependencies

WebAssembly depends on two existing standards:

- IEEE 754-2008, for the representation of floating-point data and the semantics of respective numeric operations.

- Unicode, for the representation of import/export names and the text format.

However, to make this specification self-contained, relevant aspects of the aforementioned standards are defined and formalized as part of this specification, such as the binary representation and rounding of floating-point values, and the value range and UTF-8 encoding of Unicode characters.

Note: The aforementioned standards are the authoritative source of all respective definitions. Formalizations given in this specification are intended to match these definitions. Any discrepancy in the syntax or semantics described is to be considered an error.

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4 http://ieeexplore.ieee.org/document/4610935/
5 http://www.unicode.org/versions/latest/
1.2 Overview

1.2.1 Concepts

WebAssembly encodes a low-level, assembly-like programming language. This language is structured around the following concepts.

Values WebAssembly provides only four basic value types. These are integers and IEEE 754-2008 numbers, each in 32 and 64 bit width. 32 bit integers also serve as Booleans and as memory addresses. The usual operations on these types are available, including the full matrix of conversions between them. There is no distinction between signed and unsigned integer types. Instead, integers are interpreted by respective operations as either unsigned or signed in two’s complement representation.

Instructions The computational model of WebAssembly is based on a stack machine. Code consists of sequences of instructions that are executed in order. Instructions manipulate values on an implicit operand stack and fall into two main categories. Simple instructions perform basic operations on data. They pop arguments from the operand stack and push results back to it. Control instructions alter control flow. Control flow is structured, meaning it is expressed with well-nested constructs such as blocks, loops, and conditionals. Branches can only target such constructs.

Traps Under some conditions, certain instructions may produce a trap, which immediately aborts execution. Traps cannot be handled by WebAssembly code, but are reported to the outside environment, where they typically can be caught.

Functions Code is organized into separate functions. Each function takes a sequence of values as parameters and returns a sequence of values as results. Functions can call each other, including recursively, resulting in an implicit call stack that cannot be accessed directly. Functions may also declare mutable local variables that are usable as virtual registers.

Tables A table is an array of opaque values of a particular element type. It allows programs to select such values indirectly through a dynamic index operand. Currently, the only available element type is an untyped function reference. Thereby, a program can call functions indirectly through a dynamic index into a table. For example, this allows emulating function pointers by way of table indices.

Linear Memory A linear memory is a contiguous, mutable array of raw bytes. Such a memory is created with an initial size but can be grown dynamically. A program can load and store values from/to a linear memory at any byte address (including unaligned). Integer loads and stores can specify a storage size which is smaller than the size of the respective value type. A trap occurs if an access is not within the bounds of the current memory size.

Modules A WebAssembly binary takes the form of a module that contains definitions for functions, tables, and linear memories, as well as mutable or immutable global variables. Definitions can also be imported, specifying a module/name pair and a suitable type. Each definition can optionally be exported under one or more names. In addition to definitions, modules can define initialization data for their memories or tables that takes the form of segments copied to given offsets. They can also define a start function that is automatically executed.

Embedder A WebAssembly implementation will typically be embedded into a host environment. This environment defines how loading of modules is initiated, how imports are provided (including host-side definitions), and how exports can be accessed. However, the details of any particular embedding are beyond the scope of this specification, and will instead be provided by complementary, environment-specific API definitions.

1.2.2 Semantic Phases

Conceptually, the semantics of WebAssembly is divided into three phases. For each part of the language, the specification specifies each of them.

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6 http://ieeexplore.ieee.org/document/4610935/
7 In practice, implementations need not maintain an actual operand stack. Instead, the stack can be viewed as a set of anonymous registers that are implicitly referenced by instructions. The type system ensures that the stack height, and thus any referenced register, is always known statically.
8 In the current version of WebAssembly, there may be at most one result value.
**Decoding**  WebAssembly modules are distributed in a *binary format*. Decoding processes that format and converts it into an internal representation of a module. In this specification, this representation is modelled by *abstract syntax*, but a real implementation could compile directly to machine code instead.

**Validation**  A decoded module has to be *valid*. Validation checks a number of well-formedness conditions to guarantee that the module is meaningful and safe. In particular, it performs *type checking* of functions and the instruction sequences in their bodies, ensuring for example that the operand stack is used consistently.

**Execution**  Finally, a valid module can be *executed*. Execution can be further divided into two phases:

- **Instantiation.** A module *instance* is the dynamic representation of a module, complete with its own state and execution stack. Instantiation executes the module body itself, given definitions for all its imports. It initializes globals, memories and tables and invokes the module’s start function if defined. It returns the instances of the module’s exports.

- **Invocation.** Once instantiated, further WebAssembly computations can be initiated by *invoking* an exported function on a module instance. Given the required arguments, that executes the respective function and returns its results.

Instantiation and invocation are operations within the embedding environment.
2.1 Conventions

WebAssembly is a programming language that has multiple concrete representations (its binary format and the text format). Both map to a common structure. For conciseness, this structure is described in the form of an abstract syntax. All parts of this specification are defined in terms of this abstract syntax.

2.1.1 Grammar Notation

The following conventions are adopted in defining grammar rules for abstract syntax.

- Terminal symbols (atoms) are written in sans-serif font: \texttt{i32}, \texttt{end}.
- Nonterminal symbols are written in italic font: \texttt{valtype}, \texttt{instr}.
- $A^n$ is a sequence of $n \geq 0$ iterations of $A$.
- $A^*$ is a possibly empty sequence of iterations of $A$. (This is a shorthand for $A^n$ used where $n$ is not relevant.)
- $A^+$ is a non-empty sequence of iterations of $A$. (This is a shorthand for $A^n$ where $n \geq 1$.)
- $A^?$ is an optional occurrence of $A$. (This is a shorthand for $A^n$ where $n \leq 1$.)
- Productions are written $sym ::= A_1 | \ldots | A_n$.
- Large productions may be split into multiple definitions, indicated by ending the first one with explicit ellipses, $sym ::= A_1 | \ldots$, and starting continuations with ellipses, $sym ::= \ldots | A_2$.
- Some productions are augmented with side conditions in parentheses, “(if \textit{condition} \textit{)}”, that provide a shorthand for a combinatorial expansion of the production into many separate cases.

2.1.2 Auxiliary Notation

When dealing with syntactic constructs the following notation is also used:

- $\epsilon$ denotes the empty sequence.
- $|s|$ denotes the length of a sequence $s$.
- $s[i]$ denotes the $i$-th element of a sequence $s$, starting from 0.
• $s[i : n]$ denotes the sub-sequence $s[i] \ldots s[i + n - 1]$ of a sequence $s$.
• $s$ with $[i] = A$ denotes the same sequence as $s$, except that the $i$-th element is replaced with $A$.
• $s$ with $[i : n] = A^n$ denotes the same sequence as $s$, except that the sub-sequence $s[i : n]$ is replaced with $A^n$.
• $\text{concat}(s^*)$ denotes the flat sequence formed by concatenating all sequences $s_i$ in $s^*$.

Moreover, the following conventions are employed:

• The notation $x^n$, where $x$ is a non-terminal symbol, is treated as a meta variable ranging over respective sequences of $x$ (similarly for $x^*, x^+, x?$).
• When given a sequence $x^n$, then the occurrences of $x$ in a sequence written $(A_1 x A_2) ^n$ are assumed to be in point-wise correspondence with $x^n$ (similarly for $x^*, x^+, x?$). This implicitly expresses a form of mapping syntactic constructions over a sequence.

Productions of the following form are interpreted as records that map a fixed set of fields $\text{field}_i$ to “values” $A_i$, respectively:

$$ r ::= \{ \text{field}_1 A_1, \text{field}_2 A_2, \ldots \} $$

The following notation is adopted for manipulating such records:

• $r.\text{field}$ denotes the contents of the $\text{field}$ component of $r$.
• $r$ with $\text{field} = A$ denotes the same record as $r$, except that the contents of the field component is replaced with $A$.
• $r_1 \oplus r_2$ denotes the composition of two records with the same fields of sequences by appending each sequence point-wise:

$$ \{ \text{field}_1 A_1^*, \text{field}_2 A_2^*, \ldots \} \oplus \{ \text{field}_1 B_1^*, \text{field}_2 B_2^*, \ldots \} = \{ \text{field}_1 A_1^* B_1^*, \text{field}_2 A_2^* B_2^*, \ldots \} $$

• $\bigoplus r^*$ denotes the composition of a sequence of records, respectively; if the sequence is empty, then all fields of the resulting record are empty.

The update notation for sequences and records generalizes recursively to nested components accessed by “paths” $p\text{th} ::= ([\ldots] \mid .\text{field})^+$:

• $s$ with $[i] p\text{th} = A$ is short for $s$ with $[i] = (s[i]$ with $\text{p\text{th}} = A)$.
• $r$ with $\text{field} p\text{th} = A$ is short for $r$ with $\text{field} = (r.\text{field}$ with $\text{p\text{th}} = A)$.

where $r$ with $\text{.field} = A$ is shortened to $r$ with $\text{field} = A$.

### 2.1.3 Vectors

Vectors are bounded sequences of the form $A^n$ (or $A^*$), where the $A$ can either be values or complex constructions. A vector can have at most $2^{32} - 1$ elements.

$$ \text{vec}(A) ::= A^n \quad \text{(if } n < 2^{32}) $$

### 2.2 Values

WebAssembly programs operate on primitive numeric values. Moreover, in the definition of programs, immutable sequences of values occur to represent more complex data, such as text strings or other vectors.
2.2.1 Bytes

The simplest form of value are raw uninterpreted *bytes*. In the abstract syntax they are represented as hexadecimal literals.

\[
\text{byte} ::= 0x00 | \ldots | 0xFF
\]

**Conventions**

- The meta variable \( b \) ranges over bytes.
- Bytes are sometimes interpreted as natural numbers \( n < 256 \).

2.2.2 Integers

Different classes of *integers* with different value ranges are distinguished by their *bit width* \( N \) and by whether they are *unsigned* or *signed*.

\[
\begin{align*}
\text{u}N & ::= 0 | 1 | \ldots | 2^N-1 \\
\text{s}N & ::= -2^N-1 | \ldots | -1 | 0 | 1 | \ldots | 2^{N-1}-1 \\
\text{i}N & ::= \text{u}N
\end{align*}
\]

The latter class defines *uninterpreted* integers, whose signedness interpretation can vary depending on context. In the abstract syntax, they are represented as unsigned values. However, some operations *convert* them to signed based on a two’s complement interpretation.

**Note:** The main integer types occurring in this specification are \( u32, u64, s32, s64, i8, i16, i32, i64 \). However, other sizes occur as auxiliary constructions, e.g., in the definition of floating-point numbers.

**Conventions**

- The meta variables \( m, n, i \) range over integers.
- Numbers may be denoted by simple arithmetics, as in the grammar above. In order to distinguish arithmetics like \( 2^N \) from sequences like \( (1)^N \), the latter is distinguished with parentheses.

2.2.3 Floating-Point

*Floating-point* data represents 32 or 64 bit values that correspond to the respective binary formats of the IEEE 754-2008\(^9\) standard (Section 3.3).

Every value has a *sign* and a *magnitude*. Magnitudes can either be expressed as *normal* numbers of the form \( m_0.m_1m_2 \ldots m_M \cdot 2^e \), where \( e \) is the exponent and \( m \) is the *significand* whose most significant bit \( m_0 \) is 1, or as a *subnormal* number where the exponent is fixed to the smallest possible value and \( m_0 \) is 0; among the subnormals are positive and negative zero values. Since the significands are binary values, normals are represented in the form \( (1 + m_0 \cdot 2^{-M}) \cdot 2^e \), where \( M \) is the bit width of \( m \); similarly for subnormals.

Possible magnitudes also include the special values \( \infty \) (infinity) and \( \text{nan} \) (*NaN*, not a number). NaN values have a *payload* that describes the mantissa bits in the underlying binary representation. No distinction is made between signalling and quiet NaNs.

\[
\begin{align*}
\text{f}N & ::= +\text{f}N\text{mag} | -\text{f}N\text{mag} \\
\text{f}N\text{mag} & ::= (1 + uM \cdot 2^{-M}) \cdot 2^e \quad (\text{if } -2^{E-1} + 2 \leq e \leq 2^{E-1} - 1) \\
& | (0 + uM \cdot 2^{-M}) \cdot 2^e \quad (\text{if } e = -2^{E-1} + 2) \\
& | \infty \\
& | \text{nan}(n) \quad (\text{if } 1 \leq n < 2^M)
\end{align*}
\]

\(^9\) http://ieeexplore.ieee.org/document/4610935/
where $M = \text{signif}(N)$ and $E = \text{expon}(N)$ with

\[
\begin{align*}
\text{signif}(32) &= 23 & \text{expon}(32) &= 8 \\
\text{signif}(64) &= 52 & \text{expon}(64) &= 11
\end{align*}
\]

A canonical NaN is a floating-point value $\pm \text{nan}(\text{canon}_N)$ where $\text{canon}_N$ is a payload whose most significant bit is 1 while all others are 0:

\[
\text{canon}_N = 2^{\text{signif}(N)} - 1
\]

An arithmetic NaN is a floating-point value $\pm \text{nan}(n)$ with $n \geq \text{canon}_N$, such that the most significant bit is 1 while all others are arbitrary.

**Note:** In the abstract syntax, subnormals are distinguished by the leading 0 of the significand. The exponent of subnormals has the same value as the smallest possible exponent of a normal number. Only in the *binary representation* the exponent of a subnormal is encoded differently than the exponent of any normal number.

**Conventions**

- The meta variable $z$ ranges over floating-point values where clear from context.

### 2.2.4 Names

Names are sequences of scalar code points as defined by Unicode\(^{10}\) (Section 2.4).

\[
\begin{align*}
n\\text{name} &::= \text{codepoint}^* \\
\text{codepoint} &::= \text{U+00} \mid \ldots \mid \text{U+D7FF} \mid \text{U+E000} \mid \ldots \mid \text{U+10FFFF}
\end{align*}
\]

Due to the limitations of the *binary format*, the length of a name is bounded by the length of its *UTF-8* encoding.

**Convention**

- Code points are sometimes used interchangeably with natural numbers $n < 1114112$.

### 2.3 Types

Various entities in WebAssembly are classified by types. Types are checked during validation, instantiation, and possibly execution.

#### 2.3.1 Value Types

Value types classify the individual values that WebAssembly code can compute with and the values that a variable accepts.

\[
\begin{align*}
\text{valtype} &::= \text{i32} \mid \text{i64} \mid \text{f32} \mid \text{f64}
\end{align*}
\]

The types $\text{i32}$ and $\text{i64}$ classify 32 and 64 bit integers, respectively. Integers are not inherently signed or unsigned, their interpretation is determined by individual operations.

The types $\text{f32}$ and $\text{f64}$ classify 32 and 64 bit floating-point data, respectively. They correspond to the respective binary floating-point representations, also known as *single* and *double* precision, as defined by the IEEE 754-2008\(^{11}\) standard (Section 3.3).

\(^{10}\) http://www.unicode.org/versions/latest/

\(^{11}\) http://ieeexplore.ieee.org/document/4610935/
Conventions

- The meta variable \( t \) ranges over value types where clear from context.
- The notation \(| t |\) denotes the bit width of a value type. That is, \(|\text{i32}| = |\text{f32}| = 32\) and \(|\text{i64}| = |\text{f64}| = 64\).

2.3.2 Result Types

Result types classify the result of executing instructions or blocks, which is a sequence of values written with brackets.

\[
\text{resulttype ::=} [\text{valtype}] 
\]

**Note:** In the current version of WebAssembly, at most one value is allowed as a result. However, this may be generalized to sequences of values in future versions.

2.3.3 Function Types

Function types classify the signature of functions, mapping a vector of parameters to a vector of results, written as follows.

\[
\text{functype ::=} [\text{vec(valtype)}] \rightarrow [\text{vec(valtype)}] 
\]

**Note:** In the current version of WebAssembly, the length of the result type vector of a valid function type may be at most 1. This restriction may be removed in future versions.

2.3.4 Limits

Limits classify the size range of resizeable storage associated with memory types and table types.

\[
\text{limits ::=} \{\text{min u32}, \text{max u32}\} 
\]

If no maximum is given, the respective storage can grow to any size.

2.3.5 Memory Types

Memory types classify linear memories and their size range.

\[
\text{memtype ::=} \text{limits} 
\]

The limits constrain the minimum and optionally the maximum size of a memory. The limits are given in units of page size.

2.3.6 Table Types

Table types classify tables over elements of element types within a size range.

\[
\text{tabletype ::=} \text{limits elemtype} \\
\text{elemtype ::=} \text{anyfunc} 
\]
Like memories, tables are constrained by limits for their minimum and optionally maximum size. The limits are given in numbers of entries.

The element type `anyfunc` is the infinite union of all `function types`. A table of that type thus contains references to functions of heterogeneous type.

**Note:** In future versions of WebAssembly, additional element types may be introduced.

### 2.3.7 Global Types

*Global types* classify *global* variables, which hold a value and can either be mutable or immutable.


globaltype ::= mut valtype

mut ::= const | var

### 2.3.8 External Types

*External types* classify *imports* and *external values* with their respective types.


type ::= func functype | table tabletype | mem memtype | global globaltype

**Conventions**

The following auxiliary notation is defined for sequences of external types. It filters out entries of a specific kind in an order-preserving fashion:

- \( \text{funcs}(\text{externtype}^*) = \{ \text{functype} | (\text{functype} \in \text{externtype}^*) \} \)
- \( \text{tables}(\text{externtype}^*) = \{ \text{tabletype} | (\text{tabletype} \in \text{externtype}^*) \} \)
- \( \text{mems}(\text{externtype}^*) = \{ \text{memtype} | (\text{memtype} \in \text{externtype}^*) \} \)
- \( \text{globals}(\text{externtype}^*) = \{ \text{globaltype} | (\text{globalglobaltype} \in \text{externtype}^*) \} \)

### 2.4 Instructions

WebAssembly code consists of sequences of *instructions*. Its computational model is based on a *stack machine* in that instructions manipulate values on an implicit *operand stack*, consuming (popping) argument values and producing or returning (pushing) result values.

**Note:** In the current version of WebAssembly, at most one result value can be pushed by a single instruction. This restriction may be lifted in future versions.

In addition to dynamic operands from the stack, some instructions also have static *immediate* arguments, typically *indices* or type annotations, which are part of the instruction itself.

Some instructions are *structured* in that they bracket nested sequences of instructions.

The following sections group instructions into a number of different categories.
2.4.1 Numeric Instructions

Numeric instructions provide basic operations over numeric values of specific type. These operations closely match respective operations available in hardware.

\[
\begin{align*}
nn, nm & ::= \ 32 \ | \ 64 \\
x & ::= u \ | \ s \\
instr & ::= inn.const \ inn \ | \ fnn.const \ fnn \\
& \quad \mid \ inn.unop \ | \ fnn.funop \\
& \quad \mid \ inn.ibinop \ | \ fnn.fbinop \\
& \quad \mid \ inn.itestop \\
& \quad \mid \ inn.itestop \\
i32.wrap/i64 \mid i64.extend_sx/i32 \mid inn.trunc_sx/fnn \\
f32.demote/f64 \mid f64.promote/f32 \mid fnn.convert_sx/inn \\
& \quad \mid inn.reinterpret/fnn \ | \ fnn.reinterpret/inn \\
iunop & ::= clz \ | \ ctz \ | \ popcnt \\
ibinop & ::= add \ | \ sub \ | \ mul \ | \ div_sx \ | \ rem_sx \\
& \quad \mid \ and \ | \ or \ | \ xor \ | \ shl \ | \ shr_sx \ | \ rotl \ | \ rotr \\
funop & ::= abs \ | \ neg \ | \ sqrt \ | \ ceil \ | \ floor \ | \ trunc \ | \ nearest \\
fbinop & ::= add \ | \ sub \ | \ mul \ | \ div \ | \ min \ | \ max \ | \ copysign \\
itestop & ::= eqz \\
irelop & ::= eq \ | \ ne \ | \ lt_sx \ | \ gt_sx \ | \ le_sx \ | \ ge_sx \\
frelop & ::= eq \ | \ ne \ | \ lt \ | \ gt \ | \ le \ | \ ge
\end{align*}
\]

Numeric instructions are divided by value type. For each type, several subcategories can be distinguished:

- **Constants**: return a static constant.
- **Unary Operators**: consume one operand and produce one result of the respective type.
- **Binary Operators**: consume two operands and produce one result of the respective type.
- **Tests**: consume one operand of the respective type and produce a Boolean integer result.
- **Comparisons**: consume two operands of the respective type and produce a Boolean integer result.
- **Conversions**: consume a value of one type and produce a result of another (the source type of the conversion is the one after the “/”).

Some integer instructions come in two flavors, where a signedness annotation sx distinguishes whether the operands are to be interpreted as unsigned or signed integers. For the other integer instructions, the use of two’s complement for the signed interpretation means that they behave the same regardless of signedness.

Conventions

Occasionally, it is convenient to group operators together according to the following grammar shorthands:

\[
\begin{align*}
unop & ::= iunop \ | \ funop \\
binop & ::= ibinop \ | \ fbinop \\
testop & ::= itestop \\
relop & ::= irelop \ | \ frelop \\
cvtop & ::= wrap \ | \ extend_sx \ | \ trunc_sx \ | \ convert_sx \ | \ demote \ | \ promote \ | \ reinterpret
\end{align*}
\]

2.4.2 Parametric Instructions

Instructions in this group can operate on operands of any value type.

\[
\begin{align*}
instr & ::= \ldots \\
& \quad \mid \ drop \\
& \quad \mid \ select
\end{align*}
\]
The `drop` operator simply throws away a single operand. The `select` operator selects one of its first two operands based on whether its third operand is zero or not.

### 2.4.3 Variable Instructions

Variable instructions are concerned with access to `local` or `global` variables.

```
instr ::= ... |
  get_local localidx |
  set_local localidx |
  tee_local localidx |
  get_global globalidx |
  set_global globalidx
```

These instructions get or set the values of variables, respectively. The `tee_local` instruction is like `set_local` but also returns its argument.

### 2.4.4 Memory Instructions

Instructions in this group are concerned with linear `memory`.

```
memory ::= \{ offset u32, align u32 \}
instr ::= ... |
  inn.load memory | fnn.load memory |
  inn.store memory | fnn.store memory |
  inn.load8_sx memory | inn.load16_sx memory | i64.load32_sx memory |
  inn.store8 memory | inn.store16 memory | i64.store32 memory |
  memory.size |
  memory.grow
```

Memory is accessed with `load` and `store` instructions for the different `value types`. They all take a `memory immediate memory` that contains an address `offset` and an `alignment` hint (in base 2 logarithmic representation). Integer loads and stores can optionally specify a `storage size` that is smaller than the `bit width` of the respective value type. In the case of loads, a sign extension mode `sx` is then required to select appropriate behavior.

The static address offset is added to the dynamic address operand, yielding a 33 bit `effective address` that is the zero-based index at which the memory is accessed. All values are read and written in little endian\(^{12}\) byte order. A `trap` results if any of the accessed memory bytes lies outside the address range implied by the memory’s current size.

**Note:** Future version of WebAssembly might provide memory instructions with 64 bit address ranges.

The `memory.size` instruction returns the current size of a memory. The `memory.grow` instruction grows memory by a given delta and returns the previous size, or \(-1\) if enough memory cannot be allocated. Both instructions operate in units of `page size`.

**Note:** In the current version of WebAssembly, all memory instructions implicitly operate on `memory index 0`. This restriction may be lifted in future versions.

2.4.5 Control Instructions

Instructions in this group affect the flow of control.

\[
\text{instr} ::= \ldots
| \text{nop}
| \text{unreachable}
| \text{block resulttype instr}* \text{end}
| \text{loop resulttype instr}* \text{end}
| \text{if resulttype instr}* \text{else instr}* \text{end}
| \text{br labelidx}
| \text{br if labelidx}
| \text{br_table vec(labelidx) labelidx}
| \text{return}
| \text{call funcidx}
| \text{call indirect typeidx}
\]

The \textit{nop} instruction does nothing.

The \textit{unreachable} instruction causes an unconditional \textit{trap}.

The \textit{block}, \textit{loop} and \textit{if} instructions are \textit{structured} instructions. They bracket nested sequences of instructions, called \textit{blocks}, terminated with, or separated by, \textit{end} or \textit{else} pseudo-instructions. As the grammar prescribes, they must be well-nested. A structured instruction can produce a value as described by the annotated \textit{result type}.

Each structured control instruction introduces an implicit \textit{label}. Labels are targets for branch instructions that reference them with \textit{label indices}. Unlike with other \textit{index spaces}, indexing of labels is relative by nesting depth, that is, label 0 refers to the innermost structured control instruction enclosing the referring branch instruction, while increasing indices refer to those farther out. Consequently, labels can only be referenced from \textit{within} the associated structured control instruction. This also implies that branches can only be directed outwards, “breaking” from the block of the control construct they target. The exact effect depends on that control construct. In case of \textit{block} or \textit{if} it is a \textit{forward jump}, resuming execution after the matching \textit{end}. In case of \textit{loop} it is a \textit{backward jump} to the beginning of the loop.

\textbf{Note: } This enforces \textit{structured control flow}. Intuitively, a branch targeting a \textit{block} or \textit{if} behaves like a \textit{break} statement, while a branch targeting a \textit{loop} behaves like a \textit{continue} statement.

Branch instructions come in several flavors: \textit{br} performs an unconditional branch, \textit{br if} performs a conditional branch, and \textit{br_table} performs an indirect branch through an operand indexing into the label vector that is an immediate to the instruction, or to a default target if the operand is out of bounds. The \textit{return} instruction is a shortcut for an unconditional branch to the outermost block, which implicitly is the body of the current function. Taking a branch \textit{unwinds} the operand stack up to the height where the targeted structured control instruction was entered. However, forward branches that target a control instruction with a non-empty result type consume matching operands first and push them back on the operand stack after unwinding, as a result for the terminated structured instruction.

The \textit{call} instruction invokes another \textit{function}, consuming the necessary arguments from the stack and returning the result values of the call. The \textit{call indirect} instruction calls a function indirectly through an operand indexing into a \textit{table}. Since tables may contain function elements of heterogeneous type \textit{anyfunc}, the callee is dynamically checked against the \textit{function type} indexed by the instruction’s immediate, and the call aborted with a \textit{trap} if it does not match.

\textbf{Note: } In the current version of WebAssembly, \textit{call indirect} implicitly operates on \textit{table index} 0. This restriction may be lifted in future versions.

2.4.6 Expressions

\textit{Function} bodies, initialization values for \textit{globals}, and offsets of \textit{element} or \textit{data} segments are given as expressions,
which are sequences of instructions terminated by an end marker.

\[
expr ::= \text{instr}^* \text{end}
\]

In some places, validation restricts expressions to be constant, which limits the set of allowable instructions.

## 2.5 Modules

WebAssembly programs are organized into modules, which are the unit of deployment, loading, and compilation. A module collects definitions for types, functions, tables, memories, and globals. In addition, it can declare imports and exports and provide initialization logic in the form of data and element segments or a start function.

\[
\text{module} ::= \{ \text{types vec}(\text{functype}), \\
\quad \text{funcs vec}(\text{func}), \\
\quad \text{tables vec}(\text{table}), \\
\quad \text{mems vec}(\text{mem}), \\
\quad \text{globals vec}(\text{global}), \\
\quad \text{elem vec}(\text{elem}), \\
\quad \text{data vec}(\text{data}), \\
\quad \text{start start'}, \\
\quad \text{imports vec}(\text{import}), \\
\quad \text{exports vec}(\text{export}) \} 
\]

Each of the vectors – and thus the entire module – may be empty.

### 2.5.1 Indices

Definitions are referenced with zero-based indices. Each class of definition has its own index space, as distinguished by the following classes.

\[
\begin{align*}
\text{typeidx} & ::= \text{u32} \\
\text{funcidx} & ::= \text{u32} \\
\text{tableidx} & ::= \text{u32} \\
\text{memidx} & ::= \text{u32} \\
\text{globalidx} & ::= \text{u32} \\
\text{localidx} & ::= \text{u32} \\
\text{labelidx} & ::= \text{u32}
\end{align*}
\]

The index space for functions, tables, memories and globals includes respective imports declared in the same module. The indices of these imports precede the indices of other definitions in the same index space.

The index space for locals is only accessible inside a function and includes the parameters of that function, which precede the local variables.

Label indices reference structured control instructions inside an instruction sequence.

### Conventions

- The meta variable \( l \) ranges over label indices.
- The meta variables \( x, y \) range over indices in any of the other index spaces.

### 2.5.2 Types

The types component of a module defines a vector of function types.

All function types used in a module must be defined in this component. They are referenced by type indices.
Note: Future versions of WebAssembly may add additional forms of type definitions.

2.5.3 Functions

The `funcs` component of a module defines a vector of functions with the following structure:

\[
\text{func} ::= \{\text{type typeidx}, \text{locals vec(valtype)}, \text{body expr}\}
\]

The `type` of a function declares its signature by reference to a `type` defined in the module. The parameters of the function are referenced through 0-based `local indices` in the function’s body; they are mutable.

The `locals` declare a vector of mutable local variables and their types. These variables are referenced through `local indices` in the function’s body. The index of the first local is the smallest index not referencing a parameter.

The `body` is an `instruction` sequence that upon termination must produce a stack matching the function type’s `result type`.

Functions are referenced through `function indices`, starting with the smallest index not referencing a function `import`.

2.5.4 Tables

The `tables` component of a module defines a vector of tables described by their `table type`:

\[
\text{table} ::= \{\text{type tabletype}\}
\]

A table is a vector of opaque values of a particular table `element type`. The `min` size in the `limits` of the table type specifies the initial size of that table, while its `max`, if present, restricts the size to which it can grow later.

Tables can be initialized through `element segments`.

Tables are referenced through `table indices`, starting with the smallest index not referencing a table `import`. Most constructs implicitly reference table index 0.

Note: In the current version of WebAssembly, at most one table may be defined or imported in a single module, and all constructs implicitly reference this table 0. This restriction may be lifted in future versions.

2.5.5 Memories

The `mems` component of a module defines a vector of linear memories (or memories for short) as described by their `memory type`:

\[
\text{mem} ::= \{\text{type memtype}\}
\]

A memory is a vector of raw uninterpreted bytes. The `min` size in the `limits` of the memory type specifies the initial size of that memory, while its `max`, if present, restricts the size to which it can grow later. Both are in units of `page size`.

Memories can be initialized through `data segments`.

Memories are referenced through `memory indices`, starting with the smallest index not referencing a memory `import`. Most constructs implicitly reference memory index 0.

Note: In the current version of WebAssembly, at most one memory may be defined or imported in a single module, and all constructs implicitly reference this memory 0. This restriction may be lifted in future versions.
2.5.6 Globals

The `globals` component of a module defines a vector of `global variables` (or `globals` for short):

\[
global ::= \{ \text{type globaltype, init expr} \}
\]

Each global stores a single value of the given `global type`. Its `type` also specifies whether a global is immutable or mutable. Moreover, each global is initialized with an `init` value given by a `constant` initializer `expression`.

Globals are referenced through `global indices`, starting with the smallest index not referencing a global `import`.

2.5.7 Element Segments

The initial contents of a table is uninitialized. The `elem` component of a module defines a vector of `element segments` that initialize a subrange of a table, at a given offset, from a static `vector` of elements.

\[
elem ::= \{ \text{table tableidx, offset expr, init vec(funcidx)} \}
\]

The `offset` is given by a `constant expression`.

**Note:** In the current version of WebAssembly, at most one table is allowed in a module. Consequently, the only valid `tableidx` is 0.

2.5.8 Data Segments

The initial contents of a `memory` are zero-valued bytes. The `data` component of a module defines a vector of `data segments` that initialize a range of memory, at a given offset, with a static `vector` of `bytes`.

\[
data ::= \{ \text{data memidx, offset expr, init vec(byte)} \}
\]

The `offset` is given by a `constant expression`.

**Note:** In the current version of WebAssembly, at most one memory is allowed in a module. Consequently, the only valid `memidx` is 0.

2.5.9 Start Function

The `start` component of a module declares the `function index` of a `start function` that is automatically invoked when the module is `instantiated`, after `tables` and `memories` have been initialized.

\[
start ::= \{ \text{func funcidx} \}
\]

2.5.10 Exports

The `exports` component of a module defines a set of `exports` that become accessible to the host environment once the module has been `instantiated`.

\[
extport ::= \{ \text{name name, desc exportdesc} \}
\]

Each export is labeled by a unique `name`. Exportable definitions are `functions`, `tables`, `memories`, and `globals`, which are referenced through a respective descriptor.
Conventions

The following auxiliary notation is defined for sequences of exports, filtering out indices of a specific kind in an order-preserving fashion:

- **funcs(export*)** = \[funcidx | func funcidx ∈ (export.desc)*\]
- **tables(export*)** = \[tableidx | table tableidx ∈ (export.desc)*\]
- **mems(export*)** = \[memidx | mem memidx ∈ (export.desc)*\]
- **globals(export*)** = \[globalidx | global globalidx ∈ (export.desc)*\]

2.5.11 Imports

The imports component of a module defines a set of imports that are required for instantiation.

```
import ::={ module name, name name, desc importdesc }
importdesc ::= func typeidx
| table tabletype
| mem memtype
| global globaltype
```

Each import is labeled by a two-level name space, consisting of a module name and a name for an entity within that module. Importable definitions are functions, tables, memories, and globals. Each import is specified by a descriptor with a respective type that a definition provided during instantiation is required to match.

Every import defines an index in the respective index space. In each index space, the indices of imports go before the first index of any definition contained in the module itself.

**Note:** Unlike export names, import names are not necessarily unique. It is possible to import the same module/name pair multiple times; such imports may even have different type descriptions, including different kinds of entities. A module with such imports can still be instantiated depending on the specifics of how an embedder allows resolving and supplying imports. However, embedders are not required to support such overloading, and a WebAssembly module itself cannot implement an overloaded name.
CHAPTER 3

Validation

3.1 Conventions

Validation checks that a WebAssembly module is well-formed. Only valid modules can be instantiated.

Validity is defined by a type system over the abstract syntax of a module and its contents. For each piece of abstract syntax, there is a typing rule that specifies the constraints that apply to it. All rules are given in two equivalent forms:

1. In prose, describing the meaning in intuitive form.
2. In formal notation, describing the rule in mathematical form.\(^\text{13}\)

Note: The prose and formal rules are equivalent, so that understanding of the formal notation is not required to read this specification. The formalism offers a more concise description in notation that is used widely in programming languages semantics and is readily amenable to mathematical proof.

In both cases, the rules are formulated in a declarative manner. That is, they only formulate the constraints, they do not define an algorithm. The skeleton of a sound and complete algorithm for type-checking instruction sequences according to this specification is provided in the appendix.

3.1.1 Contexts

Validity of an individual definition is specified relative to a context, which collects relevant information about the surrounding module and the definitions in scope:

- **Types**: the list of types defined in the current module.
- **Functions**: the list of functions declared in the current module, represented by their function type.
- **Tables**: the list of tables declared in the current module, represented by their table type.
- **Memories**: the list of memories declared in the current module, represented by their memory type.
- **Globals**: the list of globals declared in the current module, represented by their global type.

• **Locals**: the list of locals declared in the current function (including parameters), represented by their value type.

• **Labels**: the stack of labels accessible from the current position, represented by their result type.

• **Return**: the return type of the current function, represented as an optional result type that is absent when no return is allowed, as in free-standing expressions.

In other words, a context contains a sequence of suitable types for each index space, describing each defined entry in that space. Locals, labels and return type are only used for validating instructions in function bodies, and are left empty elsewhere. The label stack is the only part of the context that changes as validation of an instruction sequence proceeds.

More concretely, contexts are defined as records $C$ with abstract syntax:

$$
C ::= \begin{cases}
\text{types} & \text{functype}^*, \\
\text{funcs} & \text{functype}^*, \\
\text{tables} & \text{tabletype}^*, \\
\text{mems} & \text{metype}^*, \\
\text{globals} & \text{globaltype}^*, \\
\text{locals} & \text{valtype}^*, \\
\text{labels} & \text{resulttype}^*, \\
\text{return} & \text{resulttype} ? \\
\end{cases}
$$

In addition to field access written $C.\text{field}$ the following notation is adopted for manipulating contexts:

- When spelling out a context, empty fields are omitted.

- $C, \text{field} A^*$ denotes the same context as $C$ but with the elements $A^*$ prepended to its field component sequence.

**Note:** We use indexing notation like $C.\text{labels}[i]$ to look up indices in their respective index space in the context. Context extension notation $C, \text{field} A$ is primarily used to locally extend relative index spaces, such as label indices. Accordingly, the notation is defined to append at the front of the respective sequence, introducing a new relative index 0 and shifting the existing ones.

### 3.1.2 Prose Notation

Validation is specified by stylised rules for each relevant part of the abstract syntax. The rules not only state constraints defining when a phrase is valid, they also classify it with a type. The following conventions are adopted in stating these rules.

- A phrase $A$ is said to be “valid with type $T$” if and only if all constraints expressed by the respective rules are met. The form of $T$ depends on what $A$ is.

  **Note:** For example, if $A$ is a function, then $T$ is a function type; for an $A$ that is a global, $T$ is a global type; and so on.

- The rules implicitly assume a given context $C$.

- In some places, this context is locally extended to a context $C'$ with additional entries. The formulation “Under context $C'$, . . . statement . . .” is adopted to express that the following statement must apply under the assumptions embodied in the extended context.

### 3.1.3 Formal Notation
The proposition that a phrase $A$ has a respective type $T$ is written $A : T$. In general, however, typing is dependent on a context $C$. To express this explicitly, the complete form is a judgement $C \vdash A : T$, which says that $A : T$ holds under the assumptions encoded in $C$.

The formal typing rules use a standard approach for specifying type systems, rendering them into deduction rules. Every rule has the following general form:

\[
\frac{\text{premise}_1 \quad \text{premise}_2 \quad \ldots \quad \text{premise}_n}{\text{conclusion}}
\]

Such a rule is read as a big implication: if all premises hold, then the conclusion holds. Some rules have no premises; they are axioms whose conclusion holds unconditionally. The conclusion always is a judgment $C \vdash A : T$, and there is one respective rule for each relevant construct $A$ of the abstract syntax.

Note: For example, the typing rule for the \texttt{i32.add} instruction can be given as an axiom:

\[
C \vdash \texttt{i32.add} : \texttt{[i32 i32] \rightarrow [i32]}
\]

The instruction is always valid with type $\texttt{[i32 i32] \rightarrow [i32]}$ (saying that it consumes two \texttt{i32} values and produces one), independent of any side conditions.

An instruction like \texttt{get\_local} can be typed as follows:

\[
\frac{C.\texttt{locals}[x] = t}{C \vdash \texttt{get\_local x} : [] \rightarrow [t]}
\]

Here, the premise enforces that the immediate local index $x$ exists in the context. The instruction produces a value of its respective type $t$ (and does not consume any values). If $C.\texttt{locals}[x]$ does not exist then the premise does not hold, and the instruction is ill-typed.

Finally, a structured instruction requires a recursive rule, where the premise is itself a typing judgement:

\[
\frac{C.\texttt{label}[t'] \vdash \texttt{instr}^* : [] \rightarrow [t']}{C \vdash \texttt{block [t']} \texttt{instr}^* \texttt{end} : [] \rightarrow [t']}
\]

A block instruction is only valid when the instruction sequence in its body is. Moreover, the result type must match the block’s annotation $[t']$. If so, then the block instruction has the same type as the body. Inside the body an additional label of the same type is available, which is expressed by extending the context $C$ with the additional label information for the premise.

3.2 Types

Most types are universally valid. However, restrictions apply to function types as well as the limits of table types and memory types, which must be checked during validation.

3.2.1 Limits

Limits must have meaningful bounds that are within a given range.

\[\text{Note: For example: Benjamin Pierce. Types and Programming Languages. The MIT Press 2002}\]
\{\text{min } n, \text{max } m^?\}

- The value of \( n \) must not be larger than \( k \).
- If the maximum \( m^? \) is not empty, then:
  - Its value must not be larger than \( k \).
  - Its value must not be smaller than \( n \).
- Then the limit is valid within range \( k \).

\[
\frac{n \leq k \quad (m \leq k)^? \quad (n \leq m)^?}{\vdash \{\text{min } n, \text{max } m^?\} : k}
\]

### 3.2.2 Function Types

*Function types* may not specify more than one result.

\([t^1_1] \rightarrow [t^m_2]\)

- The arity \( m \) must not be larger than 1.
- Then the function type is valid.

\[\vdash [t^1_1] \rightarrow [t^m_2] \text{ ok}\]

**Note:** The restriction to at most one result may be removed in future versions of WebAssembly.

### 3.2.3 Table Types

*limits elemtype*

- The limits *limits* must be *valid* within range \(2^{32}\).
- Then the table type is valid.

\[\vdash \text{limits} : 2^{32}\]

\[\vdash \text{limits elemtype} \text{ ok}\]

### 3.2.4 Memory Types

*limits*

- The limits *limits* must be *valid* within range \(2^{16}\).
- Then the memory type is valid.

\[\vdash \text{limits} : 2^{16}\]

\[\vdash \text{limits} \text{ ok}\]
3.2.5 Global Types

**mut valtype**

- The global type is valid.

\[ \vdash \text{mut valtype} \rightarrow \text{ok} \]

3.3 Instructions

*Instructions* are classified by *function types* \([t_1^*] \rightarrow [t_2^*]\) that describe how they manipulate the *operand stack*. The types describe the required input stack with argument values of types \(t_1^*\) that an instruction pops off and the provided output stack with result values of types \(t_2^*\) that it pushes back.

**Note:** For example, the instruction `i32.add` has type \([i32 \ i32] \rightarrow [i32]\), consuming two i32 values and producing one.

Typing extends to *instruction sequences* `instr^*`. Such a sequence has a *function type* \([t_1^*] \rightarrow [t_2^*]\) if the accumulative effect of executing the instructions is consuming values of types \(t_1^*\) off the operand stack and pushing new values of types \(t_2^*\).

For some instructions, the typing rules do not fully constrain the type, and therefore allow for multiple types. Such instructions are called *polymorphic*. Two degrees of polymorphism can be distinguished:

- **value-polymorphic**: the *value type* \(t\) of one or several individual operands is unconstrained. That is the case for all *parametric instructions* like `drop` and `select`.
  - **stack-polymorphic**: the entire (or most of the) *function type* \([t_1^*] \rightarrow [t_2^*]\) of the instruction is unconstrained. That is the case for all *control instructions* that perform an *unconditional control transfer*, such as `unreachable`, `br`, `br_table`, and `return`.

In both cases, the unconstrained types or type sequences can be chosen arbitrarily, as long as they meet the constraints imposed for the surrounding parts of the program.

**Note:** For example, the `select` instruction is valid with type \([t \ t \ i32] \rightarrow [t]\), for any possible *value type* \(t\). Consequently, both instruction sequences

\[
(i32.const\ 1)\ (i32.const\ 2)\ (i32.const\ 3)\ \text{select}
\]

and

\[
(f64.const\ 1.0)\ (f64.const\ 2.0)\ (i32.const\ 3)\ \text{select}
\]

are valid, with \(t\) in the typing of `select` being instantiated to `i32` or `f64`, respectively.

The `unreachable` instruction is valid with type \([t_1^*] \rightarrow [t_2^*]\) for any possible sequences of value types \(t_1^*\) and \(t_2^*\). Consequently,

\[ \text{unreachable} \ \text{i32.add} \]

is valid by assuming type \([\ ] \rightarrow [i32 \ i32]\) for the `unreachable` instruction. In contrast,

\[ \text{unreachable} \ (i64.const\ 0)\ \text{i32.add} \]

is invalid, because there is no possible type to pick for the `unreachable` instruction that would make the sequence well-typed.
3.3.1 Numeric Instructions

\( t.\text{const} \, c \)

- The instruction is valid with type \([\text{}] \rightarrow [t].\)
  \[ C \vdash t.\text{const} : [\text{}] ightarrow [t] \]

\( t.\text{unop} \)

- The instruction is valid with type \([t] \rightarrow [t].\)
  \[ C \vdash t.\text{unop} : [t] ightarrow [t] \]

\( t.\text{binop} \)

- The instruction is valid with type \([t \, t] \rightarrow [t].\)
  \[ C \vdash t.\text{binop} : [t \, t] ightarrow [t] \]

\( t.\text{testop} \)

- The instruction is valid with type \([t] \rightarrow [\text{i32}].\)
  \[ C \vdash t.\text{testop} : [t] ightarrow [\text{i32}] \]

\( t.\text{relop} \)

- The instruction is valid with type \([t \, t] \rightarrow [\text{i32}].\)
  \[ C \vdash t.\text{relop} : [t \, t] ightarrow [\text{i32}] \]

\( t_2.\text{cetop}/t_1 \)

- The instruction is valid with type \([t_1] \rightarrow [t_2].\)
  \[ C \vdash t_2.\text{cetop}/t_1 : [t_1] ightarrow [t_2] \]

3.3.2 Parametric Instructions

\( \text{drop} \)

- The instruction is valid with type \([t] \rightarrow \text{[]}, \text{for any value type} \, t.\)
  \[ C \vdash \text{drop} : [t] ightarrow \text{[]} \]
select

• The instruction is valid with type \([t \ i32] \rightarrow [t]\), for any \textit{value type} \(t\).

\[
\begin{align*}
C \vdash \text{select} : [t \ i32] \rightarrow [t]
\end{align*}
\]

Note: Both \texttt{drop} and \texttt{select} are \textit{value-polymorphic} instructions.

### 3.3.3 Variable Instructions

\texttt{get\_local} \(x\)

• The local \(C.\text{locals}[x]\) must be defined in the context.
• Let \(t\) be the \textit{value type} \(C.\text{locals}[x]\).
• Then the instruction is valid with type \([\_] \rightarrow [t]\).

\[
\begin{align*}
C.\text{locals}[x] = t \\
C \vdash \text{get\_local} \ x : [\_] \rightarrow [t]
\end{align*}
\]

\texttt{set\_local} \(x\)

• The local \(C.\text{locals}[x]\) must be defined in the context.
• Let \(t\) be the \textit{value type} \(C.\text{locals}[x]\).
• Then the instruction is valid with type \([t] \rightarrow [\_]\).

\[
\begin{align*}
C.\text{locals}[x] = t \\
C \vdash \text{set\_local} \ x : [t] \rightarrow [\_]
\end{align*}
\]

\texttt{tee\_local} \(x\)

• The local \(C.\text{locals}[x]\) must be defined in the context.
• Let \(t\) be the \textit{value type} \(C.\text{locals}[x]\).
• Then the instruction is valid with type \([t] \rightarrow [t]\).

\[
\begin{align*}
C.\text{locals}[x] = t \\
C \vdash \text{tee\_local} \ x : [t] \rightarrow [t]
\end{align*}
\]

\texttt{get\_global} \(x\)

• The global \(C.\text{globals}[x]\) must be defined in the context.
• Let \(\texttt{mut} \ t\) be the \textit{global type} \(C.\text{globals}[x]\).
• Then the instruction is valid with type \([\_] \rightarrow [t]\).

\[
\begin{align*}
C.\text{globals}[x] = \texttt{mut} \ t \\
C \vdash \text{get\_global} \ x : [\_] \rightarrow [t]
\end{align*}
\]
set\_global \_x

- The global $C.globals[x]$ must be defined in the context.
- Let `mut` be the global type $C.globals[x]$.
- The mutability `mut` must be `var`.
- Then the instruction is valid with type $[t] \rightarrow []$.

$$\frac{C.globals[x] = \text{var } t}{C \vdash \text{set\_global } x : [t] \rightarrow []}$$

### 3.3.4 Memory Instructions

\texttt{t.load memarg}

- The memory $C.mems[0]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than the \textit{bit width} of $t$ divided by 8.
- Then the instruction is valid with type $[i32] \rightarrow [t]$.

$$\frac{C.mems[0] = \text{memtype} \quad 2^{\text{memarg.align}} \leq |t|/8}{C \vdash \text{t.load memarg} : [i32] \rightarrow [t]}$$

\texttt{t.loadN\_sx memarg}

- The memory $C.mems[0]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than $N/8$.
- Then the instruction is valid with type $[i32] \rightarrow [t]$.

$$\frac{C.mems[0] = \text{memtype} \quad 2^{\text{memarg.align}} \leq N/8}{C \vdash \text{t.loadN\_sx memarg} : [i32] \rightarrow [t]}$$

\texttt{t.store memarg}

- The memory $C.mems[0]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than the \textit{bit width} of $t$ divided by 8.
- Then the instruction is valid with type $[i32 \ t] \rightarrow []$.

$$\frac{C.mems[0] = \text{memtype} \quad 2^{\text{memarg.align}} \leq |t|/8}{C \vdash \text{t.store memarg} : [i32 \ t] \rightarrow []}$$

\texttt{t.storeN memarg}

- The memory $C.mems[0]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than $N/8$.
- Then the instruction is valid with type $[i32 \ t] \rightarrow []$.

$$\frac{C.mems[0] = \text{memtype} \quad 2^{\text{memarg.align}} \leq N/8}{C \vdash \text{t.storeN memarg} : [i32 \ t] \rightarrow []}$$
memory.size

- The memory $C.mems[0]$ must be defined in the context.
- Then the instruction is valid with type $[] \rightarrow [i32]$.

\[
C.mems[0] = \text{memtype} \\
C \vdash \text{memory.size} : [] \rightarrow [i32]
\]

memory.grow

- The memory $C.mems[0]$ must be defined in the context.
- Then the instruction is valid with type $[i32] \rightarrow [i32]$.

\[
C.mems[0] = \text{memtype} \\
C \vdash \text{memory.grow} : [i32] \rightarrow [i32]
\]

3.3.5 Control Instructions

nop

- The instruction is valid with type $[] \rightarrow []$.

\[
C \vdash \text{nop} : [] \rightarrow []
\]

unreachable

- The instruction is valid with type $[t_1^*] \rightarrow [t_2^*]$, for any sequences of value types $t_1^*$ and $t_2^*$.

\[
C \vdash \text{unreachable} : [t_1^*] \rightarrow [t_2^*]
\]

Note: The unreachable instruction is stack-polymorphic.

block $[t^?]$ instr* end

- Let $C'$ be the same context as $C$, but with the result type $[t^?]$ prepended to the labels vector.
- Under context $C'$, the instruction sequence instr* must be valid with type $[] \rightarrow [t^?]$.
- Then the compound instruction is valid with type $[] \rightarrow [t^?]$.

\[
C, \text{labels } [t^?] \vdash \text{instr*} : [] \rightarrow [t^?] \\
C \vdash \text{block } [t^?] \text{ instr* end} : [] \rightarrow [t^?]
\]

Note: The notation $C, \text{labels } [t^?]$ inserts the new label type at index 0, shifting all others.

The fact that the nested instruction sequence instr* must have type $[] \rightarrow [t^?]$ implies that it cannot access operands that have been pushed on the stack before the block was entered. This may be generalized in future versions of WebAssembly.
loop \([t^?]\) instr* end

- Let \(C'\) be the same context as \(C\), but with the empty result type \([]\) prepended to the labels vector.
- Under context \(C'\), the instruction sequence instr* must be valid with type \([] \rightarrow [t^?]\).
- Then the compound instruction is valid with type \([] \rightarrow [t^?]\).

\[
C, \text{labels} [] \vdash \text{instr}^* : [] \rightarrow [t^?]
\]

\[
C' \vdash \text{loop} [t^?] \text{instr}^* \text{end} : [] \rightarrow [t^?]
\]

**Note:** The notation \(C, \text{labels} []\) inserts the new label type at index 0, shifting all others.

The fact that the nested instruction sequence instr* must have type \([],\rightarrow [t^?]\) implies that it cannot access operands that have been pushed on the stack before the loop was entered. This may be generalized in future versions of WebAssembly.

if \([t^?]\) instr*\(_1^\) else instr*\(_2^\) end

- Let \(C'\) be the same context as \(C\), but with the result type \([t^?]\) prepended to the labels vector.
- Under context \(C'\), the instruction sequence instr*\(_1^\) must be valid with type \([] \rightarrow [t^?]\).
- Under context \(C'\), the instruction sequence instr*\(_2^\) must be valid with type \([] \rightarrow [t^?]\).
- Then the compound instruction is valid with type \([i32] \rightarrow [t^?]\).

\[
C, \text{labels} [t^?] \vdash \text{instr}^*_1 : [] \rightarrow [t^?]
\]

\[
C, \text{labels} [t^?] \vdash \text{instr}^*_2 : [] \rightarrow [t^?]
\]

\[
C \vdash \text{if} [t^?] \text{instr}^*_1 \text{else instr}^*_2 \text{end} : [i32] \rightarrow [t^?]
\]

**Note:** The notation \(C, \text{labels} [t^?]\) inserts the new label type at index 0, shifting all others.

The fact that the nested instruction sequence instr* must have type \([],\rightarrow [t^?]\) implies that it cannot access operands that have been pushed on the stack before the conditional was entered. This may be generalized in future versions of WebAssembly.

br \(l\)

- The label \(C.\text{labels}[l]\) must be defined in the context.
- Let \([t^?]\) be the result type \(C.\text{labels}[l]\).
- Then the instruction is valid with type \([t^*_1, t^*] \rightarrow [t^*_2]\), for any sequences of value types \(t^*_1\) and \(t^*_2\).

\[
C, \text{labels}[l] = [t^?]
\]

\[
C \vdash \text{br} \ l : [t^*_1, t^?] \rightarrow [t^*_2]
\]

**Note:** The label index space in the context \(C\) contains the most recent label first, so that \(C.\text{labels}[l]\) performs a relative lookup as expected.

The br instruction is stack-polymorphic.
br_if \( l \)

- The label \( C.\text{labels}[l] \) must be defined in the context.
- Let \( [t'] \) be the result type \( C.\text{labels}[l] \).
- Then the instruction is valid with type \( [t'^{\text{i32}}] \rightarrow [t'] \).

\[
C.\text{labels}[l] = [t'] \\
C \vdash \text{br_if } l : [t'^{\text{i32}}] \rightarrow [t']
\]

**Note:** The label index space in the context \( C \) contains the most recent label first, so that \( C.\text{labels}[l] \) performs a relative lookup as expected.

br_table \( l^* \ l_N \)

- The label \( C.\text{labels}[l_N] \) must be defined in the context.
- Let \( [t'] \) be the result type \( C.\text{labels}[l_N] \).
- For all \( l_i \) in \( l^* \), the label \( C.\text{labels}[l_i] \) must be defined in the context.
- For all \( l_i \) in \( l^* \), \( C.\text{labels}[l_i] \) must be \([t'] \).
- Then the instruction is valid with type \( [t_1^* \ t'^{\text{i32}}] \rightarrow [t_2^*] \), for any sequences of value types \( t_1^* \) and \( t_2^* \).

\[
(C.\text{labels}[l] = [t'])^* \quad C.\text{labels}[l_N] = [t'] \\
C \vdash \text{br_table } l^* l_N : [t_1^* t'^{\text{i32}}] \rightarrow [t_2^*]
\]

**Note:** The label index space in the context \( C \) contains the most recent label first, so that \( C.\text{labels}[l_i] \) performs a relative lookup as expected.

The \text{br_table} instruction is stack-polymorphic.

return

- The return type \( C.\text{return} \) must not be absent in the context.
- Let \( [t'] \) be the result type of \( C.\text{return} \).
- Then the instruction is valid with type \( [t_1^* \ t'] \rightarrow [t_2^*] \), for any sequences of value types \( t_1^* \) and \( t_2^* \).

\[
C.\text{return} = [t'] \\
C \vdash \text{return} : [t_1^* t'] \rightarrow [t_2^*]
\]

**Note:** The \text{return} instruction is stack-polymorphic.

\( C.\text{return} \) is absent (set to \( \epsilon \)) when validating an expression that is not a function body. This differs from it being set to the empty result type \( ([\epsilon]) \), which is the case for functions not returning anything.

call \( x \)

- The function \( C.\text{funcs}[x] \) must be defined in the context.
- Then the instruction is valid with type \( C.\text{funcs}[x] \).

\[
C.\text{funcs}[x] = [t_1^*] \rightarrow [t_2^*] \\
C \vdash \text{call } x : [t_1^*] \rightarrow [t_2^*]
\]
call间接 x

- The table $C.tables[0]$ must be defined in the context.
- Let $limits elemtype$ be the table type $C.tables[0]$.
- The $element type elemtype$ must be anyfunc.
- The type $C.types[x]$ must be defined in the context.
- Let $[t_1] \rightarrow [t_2]$ be the function type $C.types[x]$.
- Then the instruction is valid with type $[t_1 i32] \rightarrow [t_2]$.

$$
C.tables[0] = limits\ anyfunc \hspace{1cm} C.types[x] = [t_1] \rightarrow [t_2] \\
C \vdash call\ indirect\ x : [t_1 i32] \rightarrow [t_2]
$$

### 3.3.6 Instruction Sequences

Typing of instruction sequences is defined recursively.

**Empty Instruction Sequence:** $\epsilon$

- The empty instruction sequence is valid with type $[t^*] \rightarrow [t^*]$, for any sequence of value types $t^*$.

$$
C \vdash \epsilon : [t^*] \rightarrow [t^*]
$$

**Non-empty Instruction Sequence:** $instr^* instr_N$

- The instruction sequence $instr^*$ must be valid with type $[t_1^*] \rightarrow [t_2^*]$, for some sequences of value types $t_1^*$ and $t_2^*$.
- The instruction $instr_N$ must be valid with type $[t^*] \rightarrow [t_3^*]$, for some sequences of value types $t^*$ and $t_3^*$.
- There must be a sequence of value types $t_0^*$, such that $t_2^* = t_0^* t^*$.
- Then the combined instruction sequence is valid with type $[t_1^*] \rightarrow [t_0^* t_3^*]$.

$$
C \vdash instr^* : [t_1^*] \rightarrow [t_0^* t^*] \hspace{1cm} C \vdash instr_N : [t^*] \rightarrow [t_3^*] \\
C \vdash instr^* instr_N : [t_1^*] \rightarrow [t_0^* t_3^*]
$$

### 3.3.7 Expressions

Expressions $expr$ are classified by result types of the form $[t^*]$.

$instr^* end$

- The instruction sequence $instr^*$ must be valid with type $[] \rightarrow [t^*]$, for some optional value type $t^*$.
- Then the expression is valid with result type $[t^*]$.

$$
C \vdash instr^* : [] \rightarrow [t^*] \\
C \vdash instr^* end : [t^*]
$$
Constant Expressions

- In a constant expression `instr* end` all instructions in `instr*` must be constant.
- A constant instruction `instr` must be:
  - either of the form `t.const c`,
  - or of the form `get_global x`, in which case `C.globals[x]` must be a global type of the form `const t`.

\[
\frac{\begin{array}{c} C \vdash instr \text{ const} \\ C \vdash instr* \text{ end const} \end{array}}{C \vdash t.\text{const } c} \quad \frac{C \vdash \text{get}_\text{global } x \text{ const}}{C \vdash C.\text{globals}[x] = \text{const } t}
\]

**Note:** Currently, constant expressions occurring as initializers of `globals` are further constrained in that contained `get_global` instructions are only allowed to refer to imported `globals`. This is enforced in the validation rule for modules by constraining the context `C` accordingly.

The definition of constant expression may be extended in future versions of WebAssembly.

### 3.4 Modules

**Modules** are valid when all the components they contain are valid. Furthermore, most definitions are themselves classified with a suitable type.

#### 3.4.1 Functions

Functions `func` are classified by function types of the form `[t_1^*] \rightarrow [t_2^?]`.

\{type `x`, locals `t^*`, body `expr`\}

- The type `C.types[x]` must be defined in the context.
- Let `[t_1] \rightarrow [t_2^?]` be the function type `C.types[x]`.
- Let `C'` be the same context as `C`, but with:
  - `locals` set to the sequence of value types `t_1^* t^*`, concatenating parameters and locals,
  - `labels` set to the singular sequence containing only result type `[t_2^?]`.
  - `return` set to the result type `[t_2^?]`.
- Under the context `C'`, the expression `expr` must be valid with type `t_2^?`.
- Then the function definition is valid with type `[t_1] \rightarrow [t_2^?]`.

\[
C.\text{types}[x] = [t_1^*] \rightarrow [t_2^?] \quad C', \text{locals } t_1^* t^*, \text{labels } [t_2^?], \text{return } [t_2^?] \vdash expr : [t_2^?]
\]

**Note:** The restriction on the length of the result types `t_2^?` may be lifted in future versions of WebAssembly.

#### 3.4.2 Tables

Tables `table` are classified by table types.
{type tabletype}

- The table type tabletype must be valid.
- Then the table definition is valid with type tabletype.

\[ \vdash \text{tabletype ok} \]

\[ C \vdash \{\text{type tabletype}\} : \text{tabletype} \]

### 3.4.3 Memories

Memories `mem` are classified by `memory types`.

{type memtype}

- The memory type memtype must be valid.
- Then the memory definition is valid with type memtype.

\[ \vdash \text{memtype ok} \]

\[ C \vdash \{\text{type memtype}\} : \text{memtype} \]

### 3.4.4 Globals

Globals `global` are classified by `global types` of the form `mut t`.

{type mut t, init expr}

- The global type mut t must be valid.
- The expression expr must be valid with result type [t].
- The expression expr must be constant.
- Then the global definition is valid with type mut t.

\[ \vdash \text{mut t ok} \quad C \vdash \text{expr : } [t] \quad C \vdash \text{expr const} \]

\[ C \vdash \{\text{type mut t, init expr}\} : \text{mut t} \]

### 3.4.5 Element Segments

Element segments `elem` are not classified by a type.

{table x, offset expr, init y*}

- The table C.tables[x] must be defined in the context.
- Let limits elemtype be the table type C.tables[x].
- The element type elemtype must be anyfunc.
- The expression expr must be valid with result type [i32].
- The expression expr must be constant.
- For each y_i in y*, the function C.funcs[y] must be defined in the context.
• Then the element segment is valid.
\[
C.\text{tables}[x] = \text{limits anyfunc} \quad C \vdash expr : [i32] \quad C \vdash expr \text{ const} \quad (C.\text{funcs}[y] = \text{functype})^* \\
C \vdash \{\text{table } x, \text{offset } expr, \text{init } y^* \} \text{ ok}
\]

### 3.4.6 Data Segments

Data segments *data* are not classified by any type.

\[
\{\text{data } x, \text{offset } expr, \text{init } b^* \}
\]

• The memory *C.mems*[x] must be defined in the context.
• The expression *expr* must be *valid* with result type [i32].
• The expression *expr* must be *constant*.
• Then the data segment is valid.
\[
C.\text{mems}[x] = \text{limits} \quad C \vdash expr : [i32] \quad C \vdash expr \text{ const} \\
C \vdash \{\text{data } x, \text{offset } expr, \text{init } b^* \} \text{ ok}
\]

### 3.4.7 Start Function

Start function declarations *start* are not classified by any type.

\[
\{\text{func } x \}
\]

• The function *C.funcs*[x] must be defined in the context.
• The type of *C.funcs*[x] must be [] → [].
• Then the start function is valid.
\[
C.\text{funcs}[x] = \text{[]} \rightarrow \text{[]} \\
C \vdash \{\text{func } x \} \text{ ok}
\]

### 3.4.8 Exports

Exports *export* and export descriptions *exportdesc* are classified by their *external type*.

\[
\{\text{name name, desc exportdesc} \}
\]

• The export description *exportdesc* must be valid with *external type* *externctype*.
• Then the export is valid with *external type* *externctype*.
\[
C \vdash exportdesc : externctype \\
C \vdash \{\text{name name, desc exportdesc} \} : externctype
\]
func $x$

- The function $C.funcs[x]$ must be defined in the context.
- Then the export description is valid with $\text{external type } func C.funcs[x]$.

$$C.funcs[x] = \text{functype} \quad C \vdash func \ x : \text{functype}$$

table $x$

- The table $C.tables[x]$ must be defined in the context.
- Then the export description is valid with $\text{external type } table C.tables[x]$.

$$C.tables[x] = \text{tabletype} \quad C \vdash table \ x : \text{table tabletype}$$

mem $x$

- The memory $C.mems[x]$ must be defined in the context.
- Then the export description is valid with $\text{external type } mem C.mems[x]$.

$$C.mems[x] = \text{memtype} \quad C \vdash mem \ x : \text{mem memtype}$$

global $x$

- The global $C.globals[x]$ must be defined in the context.
- Then the export description is valid with $\text{external type } global C.globals[x]$.

$$C.globals[x] = \text{globaltype} \quad C \vdash global \ x : \text{global globaltype}$$

### 3.4.9 Imports

Imports $\text{import}$ and import descriptions $\text{importdesc}$ are classified by $\text{external types}$.

$$\{\text{module } name_1, name \ name_2, desc \ importdesc\}$$

- The import description $\text{importdesc}$ must be valid with type $\text{externetype}$.
- Then the import is valid with type $\text{externetype}$.

$$C \vdash \text{importdesc} : \text{externetype} \quad C \vdash \{\text{module } name_1, name \ name_2, desc \ importdesc\} : \text{externetype}$$

func $x$

- The function $C.types[x]$ must be defined in the context.
- Let $[t_1^*] \rightarrow [t_2^*]$ be the $\text{function type } C.types[x]$.
- Then the import description is valid with type $\text{func } [t_1^*] \rightarrow [t_2^*]$.

$$C.types[x] = [t_1^*] \rightarrow [t_2^*] \quad C \vdash \text{func } x : \text{func } [t_1^*] \rightarrow [t_2^*]$$
### 3.4.10 Modules

Modules are classified by their mapping from the *external types* of their *imports* to those of their *exports*.

A module is entirely *closed*, that is, its components can only refer to definitions that appear in the module itself. Consequently, no initial *context* is required. Instead, the context $C$ for validation of the module’s content is constructed from the definitions in the module.

- Let $module$ be the module to validate.
- Let $C$ be a *context* where:
  - $C.types$ is $module.types$,
  - $C.funcs$ is $funcs(it^*)$ concatenated with $ft^*$, with the import’s *external types* $it^*$ and the internal *function types* $ft^*$ as determined below,
  - $C.tables$ is $tables(it^*)$ concatenated with $tt^*$, with the import’s *external types* $it^*$ and the internal *table types* $tt^*$ as determined below,
  - $C.mems$ is $mems(it^*)$ concatenated with $mt^*$, with the import’s *external types* $it^*$ and the internal *memory types* $mt^*$ as determined below,
  - $C.globals$ is $globals(it^*)$ concatenated with $gt^*$, with the import’s *external types* $it^*$ and the internal *global types* $gt^*$ as determined below,
  - $C.locals$ is empty,
  - $C.labels$ is empty,
  - $C.return$ is empty.
- Let $C’$ be the *context* where $C’.globals$ is the sequence $globals(it^*)$ and all other fields are empty.
- Under the context $C$:
  - For each function $func_t$, in $module.types$, the function type $func_t$ must be *valid*.
For each \( \text{func}_i \) in \( \text{module.funcs} \), the definition \( \text{func}_i \) must be \textit{valid} with a \textit{function type} \( \text{ft}_i \).

For each \( \text{table}_i \) in \( \text{module.tables} \), the definition \( \text{table}_i \) must be \textit{valid} with a \textit{table type} \( \text{tt}_i \).

For each \( \text{mem}_i \) in \( \text{module.mems} \), the definition \( \text{mem}_i \) must be \textit{valid} with a \textit{memory type} \( \text{mt}_i \).

For each \( \text{global}_i \) in \( \text{module.globals} \):

* Under the context \( C' \), the definition \( \text{global}_i \) must be \textit{valid} with a \textit{global type} \( \text{gt}_i \).

For each \( \text{elem}_i \) in \( \text{module.elem} \), the segment \( \text{elem}_i \) must be \textit{valid}.

For each \( \text{data}_i \) in \( \text{module.data} \), the segment \( \text{data}_i \) must be \textit{valid}.

If \( \text{module.start} \) is non-empty, then \( \text{module.start} \) must be \textit{valid}.

For each \( \text{import}_i \) in \( \text{module.imports} \), the segment \( \text{import}_i \) must be \textit{valid} with an \textit{external type} \( \text{it}_i \).

For each \( \text{export}_i \) in \( \text{module.exports} \), the segment \( \text{export}_i \) must be \textit{valid} with \textit{external type} \( \text{et}_i \).

The length of \( C . \text{tables} \) must not be larger than 1.

The length of \( C . \text{mems} \) must not be larger than 1.

All export names \( \text{export}_i . \text{name} \) must be different.

Let \( \text{ft}' \) be the concatenation of the internal \textit{function types} \( \text{ft}_i \), in index order.

Let \( \text{tt}' \) be the concatenation of the internal \textit{table types} \( \text{tt}_i \), in index order.

Let \( \text{mt}' \) be the concatenation of the internal \textit{memory types} \( \text{mt}_i \), in index order.

Let \( \text{gt}' \) be the concatenation of the internal \textit{global types} \( \text{gt}_i \), in index order.

Let \( \text{it}' \) be the concatenation of \textit{external types} \( \text{it}_i \) of the imports, in index order.

Let \( \text{et}' \) be the concatenation of \textit{external types} \( \text{et}_i \) of the exports, in index order.

Then the module is \textit{valid} with \textit{external types} \( \text{it}' \rightarrow \text{et}' \).

\[
(\vdash \text{functype}\ \text{ok})^* \quad (C \vdash \text{func} : \text{ft})^* \quad (C \vdash \text{table} : \text{tt})^* \quad (C \vdash \text{mem} : \text{mt})^* \quad (C' \vdash \text{global} : \text{gt})^* \\
(C \vdash \text{elem} \ \text{ok})^* \quad (C \vdash \text{data} \ \text{ok})^* \quad (C \vdash \text{start} \ \text{ok})^* \quad (C \vdash \text{import} : \text{it})^* \quad (C \vdash \text{export} : \text{et})^* \\
\text{ift}' = \text{functs(it')}, \text{itt}' = \text{tables(it')}, \text{imit}' = \text{mems(it')}, \text{igt}' = \text{globals(it')}, \\
C' = \{\text{types functype}', \text{functs igt}', \text{tables itt}', \text{mems itt}', \text{mems} \ \text{mt}' \}, \text{globals} \ \text{igt'} \ \text{gt}' \} \\
|C . \text{tables}| \leq 1 \quad |C . \text{mems}| \leq 1 \quad (\text{export} . \text{name})^* \text{ disjoint}^* \\
\vdash \{\text{types functype}', \text{functs func'}, \text{tables table'}, \text{mems mem'}, \text{globals igt'}, \text{globals global'}; \\
\quad \text{elem elem'}, \text{data data'}, \text{start start'}, \text{imports import'}, \text{exports export'} \} : \text{it}' \rightarrow \text{et}'
\]

\textbf{Note:} Most definitions in a module – particularly functions – are mutually recursive. Consequently, the definition of the context \( C \) in this rule is recursive: it depends on the outcome of validation of the function, table, memory, and global definitions contained in the module, which itself depends on \( C \). However, this recursion is just a specification device. All types needed to construct \( C \) can easily be determined from a simple pre-pass over the module that does not perform any actual validation.

Globals, however, are not recursive. The effect of defining the limited context \( C' \) for validating the module’s globals is that their initialization expressions can only access imported globals and nothing else.

\textbf{Note:} The restriction on the number of tables and memories may be lifted in future versions of WebAssembly.
4.1 Conventions

WebAssembly code is executed when instantiating a module or invoking an exported function on the resulting module instance.

Execution behavior is defined in terms of an abstract machine that models the program state. It includes a stack, which records operand values and control constructs, and an abstract store containing global state.

For each instruction, there is a rule that specifies the effect of its execution on the program state. Furthermore, there are rules describing the instantiation of a module. As with validation, all rules are given in two equivalent forms:

1. In prose, describing the execution in intuitive form.
2. In formal notation, describing the rule in mathematical form.\(^{17}\)

Note: As with validation, the prose and formal rules are equivalent, so that understanding of the formal notation is not required to read this specification. The formalism offers a more concise description in notation that is used widely in programming languages semantics and is readily amenable to mathematical proof.

4.1.1 Prose Notation

Execution is specified by stylised, step-wise rules for each instruction of the abstract syntax. The following conventions are adopted in stating these rules.

- The execution rules implicitly assume a given store \(S\).
- The execution rules also assume the presence of an implicit stack that is modified by pushing or popping values, labels, and frames.
- Certain rules require the stack to contain at least one frame. The most recent frame is referred to as the current frame.

• Both the store and the current frame are mutated by replacing some of their components. Such replacement is assumed to apply globally.

• The execution of an instruction may trap, in which case the entire computation is aborted and no further modifications to the store are performed by it. (Other computations can still be initiated afterwards.)

• The execution of an instruction may also end in a jump to a designated target, which defines the next instruction to execute.

• Execution can enter and exit instruction sequences that form blocks.

• Instruction sequences are implicitly executed in order, unless a trap or jump occurs.

• In various places the rules contain assertions expressing crucial invariants about the program state.

4.1.2 Formal Notation

Note: This section gives a brief explanation of the notation for specifying execution formally. For the interested reader, a more thorough introduction can be found in respective textbook.

The formal execution rules use a standard approach for specifying operational semantics, rendering them into reduction rules. Every rule has the following general form:

\[ \text{configuration} \rightarrow \text{configuration} \]

A configuration is a syntactic description of a program state. Each rule specifies one step of execution. As long as there is at most one reduction rule applicable to a given configuration, reduction – and thereby execution – is deterministic. WebAssembly has only very few exceptions to this, which are noted explicitly in this specification.

For WebAssembly, a configuration typically is a tuple \((S; F; \text{instr}^*)\) consisting of the current store \(S\), the call frame \(F\) of the current function, and the sequence of instructions that is to be executed. (A more precise definition is given later.)

To avoid unnecessary clutter, the store \(S\) and the frame \(F\) are omitted from reduction rules that do not touch them.

There is no separate representation of the stack. Instead, it is conveniently represented as part of the configuration’s instruction sequence. In particular, values are defined to coincide with const instructions, and a sequence of const instructions can be interpreted as an operand “stack” that grows to the right.

Note: For example, the reduction rule for the i32.add instruction can be given as follows:

\[
(i32.\text{const } n_1) \ (i32.\text{const } n_2) \ i32.\text{add} \ \rightarrow \ (i32.\text{const } (n_1 + n_2) \mod 2^{32})
\]

Per this rule, two const instructions and the add instruction itself are removed from the instruction stream and replaced with one new const instruction. This can be interpreted as popping two value off the stack and pushing the result.

When no result is produced, an instruction reduces to the empty sequence:

\[
\text{nop} \ \rightarrow \ \epsilon
\]

Labels and frames are similarly defined to be part of an instruction sequence.

The order of reduction is determined by the definition of an appropriate evaluation context.

Reduction terminates when no more reduction rules are applicable. Soundness of the WebAssembly type system guarantees that this is only the case when the original instruction sequence has either been reduced to a sequence of const instructions, which can be interpreted as the values of the resulting operand stack, or if a trap occurred.

\[19\] For example: Benjamin Pierce. Types and Programming Languages. The MIT Press 2002
Note: For example, the following instruction sequence,

\[(f64\text{.const } x_1) (f64\text{.const } x_2) f64\text{.neg} (f64\text{.const } x_3) f64\text{.add} f64\text{.mul}\]

terminates after three steps:

\[
\begin{align*}
(f64\text{.const } x_1) (f64\text{.const } x_2) f64\text{.neg} (f64\text{.const } x_3) f64\text{.add} f64\text{.mul} \\
\rightarrow (f64\text{.const } x_1) (f64\text{.const } x_4) (f64\text{.const } x_3) f64\text{.add} f64\text{.mul} \\
\rightarrow (f64\text{.const } x_1)(f64\text{.const } x_5) f64\text{.mul} \\
\rightarrow (f64\text{.const } x_6)
\end{align*}
\]

where \(x_4 = -x_2 \) and \(x_5 = -x_2 + x_3 \) and \(x_6 = x_1 \cdot (x_3 - x_2) \).

### 4.2 Runtime Structure

*Store, stack,* and other *runtime structure* forming the WebAssembly abstract machine, such as *values* or *module instances*, are made precise in terms of additional auxiliary syntax.

#### 4.2.1 Values

WebAssembly computations manipulate *values* of the four basic *value types*: integers and floating-point data of 32 or 64 bit width each, respectively.

In most places of the semantics, values of different types can occur. In order to avoid ambiguities, values are therefore represented with an abstract syntax that makes their type explicit. It is convenient to reuse the same notation as for the *const instructions* producing them:

\[
\text{val} ::= i32\text{.const } i32 \\
| i64\text{.const } i64 \\
| f32\text{.const } f32 \\
| f64\text{.const } f64
\]

#### 4.2.2 Results

A *result* is the outcome of a computation. It is either a sequence of *values* or a *trap*.

\[
\text{result} ::= \text{val}^* \\
| \text{trap}
\]

Note: In the current version of WebAssembly, a result can consist of at most one value.

#### 4.2.3 Store

The *store* represents all global state that can be manipulated by WebAssembly programs. It consists of the runtime representation of all *instances* of *functions, tables, memories,* and *globals* that have been *allocated* during the life time of the abstract machine.\(^{21}\)

---

\(^{21}\) In practice, implementations may apply techniques like garbage collection to remove objects from the store that are no longer referenced. However, such techniques are not semantically observable, and hence outside the scope of this specification.
Syntactically, the store is defined as a record listing the existing instances of each category:

\[
\text{store} ::= \{ \ \text{funcs funcinst}^* , \\
\text{tables tableinst}^* , \\
\text{mems meminst}^* , \\
\text{globals globalinst}^* \}
\]

**Convention**

- The meta variable \( S \) ranges over stores where clear from context.

### 4.2.4 Addresses

Function instances, table instances, memory instances, and global instances in the store are referenced with abstract addresses. These are simply indices into the respective store component.

\[
\begin{align*}
\text{addr} & ::= 0 | 1 | 2 | \ldots \\
\text{funcaddr} & ::= \text{addr} \\
\text{tableaddr} & ::= \text{addr} \\
\text{memaddr} & ::= \text{addr} \\
\text{globaladdr} & ::= \text{addr}
\end{align*}
\]

An embedder may assign identity to exported store objects corresponding to their addresses, even where this identity is not observable from within WebAssembly code itself (such as for function instances or immutable globals).

**Note:** Addresses are dynamic, globally unique references to runtime objects, in contrast to indices, which are static, module-local references to their original definitions. A memory address \( \text{memaddr} \) denotes the abstract address of a memory instance in the store, not an offset inside a memory instance.

There is no specific limit on the number of allocations of store objects, hence logical addresses can be arbitrarily large natural numbers.

### 4.2.5 Module Instances

A module instance is the runtime representation of a module. It is created by instantiating a module, and collects runtime representations of all entities that are imported, defined, or exported by the module.

\[
\text{moduleinst} ::= \{ \ \text{types functype}^* , \\
\text{funcaddrs funcaddr}^* , \\
\text{tableaddrs tableaddr}^* , \\
\text{memaddrs memaddr}^* , \\
\text{globaladdrs globaladdr}^* , \\
\text{exports exportinst}^* \}
\]

Each component references runtime instances corresponding to respective declarations from the original module – whether imported or defined – in the order of their static indices. Function instances, table instances, memory instances, and global instances are referenced with an indirection through their respective addresses in the store.

It is an invariant of the semantics that all export instances in a given module instance have different names.

### 4.2.6 Function Instances

A function instance is the runtime representation of a function. It effectively is a closure of the original function over the runtime module instance of its originating module. The module instance is used to resolve references to
other definitions during execution of the function.

\[
\text{funcinst} := \begin{cases} \text{type functype, module moduleinst, code func} \\ \text{type functype, hostcode hostfunc} \end{cases}
\]

A host function is a function expressed outside WebAssembly but passed to a module as an import. The definition and behavior of host functions are outside the scope of this specification. For the purpose of this specification, it is assumed that when invoked, a host function behaves non-deterministically, but within certain constraints that ensure the integrity of the runtime.

Note: Function instances are immutable, and their identity is not observable by WebAssembly code. However, the embedder might provide implicit or explicit means for distinguishing their addresses.

### 4.2.7 Table Instances

A table instance is the runtime representation of a table. It holds a vector of function elements and an optional maximum size, if one was specified in the table type at the table’s definition site.

Each function element is either empty, representing an uninitialized table entry, or a function address. Function elements can be mutated through the execution of an element segment or by external means provided by the embedder.

\[
\text{tableinst} := \{ \text{elem vec(funcelem), max u32} \}
\]

It is an invariant of the semantics that the length of the element vector never exceeds the maximum size, if present.

Note: Other table elements may be added in future versions of WebAssembly.

### 4.2.8 Memory Instances

A memory instance is the runtime representation of a linear memory. It holds a vector of bytes and an optional maximum size, if one was specified at the definition site of the memory.

\[
\text{meminst} := \{ \text{data vec(byte), max u32} \}
\]

The length of the vector always is a multiple of the WebAssembly page size, which is defined to be the constant 65536 – abbreviated 64 Ki. Like in a memory type, the maximum size in a memory instance is given in units of this page size.

The bytes can be mutated through memory instructions, the execution of a data segment, or by external means provided by the embedder.

It is an invariant of the semantics that the length of the byte vector, divided by page size, never exceeds the maximum size, if present.

### 4.2.9 Global Instances

A global instance is the runtime representation of a global variable. It holds an individual value and a flag indicating whether it is mutable.

\[
\text{globalinst} := \{ \text{value val, mut mut} \}
\]

The value of mutable globals can be mutated through variable instructions or by external means provided by the embedder.
4.2.10 Export Instances

An export instance is the runtime representation of an export. It defines the export’s name and the associated external value.

\[
\text{exportinst ::= \{} \text{name name}, \text{value externval} \}\]

4.2.11 External Values

An external value is the runtime representation of an entity that can be imported or exported. It is an address denoting either a function instance, table instance, memory instance, or global instances in the shared store.

\[
\text{externval ::= \{} \text{func funcaddr} \mid \text{table tableaddr} \mid \text{mem memaddr} \mid \text{global globaladdr} \}\]

Conventions

The following auxiliary notation is defined for sequences of external values. It filters out entries of a specific kind in an order-preserving fashion:

- \(\text{funcs(externval*)} = \left[ \text{funcaddr} \mid \text{(func funcaddr) } \in \text{externval*} \right]\)
- \(\text{tables(externval*)} = \left[ \text{tableaddr} \mid \text{(table tableaddr) } \in \text{externval*} \right]\)
- \(\text{mems(externval*)} = \left[ \text{memaddr} \mid \text{(mem memaddr) } \in \text{externval*} \right]\)
- \(\text{globals(externval*)} = \left[ \text{globaladdr} \mid \text{(global globaladdr) } \in \text{externval*} \right]\)

4.2.12 Stack

Besides the store, most instructions interact with an implicit stack. The stack contains three kinds of entries:

- **Values**: the operands of instructions.
- **Labels**: active structured control instructions that can be targeted by branches.
- **Activations**: the call frames of active function calls.

These entries can occur on the stack in any order during the execution of a program. Stack entries are described by abstract syntax as follows.

**Note**: It is possible to model the WebAssembly semantics using separate stacks for operands, control constructs, and calls. However, because the stacks are interdependent, additional book keeping about associated stack heights would be required. For the purpose of this specification, an interleaved representation is simpler.

Values

Values are represented by themselves.
Labels

Labels carry an argument arity \( n \) and their associated branch target, which is expressed syntactically as an instruction sequence:

\[
\text{label} \quad ::= \quad \text{label}_n \{ \text{instr}^* \}
\]

Intuitively, \( \text{instr}^* \) is the \textit{continuation} to execute when the branch is taken, in place of the original control construct.

\textbf{Note:} For example, a loop label has the form

\[
\text{label}_n \{ \text{loop } [t^*] \ldots \text{end} \}
\]

When performing a branch to this label, this executes the loop, effectively restarting it from the beginning. Conversely, a simple block label has the form

\[
\text{label}_n \{ \epsilon \}
\]

When branching, the empty continuation ends the targeted block, such that execution can proceed with consecutive instructions.

Frames

Activation frames carry the return arity of the respective function, hold the values of its locals (including arguments) in the order corresponding to their static local indices, and a reference to the function’s own module instance:

\[
\text{activation} \quad ::= \quad \text{frame}_n \{ \text{frame} \}
\]

\[
\text{frame} \quad ::= \quad \{ \text{locals } \text{val}^*, \text{module } \text{moduleinst} \}
\]

The values of the locals are mutated by respective \textit{variable instructions}.

Conventions

- The meta variable \( L \) ranges over labels where clear from context.
- The meta variable \( F \) ranges over frames where clear from context.

\textbf{Note:} In the current version of WebAssembly, the arities of labels and frames cannot be larger than 1. This may be generalized in future versions.

4.2.13 Administrative Instructions

\textbf{Note:} This section is only relevant for the \textit{formal notation}.

In order to express the reduction of \textit{traps, calls, and control instructions}, the syntax of instructions is extended to include the following \textit{administrative instructions}:

\[
\text{instr} \quad ::= \quad \ldots \\
| \quad \text{trap} \\
| \quad \text{invoke } \text{funcaddr} \\
| \quad \text{init}_\text{elem} \text{tableaddr } u32 \text{funcidx}^* \\
| \quad \text{init}_\text{data} \text{memaddr } u32 \text{byte}^* \\
| \quad \text{label}_n \{ \text{instr}^* \} \text{instr}^* \text{end} \\
| \quad \text{frame}_n \{ \text{frame} \} \text{instr}^* \text{end}
\]
The *trap* instruction represents the occurrence of a trap. Traps are bubbled up through nested instruction sequences, ultimately reducing the entire program to a single *trap* instruction, signalling abrupt termination.

The *invoke* instruction represents the imminent invocation of a *function instance*, identified by its *address*. It unifies the handling of different forms of calls.

The *init_elem* and *init_data* instructions perform initialization of *element* and *data* segments during module *instantiation*.

**Note:** The reason for splitting instantiation into individual reduction steps is to provide a semantics that is compatible with future extensions like threads.

The *label* and *frame* instructions model *labels* and *frames “on the stack”*. Moreover, the administrative syntax maintains the nesting structure of the original *structured control instruction* or *function body* and their *instruction sequences* with an *end* marker. That way, the end of the inner instruction sequence is known when part of an outer sequence.

**Note:** For example, the *reduction rule* for *block* is:

\[
\text{block } [t^n] \text{ instr}^* \text{ end } \leftrightarrow \text{ label}_n \{ \epsilon \} \text{ instr}^* \text{ end}
\]

This replaces the block with a label instruction, which can be interpreted as “pushing” the label on the stack. When *end* is reached, i.e., the inner instruction sequence has been reduced to the empty sequence – or rather, a sequence of *n const* instructions representing the resulting values – then the *label* instruction is eliminated courtesy of its own *reduction rule*:

\[
\text{label}_n \{ \text{instr}^n \} \text{ val}^* \text{ end } \leftrightarrow \text{ val}^m
\]

This can be interpreted as removing the label from the stack and only leaving the locally accumulated operand values.

**Block Contexts**

In order to specify the reduction of *branches*, the following syntax of *block contexts* is defined, indexed by the count *k* of labels surrounding the hole:

\[
B^0 \quad ::= \quad \text{val}^* \quad [\_\_] \quad \text{instr}^* \\
B^{k+1} \quad ::= \quad \text{val}^* \quad \text{label}_n \{ \text{instr}^n \} \quad B^k \quad \text{end} \quad \text{instr}^*
\]

This definition allows to index active labels surrounding a *branch* or *return* instruction.

**Note:** For example, the *reduction* of a simple branch can be defined as follows:

\[
\text{label}_0 \{ \text{instr}^* \} \quad B^l [\text{br } l] \quad \text{end} \leftrightarrow \text{instr}^*
\]

Here, the hole [\_] of the context is instantiated with a branch instruction. When a branch occurs, this rule replaces the targeted label and associated instruction sequence with the label’s continuation. The selected label is identified through the *label index* *l*, which corresponds to the number of surrounding *label* instructions that must be hopped over – which is exactly the count encoded in the index of a block context.

**Configurations**

A *configuration* consists of the current *store* and an executing *thread*. 
A thread is a computation over instructions that operates relative to a current frame referring to the home module instance that the computation runs in.

\[
\text{config} ::= \text{store; thread} \\
\text{thread} ::= \text{frame; instr}^* \\
\]

**Note:** The current version of WebAssembly is single-threaded, but configurations with multiple threads may be supported in the future.

### Evaluation Contexts

Finally, the following definition of evaluation context and associated structural rules enable reduction inside instruction sequences and administrative forms as well as the propagation of traps:

\[
E ::= \_ | \text{val}^* E instr^* | \text{label}_n \{ \text{instr}^* \} E \text{ end} \\
S; F; E[\text{instr}^*] \leftrightarrow S'; F'; E[\text{instr}''^*] \\
\text{(if } S; F; \text{instr}^* \leftrightarrow S'; F'; \text{instr}''^*) \\
S; F; \text{frame}_n \{ F' \} \text{ instr}^* \text{ end} \leftrightarrow S'; F'; \text{frame}_n \{ F'' \} \text{ instr}''^* \text{ end} \\
\text{(if } S; F; \text{instr}^* \leftrightarrow S'; F'; \text{instr}''^*) \\
S; F; E[\text{trap}] \leftrightarrow S; F; \text{trap} \text{ (if } E \neq \_ \) \\
S; F; \text{frame}_n \{ F' \} \text{ trap} \text{ end} \leftrightarrow S; F; \text{trap} \]

Reduction terminates when a thread’s instruction sequence has been reduced to a result, that is, either a sequence of values or to a trap.

**Note:** The restriction on evaluation contexts rules out contexts like \( \_ \) and \( \varepsilon \) for which \( E[\text{trap}] = \text{trap} \).

For an example of reduction under evaluation contexts, consider the following instruction sequence.

\[
(f64.\text{const } x_1) (f64.\text{const } x_2) f64.\text{neg} (f64.\text{const } x_3) f64.\text{add} f64.\text{mul} \\
\]

This can be decomposed into \( E[(f64.\text{const } x_2) f64.\text{neg}] \) where

\[
E = (f64.\text{const } x_1) \_ (f64.\text{const } x_3) f64.\text{add} f64.\text{mul} \\
\]

Moreover, this is the only possible choice of evaluation context where the contents of the hole matches the left-hand side of a reduction rule.

### 4.3 Numerics

Numeric primitives are defined in a generic manner, by operators indexed over a bit width \( N \).

Some operators are non-deterministic, because they can return one of several possible results (such as different \( \text{NaN} \) values). Technically, each operator thus returns a set of allowed values. For convenience, deterministic results are expressed as plain values, which are assumed to be identified with a respective singleton set.

Some operators are partial, because they are not defined on certain inputs. Technically, an empty set of results is returned for these inputs.

In formal notation, each operator is defined by equational clauses that apply in decreasing order of precedence. That is, the first clause that is applicable to the given arguments defines the result. In some cases, similar clauses are combined into one by using the notation \( \pm \) or \( \mp \). When several of these placeholders occur in a single clause, then they must be resolved consistently: either the upper sign is chosen for all of them or the lower sign.
WebAssembly Specification, Release 1.0

Note: For example, the \texttt{fcopysign} operator is defined as follows:

\[
\texttt{fcopysign}_N(\pm p_1, \pm p_2) = \pm p_1 \\
\texttt{fcopysign}_N(\pm p_1, \mp p_2) = \mp p_1
\]

This definition is to be read as a shorthand for the following expansion of each clause into two separate ones:

\[
\texttt{fcopysign}_N(+p_1, +p_2) = +p_1 \\
\texttt{fcopysign}_N(-p_1, -p_2) = -p_1 \\
\texttt{fcopysign}_N(+p_1, -p_2) = -p_1 \\
\texttt{fcopysign}_N(-p_1, +p_2) = +p_1
\]

Conventions:

- The meta variable \( d \) is used to range over single bits.
- The meta variable \( p \) is used to range over (signless) \textit{magnitudes} of floating-point values, including \texttt{nan} and \( \infty \).
- The meta variable \( q \) is used to range over (signless) \textit{rational magnitudes}, excluding \texttt{nan} or \( \infty \).
- The notation \( f^{-1} \) denotes the inverse of a bijective function \( f \).
- Truncation of rational values is written \texttt{trunc}(\pm q), with the usual mathematical definition:

\[
\texttt{trunc}(\pm q) = \pm i \quad (\text{if } i \in \mathbb{N} \land q - 1 < i \leq q)
\]

4.3.1 Representations

Numbers have an underlying binary representation as a sequence of bits:

\[
\texttt{bits}_N(i) = \texttt{ibits}_N(i) \\
\texttt{bits}_N(z) = \texttt{fbits}_N(z)
\]

Each of these functions is a bijection, hence they are invertible.

Integers

\textit{Integers} are represented as base two unsigned numbers:

\[
\texttt{ibits}_N(i) = d_{N-1} \cdots d_0 \quad (i = 2^{N-1} \cdot d_{N-1} + \cdots + 2^0 \cdot d_0)
\]

Boolean operators like \( \wedge, \lor, \) or \( \lor \) are lifted to bit sequences of equal length by applying them pointwise.

Floating-Point

\textit{Floating-point values} are represented in the respective binary format defined by IEEE 754-2008\textsuperscript{22} (Section 3.4):

\[
\begin{align*}
\texttt{fbits}_N(\pm(1 + m \cdot 2^{-M}) \cdot 2^e) &= \texttt{fsign}(\pm) \texttt{fbias}_N(e + \texttt{fbias}_N) \texttt{ibits}_M(m) \\
\texttt{fbits}_N(\pm(0 + m \cdot 2^{-M}) \cdot 2^e) &= \texttt{fsign}(\pm) (0)^E \texttt{ibits}_M(m) \\
\texttt{fbits}_N(\pm\infty) &= \texttt{fsign}(\pm) (1)^E (0)^M \\
\texttt{fbits}_N(\pm\texttt{nan}(n)) &= \texttt{fsign}(\pm) (1)^E \texttt{ibits}_M(n) \\
\texttt{fbias}_N &= 2^{E-1} - 1 \\
\texttt{fsign}(+) &= 0 \\
\texttt{fsign}(-) &= 1
\end{align*}
\]

where \( M = \texttt{signif}(N) \) and \( E = \texttt{expon}(N) \).

\textsuperscript{22} http://ieeexplore.ieee.org/document/4610935/
Storage

When a number is stored into memory, it is converted into a sequence of bytes in little endian\(^\text{23}\) byte order:

\[
\text{bytes}_i(i) = \text{littleendian}(\text{bits}_i(i))
\]

\[
\text{littleendian}(\epsilon) = \epsilon
\]

\[
\text{littleendian}(d_1 d_2^{N-8}) = \text{ibits}_{8}^{-1}(d_1) \text{littleendian}(d_2^{N-8})
\]

Again these functions are invertable bijections.

4.3.2 Integer Operations

Sign Interpretation

Integer operators are defined on \(i_N\) values. Operators that use a signed interpretation convert the value using the following definition, which takes the two’s complement when the value lies in the upper half of the value range (i.e., its most significant bit is 1):

\[
\text{signed}_N(i) = i \quad (0 \leq i < 2^{N-1})
\]

\[
\text{signed}_N(i) = i - 2^N \quad (2^{N-1} \leq i < 2^N)
\]

This function is bijective, and hence invertible.

Boolean Interpretation

The integer result of predicates – i.e., tests and relational operators – is defined with the help of the following auxiliary function producing the value 1 or 0 depending on a condition.

\[
\text{bool}(C) = 1 \quad \text{(if } C\text{)}
\]

\[
\text{bool}(C) = 0 \quad \text{(otherwise)}
\]

\(\text{iadd}_N(i_1, i_2)\)

- Return the result of adding \(i_1\) and \(i_2\) modulo \(2^N\).

\[
\text{iadd}_N(i_1, i_2) = (i_1 + i_2) \mod 2^N
\]

\(\text{isub}_N(i_1, i_2)\)

- Return the result of subtracting \(i_2\) from \(i_1\) modulo \(2^N\).

\[
\text{isub}_N(i_1, i_2) = (i_1 - i_2 + 2^N) \mod 2^N
\]

\(\text{imul}_N(i_1, i_2)\)

- Return the result of multiplying \(i_1\) and \(i_2\) modulo \(2^N\).

\[
\text{imul}_N(i_1, i_2) = (i_1 \cdot i_2) \mod 2^N
\]

\(^{23}\) https://en.wikipedia.org/wiki/Endianness#Little-endian
idiv_uN(i_1, i_2)

- If \( i_2 = 0 \), then the result is undefined.
- Else, return the result of dividing \( i_1 \) by \( i_2 \), truncated toward zero.

\[
\begin{align*}
\text{idiv}_uN(i_1, 0) & = \emptyset \\
idiv_uN(i_1, i_2) & = \text{trunc}(i_1/i_2)
\end{align*}
\]

**Note:** This operator is *partial*.

idiv_sN(i_1, i_2)

- Let \( j_1 \) be the signed interpretation of \( i_1 \).
- Let \( j_2 \) be the signed interpretation of \( i_2 \).
- If \( j_2 = 0 \), then the result is undefined.
- Else if \( j_1 \) divided by \( j_2 \) is \( 2^N - 1 \), then the result is undefined.
- Else, return the result of dividing \( j_1 \) by \( j_2 \), truncated toward zero.

\[
\begin{align*}
idiv_sN(i_1, 0) & = \emptyset \\
idiv_sN(i_1, i_2) & = \emptyset \text{ (if } \text{signed}_N(i_1)/\text{signed}_N(i_2) = 2^{N-1} \text{)} \\
idiv_sN(i_1, i_2) & = \text{signed}_N^{-1}(\text{trunc}(\text{signed}_N(i_1)/\text{signed}_N(i_2)))
\end{align*}
\]

**Note:** This operator is *partial*. Besides division by 0, the result of \((-2^{N-1})/(-1) = +2^{N-1}\) is not representable as an \(N\)-bit signed integer.

irem_uN(i_1, i_2)

- If \( i_2 = 0 \), then the result is undefined.
- Else, return the remainder of dividing \( i_1 \) by \( i_2 \).

\[
\begin{align*}
\text{irem}_uN(i_1, 0) & = \emptyset \\
\text{irem}_uN(i_1, i_2) & = i_1 - i_2 \cdot \text{trunc}(i_1/i_2)
\end{align*}
\]

**Note:** This operator is *partial*.

As long as both operators are defined, it holds that \( i_1 = i_2 \cdot \text{idiv}_u(i_1, i_2) + \text{irem}_u(i_1, i_2) \).

irem_sN(i_1, i_2)

- Let \( j_1 \) be the signed interpretation of \( i_1 \).
- Let \( j_2 \) be the signed interpretation of \( i_2 \).
- If \( i_2 = 0 \), then the result is undefined.
- Else, return the remainder of dividing \( j_1 \) by \( j_2 \), with the sign of the dividend \( j_1 \).

\[
\begin{align*}
\text{irem}_sN(i_1, 0) & = \emptyset \\
\text{irem}_sN(i_1, i_2) & = \text{signed}_N^{-1}(j_1 - j_2 \cdot \text{trunc}(j_1/j_2)) \\
& \quad \text{(where } j_1 = \text{signed}_N(i_1) \land j_2 = \text{signed}_N(i_2) \text{)}
\end{align*}
\]

**Note:** This operator is *partial*. 

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As long as both operators are defined, it holds that \( i_1 = i_2 \cdot \text{idiv}_\mathbb{S}(i_1, i_2) + \text{irem}_\mathbb{S}(i_1, i_2) \).

\( \text{iand}_N(i_1, i_2) \)

- Return the bitwise conjunction of \( i_1 \) and \( i_2 \).
  \[
  \text{iand}_N(i_1, i_2) = \text{ibits}_N^{-1}(\text{ibits}_N(i_1) \land \text{ibits}_N(i_2))
  \]

\( \text{ior}_N(i_1, i_2) \)

- Return the bitwise disjunction of \( i_1 \) and \( i_2 \).
  \[
  \text{ior}_N(i_1, i_2) = \text{ibits}_N^{-1}(\text{ibits}_N(i_1) \lor \text{ibits}_N(i_2))
  \]

\( \text{ixor}_N(i_1, i_2) \)

- Return the bitwise exclusive disjunction of \( i_1 \) and \( i_2 \).
  \[
  \text{ixor}_N(i_1, i_2) = \text{ibits}_N^{-1}(\text{ibits}_N(i_1) \oplus \text{ibits}_N(i_2))
  \]

\( \text{ishl}_N(i_1, i_2) \)

- Let \( k \) be \( i_2 \) modulo \( N \).
- Return the result of shifting \( i_1 \) left by \( k \) bits, modulo \( 2^N \).
  \[
  \text{ishl}_N(i_1, i_2) = \text{ibits}_N^{-1}(d_2^{N-k} 0^k) \quad \text{(if } \text{ibits}_N(i_1) = d_1^k d_2^{N-k} \land k = i_2 \text{ mod } N)\]

\( \text{ishr}_u_N(i_1, i_2) \)

- Let \( j_2 \) be \( i_2 \) modulo \( N \).
- Return the result of shifting \( i_1 \) right by \( j_2 \) bits, extended with 0 bits.
  \[
  \text{ishr}_u_N(i_1, i_2) = \text{ibits}_N^{-1}(0^k d_1^{N-k}) \quad \text{(if } \text{ibits}_N(i_1) = d_1^{N-k} d_2^k \land k = i_2 \text{ mod } N)\]

\( \text{ishr}_s_N(i_1, i_2) \)

- Let \( j_2 \) be \( i_2 \) modulo \( N \).
- Return the result of shifting \( i_1 \) right by \( j_2 \) bits, extended with the most significant bit of the original value.
  \[
  \text{ishr}_s_N(i_1, i_2) = \text{ibits}_N^{-1}(d_0^{k+1} d_1^{N-k-1}) \quad \text{(if } \text{ibits}_N(i_1) = d_0 d_1^{N-k} d_2^k \land k = i_2 \text{ mod } N)\]

\( \text{irotl}_N(i_1, i_2) \)

- Let \( j_2 \) be \( i_2 \) modulo \( N \).
- Return the result of rotating \( i_1 \) left by \( j_2 \) bits.
  \[
  \text{irotl}_N(i_1, i_2) = \text{ibits}_N^{-1}(d_2^{N-k} d_1^k) \quad \text{(if } \text{ibits}_N(i_1) = d_1^k d_2^{N-k} \land k = i_2 \text{ mod } N)\]

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\( \text{irotr}_N(i_1, i_2) \)

- Let \( j_2 \) be \( i_2 \) modulo \( N \).
- Return the result of rotating \( i_1 \) right by \( j_2 \) bits.

\[
\text{irotr}_N(i_1, i_2) = \text{ibits}_N^{-1}(d_2^N d_1^{N-k}) \quad \text{(if ibits}_N(i_1) = d_1^{N-k}d_2^k \land k = i_2 \mod N) \]

\( \text{iclz}_N(i) \)

- Return the count of leading zero bits in \( i \); all bits are considered leading zeros if \( i \) is 0.

\[
\text{iclz}_N(i) = k \quad \text{(if ibits}_N(i) = 0^k (1 d^*)^r) \]

\( \text{ictz}_N(i) \)

- Return the count of trailing zero bits in \( i \); all bits are considered trailing zeros if \( i \) is 0.

\[
\text{ictz}_N(i) = k \quad \text{(if ibits}_N(i) = (d^* 1)^r 0^k) \]

\( \text{ipopcnt}_N(i) \)

- Return the count of non-zero bits in \( i \).

\[
\text{ipopcnt}_N(i) = k \quad \text{(if ibits}_N(i) = (0^* 1)^k 0^*) \]

\( \text{ieqz}_N(i) \)

- Return 1 if \( i \) is zero, 0 otherwise.

\[
\text{ieqz}_N(i) = \text{bool}(i = 0) \]

\( \text{ieq}_N(i_1, i_2) \)

- Return 1 if \( i_1 \) equals \( i_2 \), 0 otherwise.

\[
\text{ieq}_N(i_1, i_2) = \text{bool}(i_1 = i_2) \]

\( \text{ine}_N(i_1, i_2) \)

- Return 1 if \( i_1 \) does not equal \( i_2 \), 0 otherwise.

\[
\text{ine}_N(i_1, i_2) = \text{bool}(i_1 \neq i_2) \]

\( \text{ilt}_uN(i_1, i_2) \)

- Return 1 if \( i_1 \) is less than \( i_2 \), 0 otherwise.

\[
\text{ilt}_uN(i_1, i_2) = \text{bool}(i_1 < i_2) \]
\[ \text{ilt}_N(i_1, i_2) = \begin{cases} 1 & \text{if } i_1 < i_2 \leq 0 \\ 0 & \text{otherwise} \end{cases} \]

\[ \text{igt}_u_N(i_1, i_2) = \begin{cases} 1 & \text{if } i_1 > i_2 \\ 0 & \text{otherwise} \end{cases} \]

\[ \text{igt}_s_N(i_1, i_2) = \begin{cases} 1 & \text{if } i_1 > i_2 \\ 0 & \text{otherwise} \end{cases} \]

\[ \text{ile}_u_N(i_1, i_2) = \begin{cases} 1 & \text{if } i_1 \leq i_2 \\ 0 & \text{otherwise} \end{cases} \]

\[ \text{ile}_s_N(i_1, i_2) = \begin{cases} 1 & \text{if } i_1 \leq i_2 \\ 0 & \text{otherwise} \end{cases} \]

\[ \text{ige}_u_N(i_1, i_2) = \begin{cases} 1 & \text{if } i_1 \geq i_2 \\ 0 & \text{otherwise} \end{cases} \]

\[ \text{ige}_s_N(i_1, i_2) = \begin{cases} 1 & \text{if } i_1 \geq i_2 \\ 0 & \text{otherwise} \end{cases} \]
4.3.3 Floating-Point Operations

Floating-point arithmetic follows the IEEE 754-2008\(^{24}\) standard, with the following qualifications:

- All operators use round-to-nearest ties-to-even, except where otherwise specified. Non-default directed rounding attributes are not supported.
- Following the recommendation that operators propagate NaN payloads from their operands is permitted but not required.
- All operators use “non-stop” mode, and floating-point exceptions are not otherwise observable. In particular, neither alternate floating-point exception handling attributes nor operators on status flags are supported. There is no observable difference between quiet and signalling NaNs.

**Note:** Some of these limitations may be lifted in future versions of WebAssembly.

### Rounding

Rounding always is round-to-nearest ties-to-even, in correspondence with IEEE 754-2008\(^{25}\) (Section 4.3.1).

An *exact* floating-point number is a rational number that is exactly representable as a *floating-point number* of given bit width \(N\).

A *limit* number for a given floating-point bit width \(N\) is a positive or negative number whose magnitude is the smallest power of 2 that is not exactly representable as a floating-point number of width \(N\) (that magnitude is \(2^{128}\) for \(N = 32\) and \(2^{1024}\) for \(N = 64\)).

A *candidate* number is either an exact floating-point number or a positive or negative limit number for the given bit width \(N\).

A *candidate pair* is a pair \(z_1, z_2\) of candidate numbers, such that no candidate number exists that lies between the two.

A real number \(r\) is converted to a floating-point value of bit width \(N\) as follows:

- If \(r = 0\), then return \(+0\).
- Else if \(r\) is an exact floating-point number, then return \(r\).
- Else if \(r\) greater than or equal to the positive limit, then return \(+\infty\).
- Else if \(r\) is less than or equal to the negative limit, then return \(-\infty\).
- Else if \(z_1\) and \(z_2\) are a candidate pair such that \(z_1 < r < z_2\), then:
  - If \(|r - z_1| < |r - z_2|\), then let \(z\) be \(z_1\).
  - Else if \(|r - z_1| > |r - z_2|\), then let \(z\) be \(z_2\).
  - Else if \(|r - z_1| = |r - z_2|\) and the significand of \(z_1\) is even, then let \(z\) be \(z_1\).
  - Else, let \(z\) be \(z_2\).
- If \(z\) is \(0\), then:
  - If \(r < 0\), then return \(-0\).
  - Else, return \(+0\).
- Else if \(z\) is a limit number, then:
  - If \(r < 0\), then return \(-\infty\).
  - Else, return \(+\infty\).

\(^{24}\) http://ieeexplore.ieee.org/document/4610935/

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This non-deterministic result is expressed by the following auxiliary function producing a set of allowed outputs

\[
\text{float}_{N}(0) = +0 \\
\text{float}_{N}(r) = r \\
\text{float}_{N}(r) = +\infty \\
\text{float}_{N}(r) = -\infty \\
\text{float}_{N}(r) = \text{closest}_{N}(r, z_1, z_2) \\
\text{closest}_{N}(r, z_1, z_2) = \text{rectify}_{N}(r, z_1) \\
\text{closest}_{N}(r, z_1, z_2) = \text{rectify}_{N}(r, z_2) \\
\text{rectify}_{N}(r, \pm \text{limit}_{N}) = \pm \infty \\
\text{rectify}_{N}(r, 0) = +0 (r \geq 0) \\
\text{rectify}_{N}(r, 0) = -0 (r < 0) \\
\text{rectify}_{N}(r, z) = z
\]

where:

\[
\text{exact}_{N} = fN \cap Q \\
\text{limit}_{N} = 2^{2^\text{exponent}(N) - 1} \\
\text{candidate}_{N} = \text{exact}_{N} \cup \{\pm \text{limit}_{N}, -\text{limit}_{N}\} \\
\text{candidatepair}_{N} = \{(z_1, z_2) \in \text{candidate}_{N}^2 \mid z_1 < z_2 \land \forall z \in \text{candidate}_{N}, z \leq z_1 \lor z \geq z_2\} \\
\text{even}_{N}(d + m \cdot 2^{-M} \cdot 2^e) \iff m \mod 2 = 0 \\
\text{even}_{N}(\pm \text{limit}_{N}) \iff \text{true}
\]

NaN Propagation

When the result of a floating-point operator other than \text{fneg}, \text{fabs}, or \text{fcopysign} is a NaN, then its sign is non-deterministic and the payload is computed as follows:

- If the payload of all NaN inputs to the operator is canonical (including the case that there are no NaN inputs), then the payload of the output is canonical as well.
- Otherwise the payload is picked non-deterministically among all arithmetic NaNs; that is, its most significant bit is 1 and all others are unspecified.

This non-deterministic result is expressed by the following auxiliary function producing a set of allowed outputs from a set of inputs:

\[
\text{nans}_{N}(z^*) = \{+\text{nan}(n), -\text{nan}(n) \mid n = \text{canon}_{N}\} \\
\text{nans}_{N}(z^*) = \{+\text{nan}(n), -\text{nan}(n) \mid n \geq \text{canon}_{N}\} \\
\text{fadd}_{N}(z_1, z_2)
\]

- If either \(z_1\) or \(z_2\) is a NaN, then return an element of \(\text{nans}_{N}(z_1, z_2)\).
- Else if both \(z_1\) and \(z_2\) are infinities of opposite signs, then return an element of \(\text{nans}_{N}(z_1, z_2)\).
- Else if both \(z_1\) and \(z_2\) are infinities of equal sign, then return that infinity.
- Else if one of \(z_1\) or \(z_2\) is an infinity, then return that infinity.
- Else if both \(z_1\) and \(z_2\) are zeroes of opposite sign, then return positive zero.
- Else if both \(z_1\) and \(z_2\) are zeroes of equal sign, then return that zero.
- Else if one of \(z_1\) or \(z_2\) is a zero, then return the other operand.
- Else if both \(z_1\) and \(z_2\) are values with the same magnitude but opposite signs, then return positive zero.
- Else return the result of adding \(z_1\) and \(z_2\), \text{rounded} to the nearest representable value.
\[
\begin{align*}
\text{fadd}_N(\pm \text{nan}(n), z_2) &= \text{nans}_N \{ \pm \text{nan}(n), z_2 \} \\
\text{fadd}_N(z_1, \pm \text{nan}(n)) &= \text{nans}_N \{ \pm \text{nan}(n), z_1 \} \\
\text{fadd}_N(\pm \infty, \mp \infty) &= \text{nans}_N \{ \} \\
\text{fadd}_N(\pm \infty, \pm \infty) &= \pm \infty \\
\text{fadd}_N(z_1, \pm \infty) &= \pm \infty \\
\text{fadd}_N(\pm \infty, z_2) &= \pm \infty \\
\text{fadd}_N(\pm 0, \mp 0) &= +0 \\
\text{fadd}_N(\pm 0, \pm 0) &= \pm 0 \\
\text{fadd}_N(z_1, \pm 0) &= z_1 \\
\text{fadd}_N(\pm 0, z_2) &= z_2 \\
\text{fadd}_N(\pm q, \mp q) &= +0 \\
\text{fadd}_N(z_1, z_2) &= \text{float}_N(z_1 + z_2)
\end{align*}
\]

\[\text{fsub}_N(z_1, z_2)\]

- If either \(z_1\) or \(z_2\) is a NaN, then return an element of \(\text{nans}_N \{ z_1, z_2 \}\).
- Else if both \(z_1\) and \(z_2\) are infinities of equal signs, then return an element of \(\text{nans}_N \{ z_1, z_2 \}\).
- Else if both \(z_1\) and \(z_2\) are infinities of opposite sign, then return \(z_1\).
- Else if \(z_1\) is an infinity, then return that infinity.
- Else if \(z_2\) is an infinity, then return that infinity negated.
- Else if both \(z_1\) and \(z_2\) are zeroes of equal sign, then return positive zero.
- Else if both \(z_1\) and \(z_2\) are zeroes of opposite sign, then return \(z_1\).
- Else if \(z_2\) is a zero, then return \(z_1\).
- Else if \(z_1\) is a zero, then return \(z_2\) negated.
- Else if both \(z_1\) and \(z_2\) are the same value, then return positive zero.
- Else return the result of subtracting \(z_2\) from \(z_1\), rounded to the nearest representable value.

\[
\begin{align*}
\text{fsub}_N(\pm \text{nan}(n), z_2) &= \text{nans}_N \{ \pm \text{nan}(n), z_2 \} \\
\text{fsub}_N(z_1, \pm \text{nan}(n)) &= \text{nans}_N \{ \pm \text{nan}(n), z_1 \} \\
\text{fsub}_N(\pm \infty, \mp \infty) &= \text{nans}_N \{ \} \\
\text{fsub}_N(\pm \infty, \pm \infty) &= \pm \infty \\
\text{fsub}_N(z_1, \pm \infty) &= \mp \infty \\
\text{fsub}_N(\pm \infty, z_2) &= \pm \infty \\
\text{fsub}_N(\pm 0, \mp 0) &= +0 \\
\text{fsub}_N(\pm 0, \pm 0) &= \mp 0 \\
\text{fsub}_N(z_1, \pm 0) &= z_1 \\
\text{fsub}_N(\pm 0, z_2) &= \mp q_2 \\
\text{fsub}_N(\pm q, \mp q) &= +0 \\
\text{fsub}_N(z_1, z_2) &= \text{float}_N(z_1 - z_2)
\end{align*}
\]

**Note:** Up to the non-determinism regarding NaNs, it always holds that \(\text{fsub}_N(z_1, z_2) = \text{fadd}_N(z_1, \text{fneg}_N(z_2))\).

\[\text{fmul}_N(z_1, z_2)\]

- If either \(z_1\) or \(z_2\) is a NaN, then return an element of \(\text{nans}_N \{ z_1, z_2 \}\).
- Else if one of \(z_1\) and \(z_2\) is a zero and the other an infinity, then return an element of \(\text{nans}_N \{ z_1, z_2 \}\).
- Else if both \(z_1\) and \(z_2\) are infinities of equal sign, then return positive infinity.
- Else if both \(z_1\) and \(z_2\) are infinities of opposite sign, then return negative infinity.
- Else if one of \(z_1\) or \(z_2\) is an infinity and the other a value with equal sign, then return positive infinity.
• Else if one of \( z_1 \) or \( z_2 \) is an infinity and the other a value with opposite sign, then return negative infinity.
• Else if both \( z_1 \) and \( z_2 \) are zeroes of equal sign, then return positive zero.
• Else if both \( z_1 \) and \( z_2 \) are zeroes of opposite sign, then return negative zero.
• Else return the result of multiplying \( z_1 \) and \( z_2 \), rounded to the nearest representable value.

\[
\text{fdiv}_N(z_1, z_2)
\]

• If either \( z_1 \) or \( z_2 \) is a NaN, then return an element of \( \text{nans}_N \{z_1, z_2\} \).
• Else if both \( z_1 \) and \( z_2 \) are infinities, then return an element of \( \text{nans}_N \{z_1, z_2\} \).
• Else if both \( z_1 \) and \( z_2 \) are zeroes, then return an element of \( \text{nans}_N \{z_1, z_2\} \).
• Else if \( z_1 \) is an infinity and \( z_2 \) a value with equal sign, then return positive infinity.
• Else if \( z_1 \) is an infinity and \( z_2 \) a value with opposite sign, then return negative infinity.
• Else if \( z_2 \) is an infinity and \( z_1 \) a value with equal sign, then return positive zero.
• Else if \( z_2 \) is an infinity and \( z_1 \) a value with opposite sign, then return negative zero.
• Else if \( z_1 \) is a zero and \( z_2 \) a value with equal sign, then return positive zero.
• Else if \( z_1 \) is a zero and \( z_2 \) a value with opposite sign, then return negative zero.
• Else if \( z_2 \) is a zero and \( z_1 \) a value with equal sign, then return positive infinity.
• Else if \( z_2 \) is a zero and \( z_1 \) a value with opposite sign, then return negative infinity.
• Else return the result of dividing \( z_1 \) by \( z_2 \), rounded to the nearest representable value.

\[
\text{fdiv}_N(z_1, z_2) = \text{float}_N(z_1 / z_2)
\]
\( fmin_N(z_1, z_2) \)

- If either \( z_1 \) or \( z_2 \) is a NaN, then return an element of \( nans_N \{ z_1, z_2 \} \).
- Else if one of \( z_1 \) or \( z_2 \) is a negative infinity, then return negative infinity.
- Else if one of \( z_1 \) or \( z_2 \) is a positive infinity, then return the other value.
- Else if both \( z_1 \) and \( z_2 \) are zeroes of opposite signs, then return negative zero.
- Else return the smaller value of \( z_1 \) and \( z_2 \).

\[

text{fmin}(±\text{nan}(n), z_2) = \text{nans}(±\text{nan}(n), z_2) \\
text{fmin}(z_1, ±\text{nan}(n)) = \text{nans}(±\text{nan}(n), z_1) \\
text{fmin}(+\infty, z_2) = z_2 \\
text{fmin}(-\infty, z_2) = -\infty \\
text{fmin}(z_1, +\infty) = z_1 \\
text{fmin}(z_1, -\infty) = -\infty \\
text{fmin}(±0, ±0) = -0 \\
text{fmin}(z_1, z_2) = z_1 \quad \text{(if } z_1 \leq z_2) \\
text{fmin}(z_1, z_2) = z_2 \quad \text{(if } z_2 \leq z_1) 
\]

\( fmax_N(z_1, z_2) \)

- If either \( z_1 \) or \( z_2 \) is a NaN, then return an element of \( nans_N \{ z_1, z_2 \} \).
- Else if one of \( z_1 \) or \( z_2 \) is a positive infinity, then return positive infinity.
- Else if one of \( z_1 \) or \( z_2 \) is a negative infinity, then return the other value.
- Else if both \( z_1 \) and \( z_2 \) are zeroes of opposite signs, then return positive zero.
- Else return the larger value of \( z_1 \) and \( z_2 \).

\[

text{fmax}(±\text{nan}(n), z_2) = \text{nans}(±\text{nan}(n), z_2) \\
text{fmax}(z_1, ±\text{nan}(n)) = \text{nans}(±\text{nan}(n), z_1) \\
text{fmax}(+\infty, z_2) = +\infty \\
text{fmax}(-\infty, z_2) = z_2 \\
text{fmax}(z_1, +\infty) = +\infty \\
text{fmax}(z_1, -\infty) = z_1 \\
text{fmax}(±0, ±0) = +0 \\
text{fmax}(z_1, z_2) = z_1 \quad \text{(if } z_1 \geq z_2) \\
text{fmax}(z_1, z_2) = z_2 \quad \text{(if } z_2 \geq z_1) 
\]

\( \text{fcopysign}_N(z_1, z_2) \)

- If \( z_1 \) and \( z_2 \) have the same sign, then return \( z_1 \).
- Else return \( z_1 \) with negated sign.

\[
\text{fcopysign}(±p_1, ±p_2) = ±p_1 \\
\text{fcopysign}(±p_1, ±p_2) = ±p_1 
\]

\( \text{fabs}_N(z) \)

- If \( z \) is a NaN, then return \( z \) with positive sign.
- Else if \( z \) is an infinity, then return positive infinity.
- Else if \( z \) is a zero, then return positive zero.
- Else if \( z \) is a positive value, then \( z \).
- Else return \( z \) negated.
fabs_N(±nan(n)) = +nan(n)
fabs_N(±∞) = +∞
fabs_N(±0) = +0
f abs_N(±q) = +q

fneg_N(z)

• If z is a NaN, then return z with negated sign.
• Else if z is an infinity, then return that infinity negated.
• Else if z is a zero, then return that zero negated.
• Else return z negated.

fneg_N(±nan(n)) = ±nan(n)
fneg_N(±∞) = ±∞
fneg_N(±0) = ±0
fneg_N(±q) = ±q

fsqrt_N(z)

• If z is a NaN, then return an element of nans_N{z}.
• Else if z has a negative sign, then return an element of nans_N{z}.
• Else if z is positive infinity, then return positive infinity.
• Else if z is a zero, then return that zero.
• Else return the square root of z.

fsqrt_N(±nan(n)) = nans_N{±nan(n)}
fsqrt_N(−∞) = nans_N{−∞}
fsqrt_N(+∞) = +∞
fsqrt_N(±0) = ±0
fsqrt_N(−q) = nans_N{−q}
fsqrt_N(+q) = float_N(√q)

fceil_N(z)

• If z is a NaN, then return an element of nans_N{z}.
• Else if z is an infinity, then return z.
• Else if z is a zero, then return z.
• Else if z is smaller than 0 but greater than −1, then return negative zero.
• Else return the smallest integral value that is not smaller than z.

fceil_N(±nan(n)) = nans_N{±nan(n)}
fceil_N(±∞) = ±∞
fceil_N(±0) = ±0
fceil_N(−q) = 0 (if −1 < −q < 0)
fceil_N(±q) = float_N(i) (if ±q ≤ i < ±q + 1)

ffloor_N(z)

• If z is a NaN, then return an element of nans_N{z}.
• Else if z is an infinity, then return z.
• Else if \( z \) is a zero, then return \( z \).

• Else if \( z \) is greater than 0 but smaller than 1, then return positive zero.

• Else return the largest integral value that is not larger than \( z \).

\[
\begin{align*}
\text{floor}_N(\pm\text{nan}(n)) &= \text{nans}_N\{\pm\text{nan}(n)\} \\
\text{floor}_N(\pm\infty) &= \pm\infty \\
\text{floor}_N(\pm0) &= \pm0 \\
\text{floor}_N(\pm q) &= +0 \quad \text{(if } 0 < q < 1) \\
\text{floor}_N(\pm q) &= \text{float}_N(i) \quad \text{(if } \pm q - 1 < i \leq \pm q) \\
\end{align*}
\]

\text{ftrunc}_N(z)

• If \( z \) is a NaN, then return an element of \( \text{nans}_N\{z\} \).

• Else if \( z \) is an infinity, then return \( z \).

• Else if \( z \) is a zero, then return \( z \).

• Else if \( z \) is greater than 0 but smaller than 1, then return positive zero.

• Else if \( z \) is smaller than 0 but greater than \(-1\), then return negative zero.

• Else return the integral value with the same sign as \( z \) and the largest magnitude that is not larger than the magnitude of \( z \).

\[
\begin{align*}
\text{ftrunc}_N(\pm\text{nan}(n)) &= \text{nans}_N\{\pm\text{nan}(n)\} \\
\text{ftrunc}_N(\pm\infty) &= \pm\infty \\
\text{ftrunc}_N(\pm0) &= \pm0 \\
\text{ftrunc}_N(\pm q) &= +0 \quad \text{(if } 0 < q < 1) \\
\text{ftrunc}_N(\pm q) &= -0 \quad \text{(if } -1 < -q < 0) \\
\text{ftrunc}_N(\pm q) &= \text{float}_N(\pm i) \quad \text{(if } \pm q - 1 < i \leq +q) \\
\end{align*}
\]

\text{fnearest}_N(z)

• If \( z \) is a NaN, then return an element of \( \text{nans}_N\{z\} \).

• Else if \( z \) is an infinity, then return \( z \).

• Else if \( z \) is a zero, then return \( z \).

• Else if \( z \) is greater than 0 but smaller than or equal to 0.5, then return positive zero.

• Else if \( z \) is smaller than 0 but greater than or equal to \(-0.5\), then return negative zero.

• Else return the integral value that is nearest to \( z \); if two values are equally near, return the even one.

\[
\begin{align*}
\text{fnearest}_N(\pm\text{nan}(n)) &= \text{nans}_N\{\pm\text{nan}(n)\} \\
\text{fnearest}_N(\pm\infty) &= \pm\infty \\
\text{fnearest}_N(\pm0) &= \pm0 \\
\text{fnearest}_N(\pm q) &= +0 \quad \text{(if } 0 < q \leq 0.5) \\
\text{fnearest}_N(\pm q) &= -0 \quad \text{(if } -0.5 \leq -q < 0) \\
\text{fnearest}_N(\pm q) &= \text{float}_N(\pm i) \quad \text{(if } |i - q| < 0.5) \\
\text{fnearest}_N(\pm q) &= \text{float}_N(\pm i) \quad \text{(if } |i - q| = 0.5 \land i \text{ even}) \\
\end{align*}
\]

\text{feq}_N(z_1, z_2)

• If either \( z_1 \) or \( z_2 \) is a NaN, then return 0.

• Else if both \( z_1 \) and \( z_2 \) are zeroes, then return 1.

• Else if both \( z_1 \) and \( z_2 \) are the same value, then return 1.

• Else return 0.
\[
\begin{align*}
\text{feq}_N(\pm\text{nan}(n), z_2) &= 0 \\
\text{feq}_N(z_1, \pm\text{nan}(n)) &= 0 \\
\text{feq}_N(\pm0, \mp0) &= 1 \\
\text{feq}_N(z_1, z_2) &= \text{bool}(z_1 = z_2)
\end{align*}
\]

\text{fne}_N(z_1, z_2)

- If either \(z_1\) or \(z_2\) is a NaN, then return 1.
- Else if both \(z_1\) and \(z_2\) are zeroes, then return 0.
- Else if both \(z_1\) and \(z_2\) are the same value, then return 0.
- Else return 1.

\[
\begin{align*}
\text{fne}_N(\pm\text{nan}(n), z_2) &= 1 \\
\text{fne}_N(z_1, \pm\text{nan}(n)) &= 1 \\
\text{fne}_N(\pm0, \mp0) &= 0 \\
\text{fne}_N(z_1, z_2) &= \text{bool}(z_1 \neq z_2)
\end{align*}
\]

\text{flt}_N(z_1, z_2)

- If either \(z_1\) or \(z_2\) is a NaN, then return 0.
- Else if \(z_1\) and \(z_2\) are the same value, then return 0.
- Else if \(z_1\) is positive infinity, then return 0.
- Else if \(z_1\) is negative infinity, then return 1.
- Else if \(z_2\) is positive infinity, then return 1.
- Else if \(z_2\) is negative infinity, then return 0.
- Else if both \(z_1\) and \(z_2\) are zeroes, then return 0.
- Else if \(z_1\) is smaller than \(z_2\), then return 1.
- Else return 0.

\[
\begin{align*}
\text{flt}_N(\pm\text{nan}(n), z_2) &= 0 \\
\text{flt}_N(z_1, \pm\text{nan}(n)) &= 0 \\
\text{flt}_N(z, z) &= 0 \\
\text{flt}_N(+\infty, z_2) &= 0 \\
\text{flt}_N(-\infty, z_2) &= 1 \\
\text{flt}_N(z_1, +\infty) &= 1 \\
\text{flt}_N(z_1, -\infty) &= 0 \\
\text{flt}_N(\pm0, \mp0) &= 0 \\
\text{flt}_N(z_1, z_2) &= \text{bool}(z_1 < z_2)
\end{align*}
\]

\text{fgt}_N(z_1, z_2)

- If either \(z_1\) or \(z_2\) is a NaN, then return 0.
- Else if \(z_1\) and \(z_2\) are the same value, then return 0.
- Else if \(z_1\) is positive infinity, then return 1.
- Else if \(z_1\) is negative infinity, then return 0.
- Else if \(z_2\) is positive infinity, then return 0.
- Else if \(z_2\) is negative infinity, then return 1.
- Else if both \(z_1\) and \(z_2\) are zeroes, then return 0.
- Else if \(z_1\) is larger than \(z_2\), then return 1.
• Else return 0.

\[
\text{fgt}_N(\pm \text{nan}(n), z_2) = 0 \\
\text{fgt}_N(z_1, \pm \text{nan}(n)) = 0 \\
\text{fgt}_N(z, z) = 0 \\
\text{fgt}_N(+\infty, z_2) = 1 \\
\text{fgt}_N(-\infty, z_2) = 0 \\
\text{fgt}_N(z_1, +\infty) = 0 \\
\text{fgt}_N(z_1, -\infty) = 1 \\
\text{fgt}_N(\pm 0, \mp 0) = 0 \\
\text{fgt}_N(z_1, z_2) = \text{bool}(z_1 > z_2)
\]

\[
\text{fle}_N(z_1, z_2)
\]

• If either \(z_1\) or \(z_2\) is a NaN, then return 0.

• Else if \(z_1\) and \(z_2\) are the same value, then return 1.

• Else if \(z_1\) is positive infinity, then return 0.

• Else if \(z_1\) is negative infinity, then return 1.

• Else if \(z_2\) is positive infinity, then return 1.

• Else if \(z_2\) is negative infinity, then return 0.

• Else if both \(z_1\) and \(z_2\) are zeroes, then return 1.

• Else if \(z_1\) is smaller than or equal to \(z_2\), then return 1.

• Else return 0.

\[
\text{fle}_N(\pm \text{nan}(n), z_2) = 0 \\
\text{fle}_N(z_1, \pm \text{nan}(n)) = 0 \\
\text{fle}_N(z, z) = 1 \\
\text{fle}_N(+\infty, z_2) = 0 \\
\text{fle}_N(-\infty, z_2) = 1 \\
\text{fle}_N(z_1, +\infty) = 1 \\
\text{fle}_N(z_1, -\infty) = 0 \\
\text{fle}_N(\pm 0, \mp 0) = 1 \\
\text{fle}_N(z_1, z_2) = \text{bool}(z_1 \leq z_2)
\]

\[
\text{fge}_N(z_1, z_2)
\]

• If either \(z_1\) or \(z_2\) is a NaN, then return 0.

• Else if \(z_1\) and \(z_2\) are the same value, then return 1.

• Else if \(z_1\) is positive infinity, then return 1.

• Else if \(z_1\) is negative infinity, then return 0.

• Else if \(z_2\) is positive infinity, then return 0.

• Else if \(z_2\) is negative infinity, then return 1.

• Else if both \(z_1\) and \(z_2\) are zeroes, then return 1.

• Else if \(z_1\) is smaller than or equal to \(z_2\), then return 1.

• Else return 0.
\[ \text{fge}_N(\pm \text{nan}(n), z_2) = 0 \]
\[ \text{fge}_N(z_1, \pm \text{nan}(n)) = 0 \]
\[ \text{fge}_N(z, z) = 1 \]
\[ \text{fge}_N(+\infty, z_2) = 1 \]
\[ \text{fge}_N(-\infty, z_2) = 0 \]
\[ \text{fge}_N(z_1, +\infty) = 0 \]
\[ \text{fge}_N(z_1, -\infty) = 1 \]
\[ \text{fge}_N(\pm 0, \mp 0) = 1 \]
\[ \text{fge}_N(z_1, z_2) = \text{bool}(z_1 \geq z_2) \]

### 4.3.4 Conversions

**extend\_u_{M,N}(i)**

- Return \( i \).

\[
\text{extend\_u}_{M,N}(i) = i
\]

**Note:** In the abstract syntax, unsigned extension just reinterprets the same value.

**extend\_s_{M,N}(i)**

- Let \( j \) be the *signed interpretation* of \( i \) of size \( M \).
- Return the two’s complement of \( j \) relative to size \( N \).

\[
\text{extend\_s}_{M,N}(i) = \text{signed}^{-1}_N(\text{signed}_M(i))
\]

**wrap_{M,N}(i)**

- Return \( i \) modulo \( 2^N \).

\[
\text{wrap}_{M,N}(i) = i \mod 2^N
\]

**trunc\_u_{M,N}(z)**

- If \( z \) is a NaN, then the result is undefined.
- Else if \( z \) is an infinity, then the result is undefined.
- Else if \( z \) is a number and \( \text{trunc}(z) \) is a value within range of the target type, then return that value.
- Else the result is undefined.

\[
\text{trunc\_u}_{M,N}(\pm \text{nan}(n)) = \{\}
\]
\[
\text{trunc\_u}_{M,N}(\pm \infty) = \{\}
\]
\[
\text{trunc\_u}_{M,N}(\pm q) = \text{trunc}(\pm q) \quad (\text{if } -1 < \text{trunc}(\pm q) < 2^N)
\]
\[
\text{trunc\_u}_{M,N}(\pm q) = \{\} \quad (\text{otherwise})
\]

**Note:** This operator is *partial*. It is not defined for NaNs, infinities, or values for which the result is out of range.
\texttt{trunc}_{M,N}(z)

- If \( z \) is a NaN, then the result is undefined.
- Else if \( z \) is an infinity, then the result is undefined.
- If \( z \) is a number and \( \text{trunc}(z) \) is a value within range of the target type, then return that value.
- Else the result is undefined.

\[
\begin{align*}
\text{trunc}_{M,N}(\pm\text{nan}(n)) & = \{} \\
\text{trunc}_{M,N}(\pm\infty) & = \{} \\
\text{trunc}_{M,N}(\pm q) & = \text{trunc}(\pm q) & (\text{if } -2^{N-1} - 1 < \text{trunc}(\pm q) < 2^{N-1}) \\
\text{trunc}_{M,N}(\pm q) & = \{} & (\text{otherwise})
\end{align*}
\]

\textbf{Note:} This operator is \textit{partial}. It is not defined for NaNs, infinities, or values for which the result is out of range.

\texttt{promote}_{M,N}(z)

- If \( z \) is a \textit{canonical NaN}, then return an element of \( \text{nans}_N\{\} \) (i.e., a canonical NaN of size \( N \)).
- Else if \( z \) is a NaN, then return an element of \( \text{nans}_N\{\pm\text{nan}(1)\} \) (i.e., any NaN of size \( N \)).
- Else, return \( z \).

\[
\begin{align*}
\text{promote}_{M,N}(\pm\text{nan}(n)) & = \text{nans}_N\{\} & (\text{if } n = \text{canon}_N) \\
\text{promote}_{M,N}(\pm\text{nan}(n)) & = \text{nans}_N\{\pm\text{nan}(1)\} & (\text{otherwise}) \\
\text{promote}_{M,N}(z) & = z
\end{align*}
\]

\texttt{demote}_{M,N}(z)

- If \( z \) is a \textit{canonical NaN}, then return an element of \( \text{nans}_N\{\} \) (i.e., a canonical NaN of size \( N \)).
- Else if \( z \) is a NaN, then return an element of \( \text{nans}_N\{\pm\text{nan}(1)\} \) (i.e., any NaN of size \( N \)).
- Else if \( z \) is an infinity, then return that infinity.
- Else if \( z \) is a zero, then return that zero.
- Else, return \( \text{float}_N(z) \).

\[
\begin{align*}
\text{demote}_{M,N}(\pm\text{nan}(n)) & = \text{nans}_N\{\} & (\text{if } n = \text{canon}_N) \\
\text{demote}_{M,N}(\pm\text{nan}(n)) & = \text{nans}_N\{\pm\text{nan}(1)\} & (\text{otherwise}) \\
\text{demote}_{M,N}(\pm\infty) & = \pm\infty \\
\text{demote}_{M,N}(\pm 0) & = \pm 0 \\
\text{demote}_{M,N}(\pm q) & = \text{float}_N(\pm q)
\end{align*}
\]

\texttt{convert_{uM,N}(i)}

- Return \( \text{float}_N(i) \).

\[
\text{convert_{uM,N}(i)} = \text{float}_N(i)
\]

\texttt{convert_{sM,N}(i)}

- Let \( j \) be the \textit{signed interpretation} of \( i \).
- Return \( \text{float}_N(j) \).

\[
\text{convert_{sM,N}(i)} = \text{float}_N(\text{signed}_M(i))
\]
reinterpret\(_{t_1, t_2}(c)\)

- Let \(d^*\) be the bit sequence \(\text{bits}_{t_1}(c)\).
- Return the constant \(c'\) for which \(\text{bits}_{t_2}(c') = d^*\).

\[
\text{reinterpret}_{t_1, t_2}(c) = \text{bits}_{t_2}^{-1}(\text{bits}_{t_1}(c))
\]

### 4.4 Instructions

WebAssembly computation is performed by executing individual instructions.

#### 4.4.1 Numeric Instructions

Numeric instructions are defined in terms of the basic numeric operators. The mapping of numeric instructions to their underlying operators is expressed by the following definition:

\[
op_i N(n_1, \ldots, n_k) = \text{iop}_N(n_1, \ldots, n_k) \\
op_f N(z_1, \ldots, z_k) = \text{fop}_N(z_1, \ldots, z_k)
\]

And for conversion operators:

\[
\text{cvtop}_{t_1, t_2}(c) = \text{cvtop}_{|t_1|, |t_2|}(c)
\]

Where the underlying operators are partial, the corresponding instruction will trap when the result is not defined. Where the underlying operators are non-deterministic, because they may return one of multiple possible NaN values, so are the corresponding instructions.

**t.const c**

1. Push the value \(t.\text{const } c\) to the stack.

**Note:** No formal reduction rule is required for this instruction, since \(\text{const}\) instructions coincide with values.

**t.unop**

1. Assert: due to validation, a value of value type \(t\) is on the top of the stack.
2. Pop the value \(t.\text{const } c_1\) from the stack.
3. If \(\text{unop}_t(c_1)\) is defined, then:
   (a) Let \(c\) be a possible result of computing \(\text{unop}_t(c_1)\).
   (b) Push the value \(t.\text{const } c\) to the stack.
4. Else:
   (a) Trap.

\[
\begin{align*}
(t.\text{const } c_1) \text{ t.unop} & \leftrightarrow (t.\text{const } c) & \text{(if } c \in \text{unop}_t(c_1)\text{)} \\
(t.\text{const } c_1) \text{ t.unop} & \leftrightarrow \text{trap} & \text{(if } \text{unop}_t(c_1) = \{\}\text{)}
\end{align*}
\]
**t.binop**

1. Assert: due to validation, two values of value type $t$ are on the top of the stack.
2. Pop the value $t\.const\ const\ c_2$ from the stack.
3. Pop the value $t\.const\ c_1$ from the stack.
4. If $\text{binop}_t(c_1, c_2)$ is defined, then:
   (a) Let $c$ be a possible result of computing $\text{binop}_t(c_1, c_2)$.
   (b) Push the value $t\.const\ c$ to the stack.
5. Else:
   (a) Trap.

\[
\begin{align*}
(t\.const\ c_1) (t\.const\ c_2) & \text{ t.binop} \quad \leftrightarrow \quad (t\.const\ c) \quad \text{ (if } c \in \text{ binop}_t(c_1, c_2)) \\
(t\.const\ c_1) (t\.const\ c_2) & \text{ t.binop} \quad \leftrightarrow \quad \text{ trap} \quad \text{ (if } \text{ binop}_t(c_1, c_2) = \emptyset) \\
\end{align*}
\]

**t.testop**

1. Assert: due to validation, a value of value type $t$ is on the top of the stack.
2. Pop the value $t\.const\ c_1$ from the stack.
3. Let $c$ be the result of computing $\text{testop}_t(c_1)$.
4. Push the value $\text{i32}.const\ c$ to the stack.

\[
(t\.const\ c_1) \text{ t.testop} \quad \leftrightarrow \quad (\text{i32}.const\ c) \quad \text{ (if } c = \text{ testop}_t(c_1))
\]

**t.relop**

1. Assert: due to validation, two values of value type $t$ are on the top of the stack.
2. Pop the value $t\.const\ c_2$ from the stack.
3. Pop the value $t\.const\ c_1$ from the stack.
4. Let $c$ be the result of computing $\text{relop}_t(c_1, c_2)$.
5. Push the value $\text{i32}.const\ c$ to the stack.

\[
(t\.const\ c_1) (t\.const\ c_2) \text{ t.relop} \quad \leftrightarrow \quad (\text{i32}.const\ c) \quad \text{ (if } c = \text{ relop}_t(c_1, c_2))
\]

**t2.cvtop/t1**

1. Assert: due to validation, a value of value type $t_1$ is on the top of the stack.
2. Pop the value $t_1\.const\ c_1$ from the stack.
3. If $\text{cvtop}_{t_1, t_2}(c_1)$ is defined:
   (a) Let $c_2$ be a possible result of computing $\text{cvtop}_{t_1, t_2}(c_1)$.
   (b) Push the value $t_2\.const\ c_2$ to the stack.
4. Else:
   (a) Trap.

\[
\begin{align*}
(t_1\.const\ c_1) \text{ t2.cvtop}/t_1 & \quad \leftrightarrow \quad (t_2\.const\ c_2) \quad \text{ (if } c_2 \in \text{ cvtop}_{t_1, t_2}(c_1)) \\
(t_1\.const\ c_1) \text{ t2.cvtop}/t_1 & \quad \leftrightarrow \quad \text{ trap} \quad \text{ (if } \text{ cvtop}_{t_1, t_2}(c_1) = \emptyset) \\
\end{align*}
\]
4.4.2 Parametric Instructions

**drop**

1. Assert: due to *validation*, a value is on the top of the stack.
2. Pop the value \( val \) from the stack.

\[
\text{val drop } \leftrightarrow \epsilon
\]

**select**

1. Assert: due to *validation*, a value of value type `i32` is on the top of the stack.
2. Pop the value `i32.const c` from the stack.
3. Assert: due to *validation*, two more values (of the same value type) are on the top of the stack.
4. Pop the value `val2` from the stack.
5. Pop the value `val1` from the stack.
6. If `c` is not 0, then:
   (a) Push the value `val1` back to the stack.
7. Else:
   (a) Push the value `val2` back to the stack.

\[
\begin{align*}
\text{val} \text{ val}_1 \text{ (i32.const c) select } & \quad \rightarrow \quad \text{val}_1 & \quad (\text{if } c \neq 0) \\
\text{val} \text{ val}_1 \text{ (i32.const c) select } & \quad \rightarrow \quad \text{val}_2 & \quad (\text{if } c = 0)
\end{align*}
\]

4.4.3 Variable Instructions

**get_local x**

1. Let \( F \) be the *current frame*.
2. Assert: due to *validation*, \( F.\text{locals}[x] \) exists.
3. Let \( val \) be the value \( F.\text{locals}[x] \).
4. Push the value \( val \) to the stack.

\[
F; (\text{get}_\text{local} \, x) \quad \leftrightarrow \quad F; \text{val} & \quad (\text{if } F.\text{locals}[x] = \text{val})
\]

**set_local x**

1. Let \( F \) be the *current frame*.
2. Assert: due to *validation*, \( F.\text{locals}[x] \) exists.
3. Assert: due to *validation*, a value is on the top of the stack.
4. Pop the value \( val \) from the stack.
5. Replace \( F.\text{locals}[x] \) with the value \( val \).

\[
F; \text{val} \ (\text{set}_\text{local} \, x) \quad \leftrightarrow \quad F'; \epsilon & \quad (\text{if } F' = F \text{ with locals}[x] = \text{val})
\]
WebAssembly Specification, Release 1.0

tee\_local \(x\)

1. Assert: due to validation, a value is on the top of the stack.
2. Pop the value val from the stack.
3. Push the value val to the stack.
4. Push the value val to the stack.
5. Execute the instruction (set\_local \(x\)).

\[
\text{val (tee\_local } x) \leftrightarrow \text{val (set\_local } x)
\]

get\_global \(x\)

1. Let \(F\) be the current frame.
2. Assert: due to validation, \(F.\text{module.globaladdrs}[x]\) exists.
3. Let \(a\) be the global address \(F.\text{module.globaladdrs}[x]\).
4. Assert: due to validation, \(S.\text{globals}[a]\) exists.
5. Let \(glob\) be the global instance \(S.\text{globals}[a]\).
6. Let \(val\) be the value \(glob.\text{value}\).
7. Push the value \(val\) to the stack.

\[
S; F; (\text{get\_global } x) \leftrightarrow S; F; val
\text{ (if } S.\text{globals}[F.\text{module.globaladdrs}[x]].\text{value} = val)\]

set\_global \(x\)

1. Let \(F\) be the current frame.
2. Assert: due to validation, \(F.\text{module.globaladdrs}[x]\) exists.
3. Let \(a\) be the global address \(F.\text{module.globaladdrs}[x]\).
4. Assert: due to validation, \(S.\text{globals}[a]\) exists.
5. Let \(glob\) be the global instance \(S.\text{globals}[a]\).
6. Assert: due to validation, a value is on the top of the stack.
7. Pop the value \(val\) from the stack.
8. Replace \(glob.\text{value}\) with the value \(val\).

\[
S; F; val (\text{set\_global } x) \leftrightarrow S'; F; \epsilon
\text{ (if } S' = S \text{ with } S.\text{globals}[F.\text{module.globaladdrs}[x]].\text{value} = val)\]

Note: Validation ensures that the global is, in fact, marked as mutable.

4.4.4 Memory Instructions

Note: The alignment \(\text{memory}\_\text{align}\) in load and store instructions does not affect the semantics. It is an indication that the offset \(ea\) at which the memory is accessed is intended to satisfy the property \(ea \mod 2^{\text{memory}\_\text{align}} = 0\). A WebAssembly implementation can use this hint to optimize for the intended use. Unaligned access violating that
property is still allowed and must succeed regardless of the annotation. However, it may be substantially slower on some hardware.

### 4.4. Instructions

#### t.load memarg and t.loadN_sx memarg

1. Let $F$ be the current frame.
2. Assert: due to validation, $F$.module.memaddrs[0] exists.
3. Let $a$ be the memory address $F$.module.memaddrs[0].
5. Let $mem$ be the memory instance $S$.mems[$a$].
6. Assert: due to validation, a value of value type i32 is on the top of the stack.
7. Pop the value i32 $i$ from the stack.
8. Let $ea$ be the integer $i + memarg.offset$.
9. If $N$ is not part of the instruction, then:
   (a) Let $N$ be the bit width $|t|$ of value type $t$.
10. If $ea + N/8$ is larger than the length of $mem.data$, then:
    (a) Trap.
11. Let $b^*$ be the byte sequence $mem.data[ea : N/8]$.
12. If $N$ and $sx$ are part of the instruction, then:
    (a) Let $n$ be the integer for which $\text{bytes}_{iN}(n) = b^*$.
    (b) Let $c$ be the result of computing $\text{extend}_{sxN,iN}(n)$.
13. Else:
    (a) Let $c$ be the constant for which $\text{bytes}_{iN}(c) = b^*$.
14. Push the value t.const $c$ to the stack.

#### t.store memarg and t.storeN memarg

1. Let $F$ be the current frame.
2. Assert: due to validation, $F$.module.memaddrs[0] exists.
3. Let $a$ be the memory address $F$.module.memaddrs[0].
5. Let $mem$ be the memory instance $S$.mems[$a$].
6. Assert: due to validation, a value of value type \( t \) is on the top of the stack.

7. Pop the value \( t.\text{const} \ c \) from the stack.

8. Assert: due to validation, a value of value type \( \text{i32} \) is on the top of the stack.

9. Pop the value \( \text{i32}.\text{const} \ i \) from the stack.

10. Let \( ea \) be the integer \( i + \text{memory.offset} \).

11. If \( N \) is not part of the instruction, then:
   
   (a) Let \( N \) be the bit width \( |t| \) of value type \( t \).

12. If \( ea + N/8 \) is larger than the length of \( \text{mem.data} \), then:
   
   (a) Trap.

13. If \( N \) is part of the instruction, then:
   
   (a) Let \( n \) be the result of computing \( \text{wrap}_{|t|,N}(c) \).
   
   (b) Let \( b^* \) be the byte sequence \( \text{bytes}_{i,N}(n) \).

14. Else:
   
   (a) Replace the bytes \( \text{mem.data}[ea : N/8] \) with \( b^* \).

\[
\begin{align*}
S; F; (\text{32.const} \ i) \ (t.\text{const} \ c) \ (t.\text{store} \ \text{memory}) & \quad \rightarrow \quad S'; F; c \\
& \quad \text{(if } ea = i + \text{memory.offset} \\
& \land \ ea + \lfloor |t|/8 \rfloor \leq |S.\text{mems}[F.\text{module}.\text{memaddrs}[0]].\text{data}|
\land \ S' = S \text{ with } \text{mems}[F.\text{module}.\text{memaddrs}[0]].\text{data}[ea : \lfloor |t|/8 \rfloor] = \text{bytes}_{i,N}(c) \\
S; F; (\text{32.const} \ i) \ (t.\text{const} \ c) \ (t.\text{store}N \ \text{memory}) & \quad \rightarrow \quad S'; F; c \\
& \quad \text{(if } ea = i + \text{memory.offset} \\
& \land \ ea + N/8 \leq |S.\text{mems}[F.\text{module}.\text{memaddrs}[0]].\text{data}| \\
& \land \ S' = S \text{ with } \text{mems}[F.\text{module}.\text{memaddrs}[0]].\text{data}[ea : N/8] = \text{bytes}_{i,N}(\text{wrap}_{|t|,N}(c)) \\
S; F; (\text{32.const} \ k) \ (t.\text{const} \ c) \ (t.\text{store}N^7 \ \text{memory}) & \quad \rightarrow \quad S'; F; \text{trap} \
& \quad \text{(otherwise)}
\end{align*}
\]

\section*{memory.size}

1. Let \( F \) be the current frame.

2. Assert: due to validation, \( F.\text{module}.\text{memaddrs}[0] \) exists.

3. Let \( a \) be the memory address \( F.\text{module}.\text{memaddrs}[0] \).

4. Assert: due to validation, \( S.\text{mems}[a] \) exists.

5. Let \( \text{mem} \) be the memory instance \( S.\text{mems}[a] \).

6. Let \( sz \) be the length of \( \text{mem.data} \) divided by the page size.

7. Push the value \( \text{i32}.\text{const} \ sz \) to the stack.

\[
\begin{align*}
S; F; \text{memory.size} & \quad \rightarrow \quad S; F; (\text{i32}.\text{const} \ sz) \\
& \quad \text{(if } |S.\text{mems}[F.\text{module}.\text{memaddrs}[0]].\text{data}| = sz \cdot 64 \text{ Ki})
\end{align*}
\]

\section*{memory.grow}

1. Let \( F \) be the current frame.

2. Assert: due to validation, \( F.\text{module}.\text{memaddrs}[0] \) exists.

3. Let \( a \) be the memory address \( F.\text{module}.\text{memaddrs}[0] \).
4. Assert: due to validation, \( S.mems[a] \) exists.

5. Let \( \text{mem} \) be the memory instance \( S.mems[a] \).

6. Let \( sz \) be the length of \( S.mems[a] \) divided by the page size.

7. Assert: due to validation, a value of value type \( \text{i32} \) is on the top of the stack.

8. Pop the value \( \text{i32}.\text{const} \ n \) from the stack.

9. Either, try growing \( \text{mem} \) by \( n \) pages:
   
   (a) If it succeeds, push the value \( \text{i32}.\text{const} \ sz \) to the stack.
   
   (b) Else, push the value \( \text{i32}.\text{const} (-1) \) to the stack.

10. Or, push the value \( \text{i32}.\text{const} (-1) \) to the stack.

\[
S; F; (\text{i32}.\text{const} \ n) \text{ memory.grow } \leftrightarrow \ S'; F; (\text{i32}.\text{const} \ sz)
\]

   (if \( F\text{.module.memaddrs}[0] = a \)
   
   \( \land \ sz = \lfloor S.mems[a].data \rfloor / 64 \text{ Ki} \)
   
   \( \land \ S' = S \text{ with } \text{mems}[a] = \text{growmem}(S.mems[a], n) \)

\[
S; F; (\text{i32}.\text{const} \ n) \text{ memory.grow } \leftrightarrow \ S; F; (\text{i32}.\text{const} (-1))
\]

**Note:** The \( \text{memory.grow} \) instruction is non-deterministic. It may either succeed, returning the old memory size \( sz \), or fail, returning \(-1\). Failure must occur if the referenced memory instance has a maximum size defined that would be exceeded. However, failure can occur in other cases as well. In practice, the choice depends on the resources available to the embedder.

### 4.4.5 Control Instructions

**nop**

1. Do nothing.

\[
\text{nop} \leftrightarrow \epsilon
\]

**unreachable**

1. Trap.

\[
\text{unreachable} \leftrightarrow \text{trap}
\]

**block \([t^7]\) instr* end**

1. Let \( n \) be the arity \( |t^7| \) of the result type \( t^7 \).

2. Let \( L \) be the label whose arity is \( n \) and whose continuation is the end of the block.

3. *Enter* the block \( \text{instr}^* \) with label \( L \).

\[
\text{block \([t^n]\) instr* end } \leftrightarrow \text{label}_n \{\epsilon\} \text{ instr* end}
\]
loop \([t] \) instr\(^*\) end

1. Let \(L\) be the label whose arity is 0 and whose continuation is the start of the loop.
2. \(\text{Enter}\) the block instr\(^*\) with label \(L\).

\[
\text{loop } [t] \text{ instr}^* \text{ end} \leftrightarrow \text{label}_0\{\text{loop } [t] \text{ instr}^* \text{ end} \} \text{ instr}\(^*\) end
\]

if \([t] \) instr\(^*_1\) else instr\(^*_2\) end

1. Assert: due to validation, a value of value type i32 is on the top of the stack.
2. Pop the value i32.const \(c\) from the stack.
3. Let \(n\) be the arity \(|t|\) of the result type \(t\).
4. Let \(L\) be the label whose arity is \(n\) and whose continuation is the end of the if instruction.
5. If \(c\) is non-zero, then:
   (a) \(\text{Enter}\) the block instr\(^*_1\) with label \(L\).
6. Else:
   (a) \(\text{Enter}\) the block instr\(^*_2\) with label \(L\).

\[
(i32.\text{const } c) \text{ if } [t^n] \text{ instr}^*_1 \text{ else instr}^*_2 \text{ end} \leftrightarrow \text{label}_n\{c\} \text{ instr}^*_1 \text{ end} \quad \text{(if } c \neq 0)\\
(i32.\text{const } c) \text{ if } [t^n] \text{ instr}^*_1 \text{ else instr}^*_2 \text{ end} \leftrightarrow \text{label}_n\{c\} \text{ instr}^*_2 \text{ end} \quad \text{(if } c = 0)\]

br \(l\)

1. Assert: due to validation, the stack contains at least \(l + 1\) labels.
2. Let \(L\) be the \(l\)-th label appearing on the stack, starting from the top and counting from zero.
3. Let \(n\) be the arity of \(L\).
4. Assert: due to validation, there are at least \(n\) values on the top of the stack.
5. Pop the values \(\text{val}^n\) from the stack.
6. Repeat \(l + 1\) times:
   (a) While the top of the stack is a value, do:
      i. Pop the value from the stack.
   (b) Assert: due to validation, the top of the stack now is a label.
   (c) Pop the label from the stack.
7. Push the values \(\text{val}^n\) to the stack.
8. Jump to the continuation of \(L\).

\[
\text{label}_n\{\text{instr}^*\} \ B^l[\text{val}^n \ (\text{br } l)] \text{ end} \leftrightarrow \text{val}^n \ \text{instr}^*
\]

br if \(l\)

1. Assert: due to validation, a value of value type i32 is on the top of the stack.
2. Pop the value i32.const \(c\) from the stack.
3. If \(c\) is non-zero, then:
   (a) \(\text{Execute}\) the instruction (br \(l\)).
4. Else:
   (a) Do nothing.

\[
\begin{align*}
(i32.const\ c)\ (br\ if\ l) & \rightarrow\ (br\ l) \quad (if\ c \neq 0) \\
(i32.const\ c)\ (br\ if\ l) & \rightarrow\ \epsilon \quad (if\ c = 0)
\end{align*}
\]

**br_table** \(l^*\ l_N\)**

1. Assert: due to validation, a value of value type \(i32\) is on the top of the stack.
2. Pop the value \(i32.const\ i\) from the stack.
3. If \(i\) is smaller than the length of \(l^*\), then:
   (a) Let \(l_i\) be the label \(l^*[i]\).
   (b) Execute the instruction \((br\ l_i)\).
4. Else:
   (a) Execute the instruction \((br\ l_N)\).

\[
\begin{align*}
(i32.const\ i)\ (br\_table\ l^*\ l_N) & \rightarrow\ (br\ l_i) \quad (if\ l^*[i] = l_i) \\
(i32.const\ i)\ (br\_table\ l^*\ l_N) & \rightarrow\ (br\ l_N) \quad (if\ |l^*| \leq i)
\end{align*}
\]

**return**

1. Let \(F\) be the current frame.
2. Let \(n\) be the arity of \(F\).
3. Assert: due to validation, there are at least \(n\) values on the top of the stack.
4. Pop the results \(val^n\) from the stack.
5. Assert: due to validation, the stack contains at least one frame.
6. While the top of the stack is not a frame, do:
   (a) Pop the top element from the stack.
7. Assert: the top of the stack is the frame \(F\).
8. Pop the frame from the stack.
9. Push \(val^n\) to the stack.
10. Jump to the instruction after the original call that pushed the frame.

\[
\text{frame}_n\{F\}\ B^k[\text{val}^n\ \text{return}]\ \text{end} \leftrightarrow\ \text{val}^n
\]

**call** \(x\)

1. Let \(F\) be the current frame.
2. Assert: due to validation, \(F.\text{module}.\text{funcaddr}[x]\) exists.
3. Let \(a\) be the function address \(F.\text{module}.\text{funcaddr}[x]\).
4. Invoke the function instance at address \(a\).

\[
F;\ (\text{call}\ x) \leftrightarrow F;\ (\text{invoke}\ a) \quad (if\ F.\text{module}.\text{funcaddr}[x] = a)
\]
4.4.6 Blocks

The following auxiliary rules define the semantics of executing an instruction sequence that forms a block.

**Entering instr** with label \( L \)

1. Push \( L \) to the stack.
2. Jump to the start of the instruction sequence \( instr^* \).

**Note:** No formal reduction rule is needed for entering an instruction sequence, because the label \( L \) is embedded in the administrative instruction that structured control instructions reduce to directly.
Exiting \emph{instr} with label $L$

When the end of a block is reached without a jump or trap aborting it, then the following steps are performed.

1. Let $m$ be the number of values on the top of the stack.
2. Pop the values $val^m$ from the stack.
3. Assert: due to validation, the label $L$ is now on the top of the stack.
4. Pop the label from the stack.
5. Push $val^m$ back to the stack.
6. Jump to the position after the end of the structured control instruction associated with the label $L$.

\[
\text{label}_n \{\text{instr}*\} \text{ val}^m \text{ end} \leftarrow \text{val}^m
\]

\textbf{Note:} This semantics also applies to the instruction sequence contained in a loop instruction. Therefore, execution of a loop falls off the end, unless a backwards branch is performed explicitly.

### 4.4.7 Function Calls

The following auxiliary rules define the semantics of invoking a \emph{function instance} through one of the \emph{call instructions} and returning from it.

\textbf{Invocation of function address $a$}

1. Assert: due to validation, $S.\text{funcs}[a]$ exists.
2. Let $f$ be the \emph{function instance}, $S.\text{funcs}[a]$.
3. Let $[t^1_1] \rightarrow [t^n_2]$ be the \emph{function type} $f.\text{type}$.
4. Assert: due to validation, $m \leq 1$.
5. Let $t^*$ be the list of \emph{value types} $f.\text{code.locals}$.
6. Let $\text{instr}* \text{ end}$ be the \emph{expression} $f.\text{code.body}$.
7. Assert: due to validation, $n$ values are on the top of the stack.
8. Pop the values $val^n$ from the stack.
9. Let $val^*_0$ be the list of zero values of types $t^*$.
10. Let $F$ be the \emph{frame} \{module $f.\text{module}$, locals $val^n$ $val^*_0$\}.
11. Push the activation of $F$ with arity $m$ to the stack.
12. \textbf{Execute} the instruction block $[t^n_2] \text{ instr}* \text{ end}$.

\[
S; val^n (\text{invoke} \ a) \rightarrow S; \text{frame}_m \{F\} \text{ block } [t^n_2] \text{ instr}* \text{ end end}
\]

(if $S.\text{funcs}[a] = f$ \\
$\land f.\text{type} = [t^1_1] \rightarrow [t^n_2]$ \\
$\land m \leq 1$ \\
$\land f.\text{code} = \{\text{type } x, \text{locals } t^k, \text{body } \text{instr}* \text{ end}\}$ \\
$\land F = \{\text{module } f.\text{module}, \text{locals } val^n (t.\text{const} 0)^k\}$

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Returning from a function

When the end of a function is reached without a jump (i.e., return) or trap aborting it, then the following steps are performed.

1. Let $F$ be the current frame.
2. Let $n$ be the arity of the activation of $F$.
3. Assert: due to validation, there are $n$ values on the top of the stack.
4. Pop the results $val^n$ from the stack.
5. Assert: due to validation, the frame $F$ is now on the top of the stack.
6. Pop the frame from the stack.
7. Push $val^n$ back to the stack.
8. Jump to the instruction after the original call.

\[
\text{frame}_n \{F\} \text{ val}^n \text{ end} \leftrightarrow \text{ val}^n
\]

Host Functions

Invoking a host function has non-deterministic behavior. It may either terminate with a trap or return regularly. However, in the latter case, it must consume and produce the right number and types of WebAssembly values on the stack, according to its function type.

A host function may also modify the store. However, all store modifications must result in an extension of the original store, i.e., they must only modify mutable contents and must not have instances removed. Furthermore, the resulting store must be valid, i.e., all data and code in it is well-typed.

\[
S; \text{val}^n (\text{invoke } a) \leftrightarrow S'; \text{result} \\
(\text{if } S.\text{funcs}[a] = \{\text{type } [t^n_1] \rightarrow [t^n_m], \text{hostcode } hf\}) \\
\land (S'; \text{result}) \in hf(S; \text{val}^n))
\]

\[
S; \text{val}^n (\text{invoke } a) \leftrightarrow S; \text{val}^n (\text{invoke } a) \\
(\text{if } S.\text{funcs}[a] = \{\text{type } [t^n_1] \rightarrow [t^n_m], \text{hostcode } hf\}) \\
\land \bot \in hf(S; \text{val}^n))
\]

Here, $hf(S; \text{val}^n)$ denotes the implementation-defined execution of host function $hf$ in current store $S$ with arguments $\text{val}^n$. It yields a set of possible outcomes, where each element is either a pair of a modified store $S'$ and a result or the special value $\bot$ indicating divergence. A host function is non-deterministic if there is at least one argument for which the set of outcomes is not singular.

For a WebAssembly implementation to be sound in the presence of host functions, every host function instance must be valid, which means that it adheres to suitable pre- and post-conditions: under a valid store $S$, and given arguments $\text{val}^n$ matching the ascribed parameter types $t^n_1$, executing the host function must yield a non-empty set of possible outcomes each of which is either divergence or consists of a valid store $S'$ that is an extension of $S$ and a result matching the ascribed return types $t^n_m$. All these notions are made precise in the Appendix.

Note: A host function can call back into WebAssembly by invoking a function exported from a module. However, the effects of any such call are subsumed by the non-deterministic behavior allowed for the host function.

4.4.8 Expressions

An expression is evaluated relative to a current frame pointing to its containing module instance.

1. Jump to the start of the instruction sequence $\text{instr}^*$ of the expression.
2. Execute the instruction sequence.
3. Assert: due to validation, the top of the stack contains a value.
4. Pop the value val from the stack.

The value val is the result of the evaluation.

\[
S; F; instr^* \rightarrow S'; F'; instr'^*
\]

Note: Evaluation iterates this reduction rule until reaching a value. Expressions constituting function bodies are executed during function invocation.

4.5 Modules

For modules, the execution semantics primarily defines instantiation, which allocates instances for a module and its contained definitions, initializes tables and memories from contained element and data segments, and invokes the start function if present. It also includes invocation of exported functions.

Instantiation depends on a number of auxiliary notions for type-checking imports and allocating instances.

4.5.1 External Typing

For the purpose of checking external values against imports, such values are classified by external types. The following auxiliary typing rules specify this typing relation relative to a store S in which the referenced instances live.

func a

- The store entry S.funcs[a] must be a function instance \{type functype, \ldots\}.
- Then func a is valid with external type func functype.

\[
S\models func a : func functype
\]

table a

- The store entry S.tables[a] must be a table instance \{elem (fa^?)^n, max m^?\}.
- Then table a is valid with external type table (\{min n, max m^?\} anyfunc).

\[
S\models table a : table (\{min n, max m^?\} anyfunc)
\]

mem a

- The store entry S.mems[a] must be a memory instance \{data b^n 64Ki, max m^?\}, for some n.
- Then mem a is valid with external type mem (\{min n, max m^?\}).

\[
S\models mem a : mem (\{min n, max m^?\})
\]
global $a$

- The store entry $S$.globals[$a$] must be a global instance $\{\text{value (t.const $c$), mut mut}\}$.
- Then global $a$ is valid with external type global (mut $t$).

\[
S, S.globals[a] = \{\text{value (t.const $c$), mut mut}\}
\]

\[
S \vdash \text{global } a : \text{global (mut } t)\]

### 4.5.2 Import Matching

When instantiating a module, external values must be provided whose types are matched against the respective external types classifying each import. In some cases, this allows for a simple form of subtyping, as defined below.

#### Limits

Limits $\{\min n_1, \max m_1^2\}$ match limits $\{\min n_2, \max m_2^2\}$ if and only if:

- $n_1$ is larger than or equal to $n_2$.
- Either:
  - $m_2$ is empty.
- Or:
  - Both $m_1^2$ and $m_2^2$ are non-empty.
  - $m_1$ is smaller than or equal to $m_2$.

\[
\vdash \{\min n_1, \max m_1\} \leq \{\min n_2, \max m_2\} \quad \vdash \{\min n_1, \max m_1\} \leq \{\min n_2, \max m_2\}
\]

#### Functions

An external type func $\text{functype}_1$ matches $\text{functype}_2$ if and only if:

- Both $\text{functype}_1$ and $\text{functype}_2$ are the same.

\[
\vdash \text{functype}_1 \leq \text{functype}_2
\]

#### Tables

An external type table $(\text{limits}_1 \text{elemtype}_1)$ matches table $(\text{limits}_2 \text{elemtype}_2)$ if and only if:

- Limits $\text{limits}_1$ match $\text{limits}_2$.
- Both $\text{elemtype}_1$ and $\text{elemtype}_2$ are the same.

\[
\vdash \text{limits}_1 \leq \text{limits}_2 \quad \vdash \text{table (limits}_1 \text{elemtype}) \leq \text{table (limits}_2 \text{elemtype})
\]
Memories

An external type $\text{mem limits}_1$ matches $\text{mem limits}_2$ if and only if:

- Limits $\text{limits}_1$ match $\text{limits}_2$.

$$\vdash \text{limits}_1 \leq \text{limits}_2 \Rightarrow \text{limits}_1 \leq \text{limits}_2$$

Globals

An external type global $\text{global type}_1$ matches global $\text{global type}_2$ if and only if:

- Both $\text{global type}_1$ and $\text{global type}_2$ are the same.

$$\vdash \text{global type}_1 \leq \text{global type}_2$$

4.5.3 Allocation

New instances of $\text{functions, tables, memories, and globals}$ are $\text{allocated}$ in a store $S$, as defined by the following auxiliary functions.

Functions

1. Let $\text{func}$ be the $\text{function}$ to allocate and $\text{module inst}$ its $\text{module instance}$.
2. Let $a$ be the first free $\text{function address}$ in $S$.
3. Let $\text{func type}$ be the $\text{function type}$ $\text{module inst}.\text{types}[\text{func type}]$.
4. Let $\text{func inst}$ be the $\text{function instance}$ $\{\text{type } \text{func type}, \text{module } \text{module inst}, \text{code } \text{func}\}$.
5. Append $\text{func inst}$ to the $\text{funcs}$ of $S$.

$$\text{alloc func}(S, \text{func}, \text{module inst}) = S', \text{func addr}$$

where:

- $\text{func addr} = |S.\text{func s}|$
- $\text{func type} = \text{module inst}.\text{types}[\text{func type}]$
- $\text{func inst} = \{\text{type } \text{func type}, \text{module } \text{module inst}, \text{code } \text{func}\}$
- $S' = S \oplus \{\text{func inst}\}$

Host Functions

1. Let $\text{host func}$ be the $\text{host function}$ to allocate and $\text{func type}$ its $\text{function type}$.
2. Let $a$ be the first free $\text{function address}$ in $S$.
3. Let $\text{func inst}$ be the $\text{function instance}$ $\{\text{type } \text{func type}, \text{host code } \text{host func}\}$.
4. Append $\text{func inst}$ to the $\text{funcs}$ of $S$.
5. Return $a$.
allochostfunc(S, functype, hostfunc) = S’, funcaddr

where:
  funcaddr = |S.funcs|
  funcinst = {type functype, hostcode hostfunc}
  S’ = S ⊕ {funcs funcinst}

Note: Host functions are never allocated by the WebAssembly semantics itself, but may be allocated by the embedder.

Tables

1. Let tabletype be the table type to allocate.
2. Let ({min n, max m} elmentype) be the structure of table type tabletype.
3. Let a be the first free table address in S.
4. Let tableinst be the table instance {elem (e)ⁿ, max m} with n empty elements.
5. Append tableinst to the tables of S.

alloctable(S, tabletype) = S’, tableaddr

where:
  tabletype = {min n, max m} elmentype
  tableaddr = |S.tables|
  tableinst = {elem (e)ⁿ, max m}
  S’ = S ⊕ {tables tableinst}

Memories

1. Let memtype be the memory type to allocate.
2. Let {min n, max m} be the structure of memory type memtype.
3. Let a be the first free memory address in S.
4. Let meminst be the memory instance {data (0x00)ⁿ 64 Ki, max m} that contains n pages of zeroed bytes.
5. Append meminst to the mems of S.

allocmem(S, memtype) = S’, memaddr

where:
  memtype = {min n, max m}
  memaddr = |S.mems|
  meminst = {data (0x00)ⁿ 64 Ki, max m}
  S’ = S ⊕ {mems meminst}

Globals

1. Let globaltype be the global type to allocate and val the value to initialize the global with.
2. Let mut t be the structure of global type globaltype.
3. Let a be the first free global address in S.
4. Let $\text{globalinst}$ be the global instance $\{\text{value val, mut mut}\}$.
5. Append $\text{globalinst}$ to the globals of $S$.

$$\text{allocglobal}(S, \text{globaltype}, \text{val}) = S', \text{globaladdr}$$
where:
- $\text{globaltype} = \text{mut } t$
- $\text{globaladdr} = |S.\text{globals}|
- $\text{globalinst} = \{\text{value val, mut mut}\}$
- $S' = S \oplus \{\text{globals globalinst}\}$

**Growing tables**

1. Let $\text{tableinst}$ be the table instance to grow and $n$ the number of elements by which to grow it.
2. Let $\text{len}$ be $n$ added to the length of $\text{tableinst}.\text{elem}$.
3. If $\text{len}$ is larger than $2^{32}$, then fail.
4. If $\text{tableinst}.\text{max}$ is not empty and smaller than $\text{len}$, then fail.
5. Append $n$ empty elements to $\text{tableinst}.\text{elem}$.

$$\text{growtable} (\text{tableinst}, n) = \text{tableinst with elem = tableinst.elem (ε)$^n$}$$
if $\text{len} = n + |\text{tableinst}.\text{elem}|$
$\land \text{len} \leq 2^{32}$
$\land (\text{tableinst}.\text{max} = \epsilon \lor \text{len} \leq \text{tableinst}.\text{max})$

**Growing memories**

1. Let $\text{meminst}$ be the memory instance to grow and $n$ the number of pages by which to grow it.
2. Assert: The length of $\text{meminst}.\text{data}$ is divisible by the page size 64 Ki.
3. Let $\text{len}$ be $n$ added to the length of $\text{meminst}.\text{data}$ divided by the page size 64 Ki.
4. If $\text{len}$ is larger than $2^{16}$, then fail.
5. If $\text{meminst}.\text{max}$ is not empty and its value is smaller than $\text{len}$, then fail.
6. Append $n$ times 64 Ki bytes with value 0x00 to $\text{meminst}.\text{data}$.

$$\text{growmem} (\text{meminst}, n) = \text{meminst with data = meminst.data (0x00)$^{n \cdot 64\text{ Ki}}}$
if $\text{len} = n + |\text{meminst}.\text{data}|/64\text{ Ki}$
$\land \text{len} \leq 2^{16}$
$\land (\text{meminst}.\text{max} = \epsilon \lor \text{len} \leq \text{meminst}.\text{max})$

**Modules**

The allocation function for modules requires a suitable list of external values that are assumed to match the import vector of the module, and a list of initialization values for the module’s globals.

1. Let $\text{module}$ be the module to allocate and $\text{externval}^*_\text{im}$ the vector of external values providing the module’s imports, and $\text{val}^*$ the initialization values of the module’s globals.
2. For each function $\text{func}_i$ in $\text{module}.\text{funcs}$, do:
   a. Let $\text{funcaddr}_i$ be the function address resulting from allocating $\text{func}_i$ for the module instance $\text{moduleinst}$ defined below.
3. For each table $i$ in $module\text{.}tables$, do:
   (a) Let $\text{tableaddr}_i$ be the table address resulting from allocating $\text{table}_i\text{.type}$.
4. For each memory $mem_i$ in $module\text{.}mems$, do:
   (a) Let $\text{memaddr}_i$ be the memory address resulting from allocating $\text{mem}_i\text{.type}$.
5. For each global $global_i$ in $module\text{.}globals$, do:
   (a) Let $\text{globaladdr}_i$ be the global address resulting from allocating $\text{global}_i\text{.type}$ with initializer value $val[*i]$.
6. Let $\text{funcaddr}^*$ be the the concatenation of the function addresses $\text{funcaddr}_i$ in index order.
7. Let $\text{tableaddr}^*$ be the the concatenation of the table addresses $\text{tableaddr}_i$ in index order.
8. Let $\text{memaddr}^*$ be the the concatenation of the memory addresses $\text{memaddr}_i$ in index order.
9. Let $\text{globaladdr}^*$ be the the concatenation of the global addresses $\text{globaladdr}_i$ in index order.
10. Let $\text{funcaddr}^*\text{mod}$ be the the list of function addresses extracted from $\text{externval}^*_\text{im}$, concatenated with $\text{funcaddr}^*$.
11. Let $\text{tableaddr}^*\text{mod}$ be the list of table addresses extracted from $\text{externval}^*_\text{im}$, concatenated with $\text{tableaddr}^*$.
12. Let $\text{memaddr}^*\text{mod}$ be the list of memory addresses extracted from $\text{externval}^*_\text{im}$, concatenated with $\text{memaddr}^*$.
13. Let $\text{globaladdr}^*\text{mod}$ be the list of global addresses extracted from $\text{externval}^*_\text{im}$, concatenated with $\text{globaladdr}^*$.
14. For each export $export_i$ in $module\text{.}exports$, do:
    (a) If $export_i$ is a function export for function index $x$, then let $\text{externval}_i$ be the external value $\text{func}(\text{funcaddr}^*\text{mod}[x])$.
    (b) Else, if $export_i$ is a table export for table index $x$, then let $\text{externval}_i$ be the external value $\text{table}(\text{tableaddr}^*\text{mod}[x])$.
    (c) Else, if $export_i$ is a memory export for memory index $x$, then let $\text{externval}_i$ be the external value $\text{mem}(\text{memaddr}^*\text{mod}[x])$.
    (d) Else, if $export_i$ is a global export for global index $x$, then let $\text{externval}_i$ be the external value $\text{global}(\text{globaladdr}^*\text{mod}[x])$.
    (e) Let $\text{exportinst}_i$ be the export instance $\{name(\text{export}_i\text{.name}), value \text{externval}_i\}$.
15. Let $\text{exportinst}^*$ be the the concatenation of the export instances $\text{exportinst}_i$ in index order.
16. Let $\text{moduleinst}$ be the module instance $\{\text{types }module\text{.types}, \text{funcaddrs }\text{funcaddr}^*\text{mod}, \text{tableaddrs }\text{tableaddr}^*\text{mod}, \text{memaddrs }\text{memaddr}^*\text{mod}, \text{globaladdrs }\text{globaladdr}^*\text{mod}, \text{exports }\text{exportinst}^*\}$.
17. Return $\text{moduleinst}$.

\[
\text{allocmodule}(S, module, \text{externval}^*_\text{im}, \text{val}^*) = S', \text{moduleinst}
\]
where:

\[
\text{moduleinst} = \{ \text{types module.types, funcaddr funcs(external}_{im}^n \text{funcaddr}), tableaddr tables(external}_{im}^n \text{tableaddr}), memaddr mems(external}_{im}^n \text{memaddr}), globaladdr globals(external}_{im}^n \text{globaladdr}), exports exportinst} \}
\]

\[
S_1, \text{funcaddr} = \text{allocfunc}(S, \text{module.funcs, moduleinst})
\]

\[
S_2, \text{tableaddr} = \text{allocatable}(S_1, (\text{table.type}^n)^*) \quad \text{(where table}^n = \text{module.tables)}
\]

\[
S_3, \text{memaddr} = \text{allocmem}(S_2, (\text{mem.type}^n)^*) \quad \text{(where mem}^n = \text{module.mems)}
\]

\[
S, \text{globaladdr} = \text{allocglobal}(S_3, (\text{global.type}^n)^*, \text{val}) \quad \text{(where global}^n = \text{module.globals)}
\]

\[
\text{exportinst} = \{ \text{name (export.name), value external}_{ex}^n \}^*
\]

\[
\text{funcs(external}_{ex}^n) = (\text{moduleinst.fncaddr}[x])^* \quad \text{(where x}^n = \text{funcs(module.exports)}
\]

\[
\text{tables(external}_{ex}^n) = (\text{moduleinst.tableaddr}[x])^* \quad \text{(where x}^n = \text{tables(module.exports)}
\]

\[
\text{mems(external}_{ex}^n) = (\text{moduleinst.memaddr}[x])^* \quad \text{(where x}^n = \text{mems(module.exports)}
\]

\[
\text{globals(external}_{ex}^n) = (\text{moduleinst.globaladdr}[x])^* \quad \text{(where x}^n = \text{globals(module.exports)}
\]

Here, the notation allocx* is shorthand for multiple allocations of object kind X, defined as follows:

\[
\text{allocx}^*(S_0, X^n, \ldots) = S_n, a^n
\]

where for all i < n:

\[
S_{i+1}, a^n[i] = \text{allocx}(S_i, X^n[i], \ldots)
\]

Moreover, if the dots . . . are a sequence \( A^n \) (as for globals), then the elements of this sequence are passed to the allocation function pointwise.

**Note:** The definition of module allocation is mutually recursive with the allocation of its associated functions, because the resulting module instance moduleinst is passed to the function allocator as an argument, in order to form the necessary closures. In an implementation, this recursion is easily unraveled by mutating one or the other in a secondary step.

### 4.5.4 Instantiation

Given a store \( S \), a module module is instantiated with a list of external values external\(^n\) supplying the required imports as follows.

Instantiation checks that the module is valid and the provided imports match the declared types, and may fail with an error otherwise. Instantiation can also result in a trap from executing the start function. It is up to the embedder to define how such conditions are reported.

1. If module is not valid, then:
   (a) Fail.
2. Assert: module is valid with external types externaltype\(^m_{im}\) classifying its imports.
3. If the number \( m \) of imports is not equal to the number \( n \) of provided external values, then:
   (a) Fail.
4. For each external value external\(_i\) in external\(^n\) and external type externaltype\(_i\) in externaltype\(^m_{im}\), do:
   (a) If external\(_i\) is not valid with an external type externaltype\(_i\) in store \( S \), then:
      i. Fail.
   (b) If externaltype\(_i\) does not match externaltype\(_i\), then:
      i. Fail.
5. Let val* be the vector of global initialization values determined by module and external\(^n\). These may be calculated as follows.
(a) Let \( moduleinst_{im} \) be the auxiliary module \( \text{instance} \{ \text{globaladdrs} \ \text{globals}(\text{externval}^n) \} \) that only consists of the imported globals.

(b) Let \( F_{im} \) be the auxiliary frame \( \{ \text{module} \ moduleinst_{im}, \text{locals} \ \epsilon \} \).

(c) Push the frame \( F_{im} \) to the stack.

(d) For each \( \text{global} \ \text{global}_i \) in \( \text{module} \ \text{globals} \), do:
   i. Let \( \text{val}_i \) be the result of evaluating the initializer expression \( \text{global}_i, \text{init} \).

(e) Assert: due to validation, the frame \( F_{im} \) is now on the top of the stack.

(f) Pop the frame \( F_{im} \) from the stack.

6. Let \( moduleinst \) be a new module instance \( \text{allocated} \) from \( \text{module} \) in store \( S \) with imports \( \text{externval}^n \) and global initializer values \( \text{val}^* \), and let \( S' \) be the extended store produced by module allocation.

7. Let \( F \) be the frame \( \{ \text{module} \ moduleinst, \text{locals} \ \epsilon \} \).

8. Push the frame \( F \) to the stack.

9. For each \( \text{element segment} \ \text{elem}_i \) in \( \text{module} \ . \ \text{elem} \), do:
   (a) Let \( \text{eval}_i \) be the result of evaluating the expression \( \text{elem}_i, \text{offset} \).

(b) Assert: due to validation, \( \text{eval}_i \) is of the form \( \text{i32}\text{const} \ \text{eo}_i \).

(c) Let \( \text{tableidx}_i \) be the \( \text{table index} \ \text{elem}_i, \text{table} \).

(d) Assert: due to validation, \( moduleinst_{.}\text{tableaddrs}[\text{tableidx}_i] \) exists.

(e) Let \( \text{tableaddr}_i \) be the \( \text{table address} \ moduleinst_{.}\text{tableaddrs}[\text{tableidx}_i] \).

(f) Assert: due to validation, \( S'.\text{tables}[\text{tableaddr}_i] \) exists.

(g) Let \( \text{tableinst}_i \) be the \( \text{table instance} \ S'.\text{tables}[\text{tableaddr}_i] \).

(h) Let \( \text{eoval}_i \) be \( \text{eo}_i \) plus the length of \( \text{elem}_i, \text{init} \).

(i) If \( \text{eoval}_i \) is larger than the length of \( \text{tableinst}_i, \text{elem} \), then:
   i. Fail.

10. For each \( \text{data segment} \ \text{data}_i \) in \( \text{module} \ . \ \text{data} \), do:
    (a) Let \( \text{doval}_i \) be the result of evaluating the expression \( \text{data}_i, \text{offset} \).

    (b) Assert: due to validation, \( \text{doval}_i \) is of the form \( \text{i32}\text{const} \ \text{do}_i \).

    (c) Let \( \text{memidx}_i \) be the \( \text{memory index} \ \text{data}_i, \text{data} \).

    (d) Assert: due to validation, \( moduleinst_{.}\text{memaddrs}[\text{memidx}_i] \) exists.

    (e) Let \( \text{memaddr}_i \) be the \( \text{memory address} \ moduleinst_{.}\text{memaddrs}[\text{memidx}_i] \).

    (f) Assert: due to validation, \( S'.\text{mems}[\text{memaddr}_i] \) exists.

    (g) Let \( \text{meminst}_i \) be the \( \text{memory instance} \ S'.\text{mems}[\text{memaddr}_i] \).

    (h) Let \( \text{dend}_i \) be \( \text{do}_i \) plus the length of \( \text{data}_i, \text{init} \).

    (i) If \( \text{dend}_i \) is larger than the length of \( \text{meminst}_i, \text{data} \), then:
       i. Fail.

11. Assert: due to validation, the frame \( F \) is now on the top of the stack.

12. Pop the frame from the stack.

13. For each \( \text{element segment} \ \text{elem}_i \) in \( \text{module} \ . \ \text{elem} \), do:
    (a) For each \( \text{function index} \ \text{funcidx}_{ij} \) in \( \text{elem}_i, \text{init} \) (starting with \( j = 0 \)), do:
       i. Assert: due to validation, \( moduleinst_{.}\text{funcaddrs}[\text{funcidx}_{ij}] \) exists.

       ii. Let \( \text{funcaddr}_{ij} \) be the \( \text{function address} \ moduleinst_{.}\text{funcaddrs}[\text{funcidx}_{ij}] \).
iii. Replace \text{tableinst}.\text{elem}[co_i + j] with \text{funcaddr}_{ij}.

14. For each data segment \text{data}_i in \text{module.data}, do:
   (a) For each byte \(b_{ij}\) in \text{data}_i.init (starting with \(j = 0\)), do:
      i. Replace \text{meminst}.\text{data}[do_i + j] with \(b_{ij}\).

15. If the start function \text{module.start} is not empty, then:
   (a) Assert: due to validation, \text{moduleinst}.\text{funcaddr}[\text{module.start.func}] exists.
   (b) Let \text{funcaddr} be the function address \text{moduleinst}.\text{funcaddr}[\text{module.start.func}].
   (c) Invoke the function instance at \text{funcaddr}.

\[
\text{instantiate}(S, \text{module}, \text{externval}^n) = S'; F; (\text{init_elem tableaddr co elem.init})^* \\
\quad (\text{init_data memaddr do data.init})^* \\
\quad (\text{invoke funcaddr})^*
\]

\[
\text{if } (\vdash \text{module} : \text{externTYPE}_n \rightarrow \text{externTYPE}_{ex} \\
\quad (S \vdash \text{externval} : \text{externTYPE}_{ex})^* \\
\quad (\vdash \text{externTYPE} \leq \text{externTYPE}_n)^n \\
\quad \text{module.globals} = \text{global}^* \\
\quad \text{module.elem} = \text{elem}^* \\
\quad \text{module.data} = \text{data}^* \\
\quad \text{module.start} = \text{start}^? \\
\quad S', \text{moduleinst} = \text{allocmodule}(S, \text{module}, \text{externval}^n, \text{val}^*) \\
\quad F = \{\text{module moduleinst}, \text{locals }\epsilon\} \\
\quad (S'; F; \text{global.init} \leftrightarrow *S'; F; \text{val end})^* \\
\quad (S'; F; \text{elem.offset} \leftrightarrow *S'; F; \text{i32.const co end})^* \\
\quad (S'; F; \text{data.offset} \leftrightarrow *S'; F; \text{i32.const do end})^* \\
\quad (eo + |\text{elem.init} \leq |S'.\text{tables[tableaddr]}.\text{elem}|)^* \\
\quad (do + |\text{data.init} \leq |S'.\text{mems}[\text{memaddr}].\text{data}|)^* \\
\quad (\text{tableaddr} = \text{moduleinst}.\text{tableaddrs[elem.table]})^* \\
\quad (\text{memaddr} = \text{moduleinst}.\text{memaddrs[data.data]})^* \\
\quad (\text{funcaddr} = \text{moduleinst}.\text{funcaddrs[start.func]})^*)
\]

\[
S; F; \text{init_elem }a \ i \ \epsilon \\
S; F; \text{init_data }a \ i \ (x_0 \ x^*)
\]

\[
S; F; \text{init_elem }a \ i \ (x_0 \ x^*) \\ \\
S; F; \text{init_data }a \ i \ (b_0 \ b^*)
\]

**Note:** Module allocation and the evaluation of global initializers are mutually recursive because the global initialization values \text{val}^* are passed to the module allocator but depend on the store \(S'\) and module instance \text{moduleinst} returned by allocation. However, this recursion is just a specification device. Due to validation, the initialization values can easily be determined from a simple pre-pass that evaluates global initializers in the initial store.

All failure conditions are checked before any observable mutation of the store takes place. Store mutation is not atomic; it happens in individual steps that may be interleaved with other threads.

**Evaluation of constant expressions** does not affect the store.
4.5.5 Invocation

Once a module has been instantiated, any exported function can be invoked externally via its function address \( \text{funcaddr} \) in the store \( S \) and an appropriate list \( \text{val}^* \) of argument values.

Invocation may fail with an error if the arguments do not fit the function type. Invocation can also result in a trap. It is up to the embedder to define how such conditions are reported.

**Note:** If the embedder API performs type checks itself, either statically or dynamically, before performing an invocation, then no failure other than traps can occur.

The following steps are performed:

1. Assert: \( S.\text{funcs}[\text{funcaddr}] \) exists.
2. Let \( \text{funcinst} \) be the function instance \( S.\text{funcs}[\text{funcaddr}] \).
3. Let \( [t^n_1] \rightarrow [t^n_2] \) be the function type \( \text{funcinst}.\text{type} \).
4. If the length \( |\text{val}^*| \) of the provided argument values is different from the number \( n \) of expected arguments, then:
   (a) Fail.
5. For each value type \( t_i \) in \( t^n_1 \) and corresponding value \( \text{val}_i \) in \( \text{val}^* \), do:
   (a) If \( \text{val}_i \) is not \( t_i.\text{const} c_i \) for some \( c_i \), then:
      i. Fail.
6. Push the values \( \text{val}^* \) to the stack.
7. Invoke the function instance at address \( \text{funcaddr} \).

Once the function has returned, the following steps are executed:

1. Assert: due to validation, \( m \) values are on the top of the stack.
2. Pop \( \text{val}^{\text{res}}_m \) from the stack.

The values \( \text{val}_{\text{res}}^m \) are returned as the results of the invocation.

\[
\text{invoke}(S, \text{funcaddr}, \text{val}^m) = \begin{cases} 
S; F; \text{val}^m (\text{invoke funcaddr}) \\
\text{(if } S.\text{funcs}[\text{funcaddr}].\text{type} = [t^n_1] \rightarrow [t^n_2] \\
\wedge \text{val}^m = (t_i.\text{const } c)^n \\
\wedge F = \{\text{module } \{\}, \text{locals } \epsilon \}) \end{cases}
\]
5.1 Conventions

The binary format for WebAssembly modules is a dense linear encoding of their abstract syntax.\(^{27}\)

The format is defined by an attribute grammar whose only terminal symbols are bytes. A byte sequence is a well-formed encoding of a module if and only if it is generated by the grammar.

Each production of this grammar has exactly one synthesized attribute: the abstract syntax that the respective byte sequence encodes. Thus, the attribute grammar implicitly defines a decoding function (i.e., a parsing function for the binary format).

Except for a few exceptions, the binary grammar closely mirrors the grammar of the abstract syntax.

**Note:** Some phrases of abstract syntax have multiple possible encodings in the binary format. For example, numbers may be encoded as if they had optional leading zeros. Implementations of decoders must support all possible alternatives; implementations of encoders can pick any allowed encoding.

The recommended extension for files containing WebAssembly modules in binary format is “.wasm” and the recommended Media Type\(^ {26}\) is “application/wasm”.

5.1.1 Grammar

The following conventions are adopted in defining grammar rules for the binary format. They mirror the conventions used for abstract syntax. In order to distinguish symbols of the binary syntax from symbols of the abstract syntax, typewriter font is adopted for the former.

- Terminal symbols are bytes expressed in hexadecimal notation: 0x0F.
- Nonterminal symbols are written in typewriter font: valtype, instr.
- \(B^n\) is a sequence of \(n \geq 0\) iterations of \(B\).
- \(B^*\) is a possibly empty sequence of iterations of \(B\). (This is a shorthand for \(B^n\) used where \(n\) is not relevant.)

---

\(^{27}\) Additional encoding layers – for example, introducing compression – may be defined on top of the basic representation defined here. However, such layers are outside the scope of the current specification.

\(^{26}\) https://www.iana.org/assignments/media-types/media-types.xhtml
• $B^?\nu$ is an optional occurrence of $B\nu$. (This is a shorthand for $B\nu\nu\nu$ where $n \leq 1$.)

• $x:B$ denotes the same language as the nonterminal $B$, but also binds the variable $x$ to the attribute synthesized for $B$.

• Productions are written $\text{sym} ::= B_1 \Rightarrow A_1 | \ldots | B_n \Rightarrow A_n$, where each $A_i$ is the attribute that is synthesized for $\text{sym}$ in the given case, usually from attribute variables bound in $B_i$.

• Some productions are augmented by side conditions in parentheses, which restrict the applicability of the production. They provide a shorthand for a combinatorial expansion of the production into many separate cases.

**Note:** For example, the binary grammar for value types is given as follows:

\[
\text{valtype} ::= 0x7F \Rightarrow \text{i32} \\
| 0x7E \Rightarrow \text{i64} \\
| 0x7D \Rightarrow \text{f32} \\
| 0x7C \Rightarrow \text{f64}
\]

Consequently, the byte 0x7F encodes the type i32, 0x7E encodes the type i64, and so forth. No other byte value is allowed as the encoding of a value type.

The binary grammar for limits is defined as follows:

\[
\text{limits} ::= 0x00 n:u32 \Rightarrow \{\min n, \max \epsilon\} \\
| 0x01 n:u32 m:u32 \Rightarrow \{\min n, \max m\}
\]

That is, a limits pair is encoded as either the byte 0x00 followed by the encoding of a u32 value, or the byte 0x01 followed by two such encodings. The variables $n$ and $m$ name the attributes of the respective u32 nonterminals, which in this case are the actual unsigned integers those decode into. The attribute of the complete production then is the abstract syntax for the limit, expressed in terms of the former values.

### 5.1.2 Auxiliary Notation

When dealing with binary encodings the following notation is also used:

• $\epsilon$ denotes the empty byte sequence.

• $||B||$ is the length of the byte sequence generated from the production $B$ in a derivation.

### 5.1.3 Vectors

Vectors are encoded with their u32 length followed by the encoding of their element sequence.

\[
\text{vec}(B) ::= n:u32 (x:B)^n \Rightarrow x^n
\]

### 5.2 Values

#### 5.2.1 Bytes

Bytes encode themselves.

\[
\text{byte} ::= 0x00 \Rightarrow 0x00 \\
| \ldots \\
| 0xFF \Rightarrow 0xFF
\]
5.2.2 Integers

All integers are encoded using the LEB128\(^{28}\) variable-length integer encoding, in either unsigned or signed variant.

Unsigned integers are encoded in unsigned LEB128\(^{29}\) format. As an additional constraint, the total number of bytes encoding a value of type \(uN\) must not exceed \(\text{ceil}(N/7)\) bytes.

\[
uN ::= n:\text{byte} \quad \Rightarrow \quad n \quad \text{(if } n < 2^7 \land n < 2^N)\]
\[
\quad | \quad n:\text{byte} \quad m:u(N-7) \quad \Rightarrow \quad 2^7 \cdot m + (n - 2^7) \quad \text{(if } n \geq 2^7 \land N > 7)\]

Signed integers are encoded in signed LEB128\(^{30}\) format, which uses a two’s complement representation. As an additional constraint, the total number of bytes encoding a value of type \(sN\) must not exceed \(\text{ceil}(N/7)\) bytes.

\[
sN ::= n:\text{byte} \quad \Rightarrow \quad n \quad \text{(if } n < 2^6 \land n < 2^{N-1})\]
\[
\quad | \quad n:\text{byte} \quad \Rightarrow \quad n - 2^7 \quad \text{(if } 2^6 \leq n < 2^7 \land n \geq 2^7 - 2^{N-1})\]
\[
\quad | \quad n:\text{byte} \quad m:s(N-7) \quad \Rightarrow \quad 2^7 \cdot m + (n - 2^7) \quad \text{(if } n \geq 2^7 \land N > 7)\]

Uninterpreted integers are encoded as signed integers.

\[
iN ::= n:sN \quad \Rightarrow \quad i \quad \text{(if } n = \text{signed}_{iN}(i))\]

**Note:** The side conditions \(N > 7\) in the productions for non-terminal bytes of the \(u\) and \(s\) encodings restrict the encoding’s length. However, “trailing zeros” are still allowed within these bounds. For example, 0x03 and 0x83 0x00 are both well-formed encodings for the value 3 as a \(u8\). Similarly, either of 0x7e and 0xFF 0x7F and 0xFE 0xFF 0x7F are well-formed encodings of the value −2 as a \(s16\).

The side conditions on the value \(n\) of terminal bytes further enforce that any unused bits in these bytes must be 0 for positive values and 1 for negative ones. For example, 0x83 0x10 is malformed as a \(u8\) encoding. Similarly, both 0x83 0x3E and 0xFF 0x7B are malformed as \(s8\) encodings.

5.2.3 Floating-Point

Floating-point values are encoded directly by their IEEE 754-2008\(^{31}\) bit pattern in little endian\(^{32}\) byte order:

\[
fN ::= b*:\text{byte}^{N/8} \quad \Rightarrow \quad \text{bytes}_{fN}^{-1}(b*)\]

5.2.4 Names

Names are encoded as a vector of bytes containing the Unicode\(^{33}\) UTF-8 encoding of the name’s code point sequence.

\[
\text{name} ::= b*:\text{vec}(\text{byte}) \quad \Rightarrow \quad \text{name} \quad \text{(if } \text{utf8}(\text{name}) = b*)\]

---

\(^{28}\) https://en.wikipedia.org/wiki/LEB128  
\(^{29}\) https://en.wikipedia.org/wiki/LEB128#Unsigned_LEB128  
\(^{30}\) https://en.wikipedia.org/wiki/LEB128#Signed_LEB128  
\(^{31}\) http://ieeexplore.ieee.org/document/4610935/  
\(^{32}\) https://en.wikipedia.org/wiki/Endianness#Little-endian  
\(^{33}\) http://www.unicode.org/versions/latest/
The auxiliary utf8 function expressing this encoding is defined as follows:

\[
\begin{align*}
\text{utf8}(c^*) &= (\text{utf8}(c))^* \\
\text{utf8}(c) &= b & \text{if } c < U+80 \\
& & \land c = b \\
\text{utf8}(c) &= b_1 b_2 & \text{if } U+80 \leq c < U+800 \\
& & \land c = 2^6(b_1 - 0xC0) + (b_2 - 0x80) \\
\text{utf8}(c) &= b_1 b_2 b_3 & \text{if } U+800 \leq c < U+10000 \\
& & \land c = 2^{12}(b_1 - 0xE0) + 2^6(b_2 - 0x80) + (b_3 - 0x80) \\
\text{utf8}(c) &= b_1 b_2 b_3 b_4 & \text{if } U+10000 \leq c < U+110000 \\
& & \land c = 2^{18}(b_1 - 0xF0) + 2^{12}(b_2 - 0x80) + 2^6(b_3 - 0x80) + (b_4 - 0x80)
\end{align*}
\]

Note: Unlike in some other formats, name strings are not 0-terminated.

5.3 Types

5.3.1 Value Types

Value types are encoded by a single byte.

\[
\text{valtype} ::= 0x7F \Rightarrow i32 \\
& | 0x7E \Rightarrow i64 \\
& | 0x7D \Rightarrow f32 \\
& | 0x7C \Rightarrow f64
\]

Note: In future versions of WebAssembly, value types may include types denoted by type indices. Thus, the binary format for types corresponds to the signed LEB128\(^{34}\) encoding of small negative \(sN\) values, so that they can coexist with (positive) type indices in the future.

5.3.2 Result Types

The only result types occurring in the binary format are the types of blocks. These are encoded in special compressed form, by either the byte 0x40 indicating the empty type or as a single value type.

\[
\text{blocktype} ::= 0x40 \Rightarrow \[] \\
& | t:\text{valtype} \Rightarrow [t]
\]

Note: In future versions of WebAssembly, this scheme may be extended to support multiple results or more general block types.

5.3.3 Function Types

Function types are encoded by the byte 0x60 followed by the respective vectors of parameter and result types.

\[
\text{functype} ::= 0x60 \ t_1:\text{vec(valtype)} \ t_2:\text{vec(valtype)} \Rightarrow [t_1] \rightarrow [t_2]
\]

\(^{34}\)https://en.wikipedia.org/wiki/LEB128#Signed_LEB128
5.3.4 Limits

Limits are encoded with a preceding flag indicating whether a maximum is present.

\[
\text{limits} ::= 0x00 \ n:u32 \Rightarrow \{\min n, \max \epsilon\} \\
| 0x01 \ n:u32 \ m:u32 \Rightarrow \{\min n, \max m\}
\]

5.3.5 Memory Types

Memory types are encoded with their limits.

\[
\text{memtype} ::= \text{lim:limits} \Rightarrow \text{lim}
\]

5.3.6 Table Types

Table types are encoded with their limits and a constant byte indicating their element type.

\[
\text{tabletype} ::= \text{et:elemtype \ lim:limits} \Rightarrow \text{lim et} \\
\text{elemtype} ::= 0x70 \Rightarrow \text{anyfunc}
\]

5.3.7 Global Types

Global types are encoded by their value type and a flag for their mutability.

\[
\text{globaltype} ::= \text{t:valtype \ m:mut} \Rightarrow \text{m t} \\
\text{mut} ::= 0x00 \Rightarrow \text{const} \\
| 0x01 \Rightarrow \text{var}
\]

5.4 Instructions

Instructions are encoded by opcodes. Each opcode is represented by a single byte, and is followed by the instruction’s immediate arguments, where present. The only exception are structured control instructions, which consist of several opcodes bracketing their nested instruction sequences.

Note: Gaps in the byte code ranges for encoding instructions are reserved for future extensions.

5.4.1 Control Instructions

Control instructions have varying encodings. For structured instructions, the instruction sequences forming nested blocks are terminated with explicit opcodes for end and else.
The WebAssembly Specification, Release 1.0

5.4.2 Parametric Instructions

Parametric instructions are represented by single byte codes.

\[ \text{instr} ::= \ldots \]
\[ | \text{0x00} \Rightarrow \text{unreachable} \]
\[ | \text{0x01} \Rightarrow \text{nop} \]
\[ | \text{0x02} \Rightarrow \text{br} \text{l} \]
\[ | \text{0x03} \Rightarrow \text{br} \text{if} \text{l} \]
\[ | \text{0x04} \Rightarrow \text{br_table} \text{l}^* \text{l}_N \]
\[ | \text{0x05} \Rightarrow \text{return} \]
\[ | \text{0x10} \Rightarrow \text{call} \text{x} \]
\[ | \text{0x11} \Rightarrow \text{call_indirect} \text{x} \]

Note: The else opcode 0x05 in the encoding of an if instruction can be omitted if the following instruction sequence is empty.

Note: In future versions of WebAssembly, the zero byte occurring in the encoding of the call_indirect instruction may be used to index additional tables.

5.4.3 Variable Instructions

Variable instructions are represented by byte codes followed by the encoding of the respective index.

\[ \text{instr} ::= \ldots \]
\[ | \text{0x020} \Rightarrow \text{get_local} \text{x} \]
\[ | \text{0x021} \Rightarrow \text{set_local} \text{x} \]
\[ | \text{0x022} \Rightarrow \text{tee_local} \text{x} \]
\[ | \text{0x023} \Rightarrow \text{get_global} \text{x} \]
\[ | \text{0x024} \Rightarrow \text{set_global} \text{x} \]

5.4.4 Memory Instructions

Each variant of memory instruction is encoded with a different byte code. Loads and stores are followed by the encoding of their memory immediate.
memarg ::= \( a : \text{u32} \ o : \text{u32} \) \( \Rightarrow \) \{align \( a \), offset \( o \)\}

instr ::= ...

| 0x28 \( m : \text{memarg} \) | \( \Rightarrow \) \( i32.\text{load} \ m \) |
| 0x29 \( m : \text{memarg} \) | \( \Rightarrow \) \( i64.\text{load} \ m \) |
| 0x2A \( m : \text{memarg} \) | \( \Rightarrow \) \( f32.\text{load} \ m \) |
| 0x2B \( m : \text{memarg} \) | \( \Rightarrow \) \( f64.\text{load} \ m \) |
| 0x2C \( m : \text{memarg} \) | \( \Rightarrow \) \( i32.\text{load8_s} \ m \) |
| 0x2D \( m : \text{memarg} \) | \( \Rightarrow \) \( i32.\text{load8_u} \ m \) |
| 0x2E \( m : \text{memarg} \) | \( \Rightarrow \) \( i32.\text{load16_s} \ m \) |
| 0x2F \( m : \text{memarg} \) | \( \Rightarrow \) \( i32.\text{load16_u} \ m \) |
| 0x30 \( m : \text{memarg} \) | \( \Rightarrow \) \( i64.\text{load8_s} \ m \) |
| 0x31 \( m : \text{memarg} \) | \( \Rightarrow \) \( i64.\text{load8_u} \ m \) |
| 0x32 \( m : \text{memarg} \) | \( \Rightarrow \) \( i64.\text{load16_s} \ m \) |
| 0x33 \( m : \text{memarg} \) | \( \Rightarrow \) \( i64.\text{load16_u} \ m \) |
| 0x34 \( m : \text{memarg} \) | \( \Rightarrow \) \( i64.\text{load32_s} \ m \) |
| 0x35 \( m : \text{memarg} \) | \( \Rightarrow \) \( i64.\text{load32_u} \ m \) |
| 0x36 \( m : \text{memarg} \) | \( \Rightarrow \) \( i32.\text{store} \ m \) |
| 0x37 \( m : \text{memarg} \) | \( \Rightarrow \) \( i64.\text{store} \ m \) |
| 0x38 \( m : \text{memarg} \) | \( \Rightarrow \) \( f32.\text{store} \ m \) |
| 0x39 \( m : \text{memarg} \) | \( \Rightarrow \) \( f64.\text{store} \ m \) |
| 0x3A \( m : \text{memarg} \) | \( \Rightarrow \) \( i32.\text{store8} \ m \) |
| 0x3B \( m : \text{memarg} \) | \( \Rightarrow \) \( i32.\text{store16} \ m \) |
| 0x3C \( m : \text{memarg} \) | \( \Rightarrow \) \( i64.\text{store8} \ m \) |
| 0x3D \( m : \text{memarg} \) | \( \Rightarrow \) \( i64.\text{store16} \ m \) |
| 0x3E \( m : \text{memarg} \) | \( \Rightarrow \) \( i64.\text{store32} \ m \) |
| 0x3F 0x00 | \( \Rightarrow \) \( \text{memory.size} \) |
| 0x40 0x00 | \( \Rightarrow \) \( \text{memory.grow} \) |

**Note:** In future versions of WebAssembly, the additional zero bytes occurring in the encoding of the `memory.size` and `memory.grow` instructions may be used to index additional memories.

### 5.4.5 Numeric Instructions

All variants of numeric instructions are represented by separate byte codes.

All other numeric instructions are plain opcodes without any immediates.


<table>
<thead>
<tr>
<th>instr</th>
<th>meaning</th>
</tr>
</thead>
<tbody>
<tr>
<td>0x45</td>
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<td>i32.lte</td>
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<td>0x4C</td>
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</tr>
<tr>
<td>0x4D</td>
<td>i32.lege</td>
</tr>
<tr>
<td>0x4E</td>
<td>i32.ge</td>
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<td>i32.geu</td>
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<tr>
<td>0xA8</td>
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<tr>
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<tr>
<td>0xAB</td>
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<td>⇒ i64.extend_u/i32</td>
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<tr>
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</tr>
<tr>
<td>0xAF</td>
<td>⇒ i64.trunc_u/f32</td>
</tr>
<tr>
<td>0xB0</td>
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</tr>
<tr>
<td>0xB1</td>
<td>⇒ i64.trunc_u/f64</td>
</tr>
<tr>
<td>0xB2</td>
<td>⇒ f32.convert_s/i32</td>
</tr>
<tr>
<td>0xB3</td>
<td>⇒ f32.convert_u/i32</td>
</tr>
<tr>
<td>0xB4</td>
<td>⇒ f32.convert_s/f32</td>
</tr>
<tr>
<td>0xB5</td>
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</tr>
<tr>
<td>0xB6</td>
<td>⇒ f32.demote/f64</td>
</tr>
<tr>
<td>0xB7</td>
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<tr>
<td>0xB8</td>
<td>⇒ f64.convert_u/i32</td>
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<td>⇒ i64.reinterpret/f64</td>
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<tr>
<td>0xBE</td>
<td>⇒ f32.reinterpret/i32</td>
</tr>
<tr>
<td>0xBF</td>
<td>⇒ f64.reinterpret/i64</td>
</tr>
</tbody>
</table>

5.4.6 Expressions

*Expressions* are encoded by their instruction sequence terminated with an explicit 0x0B opcode for **end**.

\[
\text{expr} ::= (in:instr)^* 0x0B \Rightarrow in^* end
\]

5.5 Modules

The binary encoding of modules is organized into *sections*. Most sections correspond to one component of a *module* record, except that *function definitions* are split into two sections, separating their type declarations in the *function section* from their bodies in the *code section*.

*Note:* This separation enables *parallel* and *streaming* compilation of the functions in a module.

5.5.1 Indices

All *indices* are encoded with their respective value.

- typeidx ::= x:u32 ⇒ x
- funcidx ::= x:u32 ⇒ x
- tableidx ::= x:u32 ⇒ x
- memidx ::= x:u32 ⇒ x
- globalidx ::= x:u32 ⇒ x
- localidx ::= x:u32 ⇒ x
- labelidx ::= l:u32 ⇒ l
5.5.2 Sections

Each section consists of

- a one-byte section *id*,
- the \( u32 \) *size* of the contents, in bytes,
- the actual *contents*, whose structure is depended on the section *id*.

Every section is optional; an omitted section is equivalent to the section being present with empty contents.

The following parameterized grammar rule defines the generic structure of a section with id \( N \) and contents described by the grammar \( B \).

\[
\text{section}_N(B) ::= N:\text{byte} \; \text{size:}u32 \; \text{cont:B} \Rightarrow \text{cont} \; \text{if} \; \text{size} = |B| \|
\]

\[
\Rightarrow \epsilon
\]

For most sections, the contents \( B \) encodes a *vector*. In these cases, the empty result \( \epsilon \) is interpreted as the empty vector.

**Note:** Other than for unknown custom sections, the *size* is not required for decoding, but can be used to skip sections when navigating through a binary. The module is malformed if the size does not match the length of the binary contents \( B \).

The following section ids are used:

<table>
<thead>
<tr>
<th>Id</th>
<th>Section</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>custom section</td>
</tr>
<tr>
<td>1</td>
<td>type section</td>
</tr>
<tr>
<td>2</td>
<td>import section</td>
</tr>
<tr>
<td>3</td>
<td>function section</td>
</tr>
<tr>
<td>4</td>
<td>table section</td>
</tr>
<tr>
<td>5</td>
<td>memory section</td>
</tr>
<tr>
<td>6</td>
<td>global section</td>
</tr>
<tr>
<td>7</td>
<td>export section</td>
</tr>
<tr>
<td>8</td>
<td>start section</td>
</tr>
<tr>
<td>9</td>
<td>element section</td>
</tr>
<tr>
<td>10</td>
<td>code section</td>
</tr>
<tr>
<td>11</td>
<td>data section</td>
</tr>
</tbody>
</table>

5.5.3 Custom Section

*Custom sections* have the id 0. They are intended to be used for debugging information or third-party extensions, and are ignored by the WebAssembly semantics. Their contents consist of a *name* further identifying the custom section, followed by an uninterpreted sequence of bytes for custom use.

\[
\text{customsec} ::= \text{section}_0(\text{custom})
\]

\[
\text{custom} ::= \text{name byte}^* \]

**Note:** If an implementation interprets the contents of a custom section, then errors in that contents, or the placement of the section, must not invalidate the module.
5.5.4 Type Section

The type section has the id 1. It decodes into a vector of function types that represent the types component of a module.

\[
\text{typesec ::= } ft^*:\text{section}1(\text{vec(functype)}) \Rightarrow ft^*
\]

5.5.5 Import Section

The import section has the id 2. It decodes into a vector of imports that represent the imports component of a module.

\[
\begin{align*}
\text{importsec ::= } & \text{im}^*:\text{section}2(\text{vec(import)}) \Rightarrow im^* \\
\text{import} ::= & \text{mod}:\text{name }nm:\text{name }d:\text{importdesc} \Rightarrow \{\text{module mod, name nm, desc d}\} \\
\text{importdesc} ::= & 0\times00 \text{x}:\text{typeidx} \Rightarrow \text{func }x \\
& | 0\times01 \text{tt}:\text{tabletype} \Rightarrow \text{table tt} \\
& | 0\times02 \text{mt}:\text{memtype} \Rightarrow \text{mem mt} \\
& | 0\times03 \text{gt}:\text{globaltype} \Rightarrow \text{global gt}
\end{align*}
\]

5.5.6 Function Section

The function section has the id 3. It decodes into a vector of type indices that represent the type fields of the functions in the funcs component of a module. The locals and body fields of the respective functions are encoded separately in the code section.

\[
\text{funcsec ::= } x^*:\text{section}3(\text{vec(typeidx)}) \Rightarrow x^*
\]

5.5.7 Table Section

The table section has the id 4. It decodes into a vector of tables that represent the tables component of a module.

\[
\begin{align*}
\text{tablesec ::= } & \text{tab}^*:\text{section}4(\text{vec(table)}) \Rightarrow \text{tab}^* \\
\text{table} ::= & \text{tt}:\text{tabletype} \Rightarrow \{\text{type tt}\}
\end{align*}
\]

5.5.8 Memory Section

The memory section has the id 5. It decodes into a vector of memories that represent the mems component of a module.

\[
\begin{align*}
\text{memsec ::= } & \text{mem}^*:\text{section}5(\text{vec(mem)}) \Rightarrow \text{mem}^* \\
\text{mem} ::= & \text{mt}:\text{memtype} \Rightarrow \{\text{type mt}\}
\end{align*}
\]

5.5.9 Global Section

The global section has the id 6. It decodes into a vector of globals that represent the globals component of a module.

\[
\begin{align*}
\text{globalsec ::= } & \text{glob}^*:\text{section}6(\text{vec(global)}) \Rightarrow \text{glob}^* \\
\text{global} ::= & \text{gt}:\text{globaltype }e:\text{expr} \Rightarrow \{\text{type gt, init e}\}
\end{align*}
\]
5.5.10 Export Section

The export section has the id 7. It decodes into a vector of exports that represent the exports component of a module.

\[
\text{exportsec ::= } \text{ex}^*:\text{section7}(\text{vec export}) \Rightarrow \text{ex}^*
\]
\[
\text{export ::= nm:}\text{name d:exportdesc} \Rightarrow \{\text{name nm, desc d}\}
\]
\[
\text{exportdesc ::= } 0x00 x:funcidx \Rightarrow \text{func x}
\]
\[
| 0x01 x:tableidx \Rightarrow \text{table x}
\]
\[
| 0x02 x:memidx \Rightarrow \text{mem x}
\]
\[
| 0x03 x:globalidx \Rightarrow \text{global x}
\]

5.5.11 Start Section

The start section has the id 8. It decodes into an optional start function that represents the start component of a module.

\[
\text{startsec ::= } \text{st?}:\text{section8}(\text{start}) \Rightarrow \text{st?}
\]
\[
\text{start ::= x:funcidx} \Rightarrow \{\text{func x}\}
\]

5.5.12 Element Section

The element section has the id 9. It decodes into a vector of element segments that represent the elem component of a module.

\[
\text{elemsec ::= } \text{seg*:section9}(\text{vec elem}) \Rightarrow \text{seg}
\]
\[
\text{elem ::= x:tableidx e:expr y*:vec(funcidx)} \Rightarrow \{\text{table x, offset e, init y*}\}
\]

5.5.13 Code Section

The code section has the id 10. It decodes into a vector of code entries that are pairs of value type vectors and expressions. They represent the locals and body field of the functions in the \text{funcs} component of a module. The type fields of the respective functions are encoded separately in the function section.

The encoding of each code entry consists of
- the \text{u32 size} of the function code in bytes,
- the actual function code, which in turn consists of
  - the declaration of locals,
  - the function body as an expression.

Local declarations are compressed into a vector whose entries consist of
- a \text{u32 count},
- a value type,

denoting \text{count} locals of the same value type.

\[
\text{codesec ::= } \text{code*:section10}(\text{vec code}) \Rightarrow \text{code*}
\]
\[
\text{code ::= size:u32 code:func} \Rightarrow \text{code} \text{ if size = ||func||}
\]
\[
\text{func ::= (t\*)*:vec(locals) e:expr} \Rightarrow \text{concat((t\*)*, e')} \text{ if } ||\text{concat((t\*)*)} < 2^{32}
\]
\[
\text{locals ::= n:u32 t:valtype} \Rightarrow t^n
\]
Here, *code* ranges over pairs \((\text{valtype}\,*, \,\text{expr})\). The meta function \(\text{concat}(\,^*(t^*)\,)\) concatenates all sequences \(t^*_i\) in \(\,^*(t^*)\). Any code for which the length of the resulting sequence is out of bounds of the maximum size of a *vector* is malformed.

**Note:** Like with *sections*, the code *size* is not needed for decoding, but can be used to skip functions when navigating through a binary. The module is malformed if a size does not match the length of the respective function code.

### 5.5.14 Data Section

The data section has the id 11. It decodes into a vector of *data segments* that represent the *data* component of a module.

\[
\begin{align*}
\text{datasec} &::= \text{seg}\,^*:\text{section}_{11}(\text{vec}(\text{data})) \Rightarrow \text{seg} \\
\text{data} &::= \text{x}\,\text{memidx} \,\text{e}\,\text{expr} \,\text{b}\,^*:\text{vec}(\text{byte}) \Rightarrow \{\text{data } x, \text{offset } e, \text{init } b^*\}
\end{align*}
\]

### 5.5.15 Modules

The encoding of a *module* starts with a preamble containing a 4-byte magic number (the string ‘\(\backslash 0asm\)’) and a version field. The current version of the WebAssembly binary format is 1.

The preamble is followed by a sequence of *sections*. *Custom sections* may be inserted at any place in this sequence, while other sections must occur at most once and in the prescribed order. All sections can be empty. The lengths
of vectors produced by the (possibly empty) function and code section must match up.

\[
\begin{align*}
\text{magic} & ::= 0x00 0x61 0x73 0x6D \\
\text{version} & ::= 0x01 0x00 0x00 0x00 \\
\text{module} & ::= \text{magic} \\
& \quad \text{version} \\
& \quad \text{customsec}^* \\
& \quad \text{functype}^*:\text{typesec} \\
& \quad \text{customsec}^* \\
& \quad \text{import}^*:\text{importsec} \\
& \quad \text{customsec}^* \\
& \quad \text{typeid}^*:\text{funcsec} \\
& \quad \text{customsec}^* \\
& \quad \text{table}^*:\text{tablesec} \\
& \quad \text{customsec}^* \\
& \quad \text{mem}^*:\text{memsec} \\
& \quad \text{customsec}^* \\
& \quad \text{global}^*:\text{globalsec} \\
& \quad \text{customsec}^* \\
& \quad \text{export}^*:\text{exportsec} \\
& \quad \text{customsec}^* \\
& \quad \text{start}^*:\text{startsec} \\
& \quad \text{customsec}^* \\
& \quad \text{elem}^*:\text{elemsec} \\
& \quad \text{customsec}^* \\
& \quad \text{code}^*:\text{codesec} \\
& \quad \text{customsec}^* \\
& \quad \text{data}^*:\text{datasec} \\
\text{customsec}^* & \Rightarrow \{ \text{types functype}^*, \\
& \quad \text{funcs func}^n, \\
& \quad \text{tables table}^*, \\
& \quad \text{mems mem}^*, \\
& \quad \text{globals global}^*, \\
& \quad \text{elem elem}^*, \\
& \quad \text{data data}^*, \\
& \quad \text{start start}^*, \\
& \quad \text{imports import}^*, \\
& \quad \text{exports export}^* \} \\
\end{align*}
\]

where for each \( t^*_i, e_i \) in \( \text{code}^n \),

\[\text{func}^n[i] = \{ \text{typeid}^n[i], \text{locals} t^*_i, \text{body} e_i \}\]

**Note:** The version of the WebAssembly binary format may increase in the future if backward-incompatible changes have to be made to the format. However, such changes are expected to occur very infrequently, if ever. The binary format is intended to be forward-compatible, such that future extensions can be made without incrementing its version.
CHAPTER 6

Text Format

6.1 Conventions

The textual format for WebAssembly modules is a rendering of their abstract syntax into S-expressions. Like the binary format, the text format is defined by an attribute grammar. A text string is a well-formed description of a module if and only if it is generated by the grammar. Each production of this grammar has at most one synthesized attribute: the abstract syntax that the respective character sequence expresses. Thus, the attribute grammar implicitly defines a parsing function. Some productions also take a context as an inherited attribute that records bound identifiers.

Except for a few exceptions, the core of the text grammar closely mirrors the grammar of the abstract syntax. However, it also defines a number of abbreviations that are “syntactic sugar” over the core syntax.

The recommended extension for files containing WebAssembly modules in text format is “.wat”. Files with this extension are assumed to be encoded in UTF-8, as per Unicode (Section 2.5).

6.1.1 Grammar

The following conventions are adopted in defining grammar rules of the text format. They mirror the conventions used for abstract syntax and for the binary format. In order to distinguish symbols of the textual syntax from symbols of the abstract syntax, typewriter font is adopted for the former.

- Terminal symbols are either literal strings of characters enclosed in quotes or expressed as Unicode code points: ‘module’, U+0A. (All characters written literally are unambiguously drawn from the 7-bit ASCII subset of Unicode.)

- Nonterminal symbols are written in typewriter font: valtype, instr.

- \( T^n \) is a sequence of \( n \geq 0 \) iterations of \( T \).

- \( T^* \) is a possibly empty sequence of iterations of \( T \). (This is a shorthand for \( T^n \) used where \( n \) is not relevant.)

- \( T^+ \) is a sequence of one or more iterations of \( T \). (This is a shorthand for \( T^n \) where \( n \geq 1 \).)

- \( T^? \) is an optional occurrence of \( T \). (This is a shorthand for \( T^n \) where \( n \leq 1 \).)

---

36 http://www.unicode.org/versions/latest/
37 http://www.unicode.org/versions/latest/
38 http://webstore.ansi.org/RecordDetail.aspx?sku=INCITS+-+4-1986%5bR2012%5d
• $x: T$ denotes the same language as the nonterminal $T$, but also binds the variable $x$ to the attribute synthesized for $T$.

• Productions are written $\text{sym} ::= T_1 \Rightarrow A_1 \mid \ldots \mid T_n \Rightarrow A_n$, where each $A_i$ is the attribute that is synthesized for $\text{sym}$ in the given case, usually from attribute variables bound in $T_i$.

• Some productions are augmented by side conditions in parentheses, which restrict the applicability of the production. They provide a shorthand for a combinatorial expansion of the production into many separate cases.

• A distinction is made between lexical and syntactic productions. For the latter, arbitrary white space is allowed in any place where the grammar contains spaces. The productions defining lexical syntax and the syntax of values are considered lexical, all others are syntactic.

Note: For example, the textual grammar for value types is given as follows:

\[
\text{valtype} ::= \text{'i32'} \Rightarrow \text{i32} \\
\mid \text{'i64'} \Rightarrow \text{i64} \\
\mid \text{'f32'} \Rightarrow \text{f32} \\
\mid \text{'f64'} \Rightarrow \text{f64}
\]

The textual grammar for limits is defined as follows:

\[
\text{limits} ::= n:u32 \Rightarrow \{\text{min } n, \text{max } \epsilon\} \\
\mid n:u32 \ m:u32 \Rightarrow \{\text{min } n, \text{max } m\}
\]

The variables $n$ and $m$ name the attributes of the respective $u32$ nonterminals, which in this case are the actual unsigned integers those parse into. The attribute of the complete production then is the abstract syntax for the limit, expressed in terms of the former values.

### 6.1.2 Abbreviations

In addition to the core grammar, which corresponds directly to the abstract syntax, the textual syntax also defines a number of abbreviations that can be used for convenience and readability.

Abbreviations are defined by rewrite rules specifying their expansion into the core syntax:

\[
\text{abbreviation syntax} \equiv \text{expanded syntax}
\]

These expansions are assumed to be applied, recursively and in order of appearance, before applying the core grammar rules to construct the abstract syntax.

### 6.1.3 Contexts

The text format allows the use of symbolic identifiers in place of indices. To resolve these identifiers into concrete indices, some grammar production are indexed by an identifier context $I$ as a synthesized attribute that records the declared identifiers in each index space. In addition, the context records the types defined in the module, so that parameter indices can be computed for functions.

It is convenient to define identifier contexts as records $I$ with abstract syntax as follows:

\[
I ::= \{\text{types} \ (\text{id}^\ast)^\ast, \text{funcs} \ (\text{id}^\ast)^\ast, \text{tables} \ (\text{id}^\ast)^\ast, \text{mems} \ (\text{id}^\ast)^\ast, \text{globals} \ (\text{id}^\ast)^\ast, \text{locals} \ (\text{id}^\ast)^\ast, \text{labels} \ (\text{id}^\ast)^\ast, \text{typedefs} \ \text{functype}\}
\]
For each index space, such a context contains the list of identifiers assigned to the defined indices. Unnamed indices are associated with empty (ε) entries in these lists.

An identifier context is well-formed if no index space contains duplicate identifiers.

Conventions

To avoid unnecessary clutter, empty components are omitted when writing out identifier contexts. For example, the record {} is shorthand for an identifier context whose components are all empty.

6.1.4 Vectors

Vectors are written as plain sequences, but with a restriction on the length of these sequence.

\[ \text{vec}(A) ::= (x:A)^n \Rightarrow x^n \quad (\text{if } n < 2^{32}) \]

6.2 Lexical Format

6.2.1 Characters

The text format assigns meaning to source text, which consists of a sequence of characters. Characters are assumed to be represented as valid Unicode\(^\text{39}\) (Section 2.4) code points.

\[
\begin{align*}
\text{source} & ::= \text{char}^* \\
\text{char} & ::= \text{U+00} | \ldots | \text{U+D7FF} | \text{U+E000} | \ldots | \text{U+10FFFF}
\end{align*}
\]

Note: While source text may contain any Unicode character in comments or string literals, the rest of the grammar is formed exclusively from the characters supported by the 7-bit ASCII\(^\text{40}\) subset of Unicode.

6.2.2 Tokens

The character stream in the source text is divided, from left to right, into a sequence of tokens, as defined by the following grammar.

\[
\begin{align*}
\text{token} & ::= \text{keyword} | \text{uN} | \text{sN} | \text{fN} | \text{string} | \text{id} | '(' | ')' | \text{reserved} \\
\text{keyword} & ::= ('a' | \ldots | 'z') \text{idchar}^* \quad (\text{if occurring as a literal terminal in the grammar}) \\
\text{reserved} & ::= \text{idchar}^+
\end{align*}
\]

Tokens are formed from the input character stream according to the longest match rule. That is, the next token always consists of the longest possible sequence of characters that is recognized by the above lexical grammar. Tokens can be separated by white space, but except for strings, they cannot themselves contain whitespace.

The set of keyword tokens is defined implicitly, by all occurrences of a terminal symbol in literal form, such as ‘keyword’, in a syntactic production of this chapter.

Any token that does not fall into any of the other categories is considered reserved, and cannot occur in source text.

Note: The effect of defining the set of reserved tokens is that all tokens must be separated by either parentheses or white space. For example, ‘0$\alpha’ is a single reserved token. Consequently, it is not recognized as two separate

\(^{39}\) http://www.unicode.org/versions/latest/

\(^{40}\) http://webstore.ansi.org/RecordDetail.aspx?sku=INCTS+4-1986%5bR2012%5d
tokens ‘0’ and ‘$x’ but instead disallowed. This property of tokenization is not affected by the fact that the definition of reserved tokens overlaps with other token classes.

6.2.3 White Space

White space is any sequence of literal space characters, formatting characters, or comments. The allowed formatting characters correspond to a subset of the ASCII format effectors, namely, horizontal tabulation (U+09), line feed (U+0A), and carriage return (U+0D).

\[
\text{space} ::= (' ' | \text{format} | \text{comment})^* \\
\text{format} ::= \text{U+09} | \text{U+0A} | \text{U+0D}
\]

The only relevance of white space is to separate tokens. It is otherwise ignored.

6.2.4 Comments

A comment can either be a line comment, started with a double semicolon ‘;;’ and extending to the end of the line, or a block comment, enclosed in delimiters ‘(‘...’’)’. Block comments can be nested.

\[
\text{comment} ::= \text{linecomment} | \text{blockcomment} \\
\text{linecomment} ::= ‘;;’ \text{linechar}^* (\text{U+0A} | \text{eof}) \\
\text{linechar} ::= \text{c:char} \quad \text{(if} \; c \neq \text{U+0A)} \\
\text{blockcomment} ::= ‘(‘ \text{blockchar}^* ‘;)’ \\
\text{blockchar} ::= \text{c:char} \quad \text{(if} \; c \neq ‘;’ \quad \text{and} \; c \neq ‘(‘)’ \\
| ‘(‘ \quad \text{(if the next character is not ‘)’)} \\
| ‘(‘ \quad \text{(if the next character is not ‘;’) }
| \text{blockcomment}
\]

Here, the pseudo token \text{eof} indicates the end of the input. The look-ahead restrictions on the productions for \text{blockchar} disambiguate the grammar such that only well-bracketed uses of block comment delimiters are allowed.

\textbf{Note:} Any formatting and control characters are allowed inside comments.

6.3 Values

The grammar productions in this section define lexical syntax, hence no white space is allowed.

6.3.1 Integers

All integers can be written in either decimal or hexadecimal notation. In both cases, digits can optionally be separated by underscores.

\[
\text{sign} ::= ε \Rightarrow + | ‘+’ ⇒ + | ‘-’ ⇒ - \\
\text{digit} ::= ‘0’ ⇒ 0 | ... | ‘9’ ⇒ 9 \\
\text{hexdigit} ::= d:digit ⇒ d \\
| ‘A’ ⇒ 10 | ... | ‘F’ ⇒ 15 \\
| ‘a’ ⇒ 10 | ... | ‘f’ ⇒ 15 \\
\text{num} ::= d:digit \quad \Rightarrow d \\
| n:num ‘_’ d:digit \quad ⇒ 10 \cdot n + d \\
\text{hexnum} ::= h:hexdigit \quad \Rightarrow h \\
| n:hexnum ‘_’ h:hexdigit \quad ⇒ 16 \cdot n + h
\]

http://webstore.ansi.org/RecordDetail.aspx?sku=INCITS+4-1986%5bR2012%5d
The allowed syntax for integer literals depends on size and signedness. Moreover, their value must lie within the range of the respective type.

\[
\begin{align*}
\text{uN} & ::= \text{n: num} \quad \Rightarrow \text{n} \quad (\text{if } n < 2^N) \\
& \quad | \quad \text{’0x’ n: hexnum} \quad \Rightarrow \text{n} \quad (\text{if } n < 2^N) \\
\text{sN} & ::= \pm\text{: sign n: num} \quad \Rightarrow \pm\text{n} \quad (\text{if } -2^{N-1} \leq \pm\text{n} < 2^{N-1}) \\
& \quad | \quad \pm\text{: sign ’0x’ n: hexnum} \quad \Rightarrow \pm\text{n} \quad (\text{if } -2^{N-1} \leq \pm\text{n} < 2^{N-1})
\end{align*}
\]

Uninterpreted integers can be written as either signed or unsigned, and are normalized to unsigned in the abstract syntax.

\[
\text{iN} ::= \text{uN} \Rightarrow \text{n} \\
& \quad | \quad \text{i:sN} \Rightarrow \text{n} \quad (\text{if } i = \text{signed(n)})
\]

### 6.3.2 Floating-Point

Floating-point values can be represented in either decimal or hexadecimal notation.

\[
\begin{align*}
\text{frac} & ::= \epsilon \Rightarrow 0 \\
& \quad | \quad \text{d: digit q: frac} \Rightarrow (d + q)/10 \\
& \quad | \quad \text{d: digit ‘_’ p: digit q: frac} \Rightarrow (d + (p + q)/10)/10 \\
\text{hexfrac} & ::= \epsilon \Rightarrow 0 \\
& \quad | \quad \text{h: hexdigit q: hexfrac} \Rightarrow (h + q)/16 \\
& \quad | \quad \text{h: hexdigit ‘_’ p: hexdigit q: hexfrac} \Rightarrow (h + (p + q)/16)/16 \\
\text{float} & ::= \text{p: num ‘.’ q: frac} \Rightarrow p + q \\
& \quad | \quad \text{p: num (’E’ | ’e’) \pm: sign e: num} \Rightarrow p \cdot 10^\pm e \\
& \quad | \quad \text{p: num ‘.’ q: frac (’E’ | ’e’) \pm: sign e: num} \Rightarrow (p + q) \cdot 10^\pm e \\
\text{hexfloat} & ::= \text{’0x’ p: hexnum ‘.’ q: hexfrac} \Rightarrow p + q \\
& \quad | \quad \text{’0x’ p: hexnum (’P’ | ’p’) \pm: sign e: num} \Rightarrow p \cdot 2^\pm e \\
& \quad | \quad \text{’0x’ p: hexnum ‘.’ q: hexfrac (’P’ | ’p’) \pm: sign e: num} \Rightarrow (p + q) \cdot 2^\pm e
\end{align*}
\]

The value of a literal must not lie outside the representable range of the corresponding IEEE 754-2008\(^{42}\) type (that is, a numeric value must not overflow to ±infinity), but it may be rounded to the nearest representable value.

**Note:** Rounding can be prevented by using hexadecimal notation with no more significant bits than supported by the required type.

Floating-point values may also be written as constants for *infinity* or *canonical NaN (not a number)*. Furthermore, arbitrary NaN values may be expressed by providing an explicit payload value.

\[
\begin{align*}
\text{fN} & ::= \pm\text{: sign z: fNmag} \Rightarrow \pm z \\
\text{fNmag} & ::= \text{z: float} \Rightarrow \text{float}_N(z) \quad (\text{if } \text{float}_N(z) \neq \pm\infty) \\
& \quad | \quad \text{z: hexfloat} \Rightarrow \text{float}_N(z) \quad (\text{if } \text{float}_N(z) \neq \pm\infty) \\
& \quad | \quad \text{’inf’} \Rightarrow \infty \\
& \quad | \quad \text{’nan’} \Rightarrow \text{nan}(2^{\text{signif}(N)-1}) \\
& \quad | \quad \text{’nan:0x’ n: hexnum} \Rightarrow \text{nan}(n) \quad (1 \leq n < 2^{\text{signif}(N)})
\end{align*}
\]

### 6.3.3 Strings

Strings denote sequences of bytes that can represent both textual and binary data. They are enclosed in quotation marks and may contain any character other than ASCII\(^{43}\) control characters, quotation marks (""), or backslash


WebAssembly Specification, Release 1.0

(string), except when expressed with an escape sequence.

```
string ::= "" (b:stringelem)* "" ⇒ concat((b)*) (if |concat((b)*)| < 2\(^{32}\))
stringelem ::= c:stringchar ⇒ utf8(c)
  | \ n:hexdigit m:hexdigit ⇒ 16 ⋅ n + m
```

Each character in a string literal represents the byte sequence corresponding to its UTF-8 Unicode44 (Section 2.5) encoding, except for hexadecimal escape sequences \(\backslash hh\), which represent raw bytes of the respective value.

```
stringchar ::= c:char ⇒ c (if c ≥ U+20 ∧ c ≠ U+7F ∧ c ≠ ‘\’)
  | ‘t’ ⇒ U+09
  | ‘n’ ⇒ U+0A
  | ‘r’ ⇒ U+0D
  | ‘u’ ⇒ U+0D
  | ‘u‘ n:hexnum ‘r’ ⇒ U+(n) (if n < 0xD800 ∨ 0xE000 ≤ n < 0x110000)
```

### 6.3.4 Names

*Names* are strings denoting a literal character sequence. A name string must form a valid UTF-8 encoding as defined by Unicode45 (Section 2.5) and is interpreted as a string of Unicode code points.

```
name ::= b*:string ⇒ c* (if b* = utf8(c*))
```

**Note:** Presuming the source text is itself encoded correctly, strings that do not contain any uses of hexadecimal byte escapes are always valid names.

### 6.3.5 Identifiers

*Indices* can be given in both numeric and symbolic form. Symbolic *identifiers* that stand in lieu of indices start with ‘$’, followed by any sequence of printable ASCII46 characters that does not contain a space, quotation mark, comma, semicolon, or bracket.

```
id ::= ‘$’ idchar+  
idchar ::= ‘0’ | ... | ‘9’  
  | ‘A’ | ... | ‘Z’  
  | ‘a’ | ... | ‘z’  
  | ‘!’ | ‘#’ | ‘$’ | ‘%’ | ‘&’ | ‘‘’ | ‘*’ | ‘+’ | ‘=’ | ‘?’ | ‘@’ | ‘\’ | ‘`’ | ‘^’ | ‘_’ | ‘`’ | ‘~’ |
```

**Conventions**

The expansion rules of some abbreviations require insertion of a *fresh* identifier. That may be any syntactically valid identifier that does not already occur in the given source text.

44 http://www.unicode.org/versions/latest/  
45 http://www.unicode.org/versions/latest/  
46 http://webstore.ansi.org/RecordDetail.aspx?sku=INCITS+4-1986%5bR2012%5d
6.4 Types

6.4.1 Value Types

valtype ::= ‘i32’ ⇒ i32
  | ‘i64’ ⇒ i64
  | ‘f32’ ⇒ f32
  | ‘f64’ ⇒ f64

6.4.2 Result Types

resulttype ::= (t:result)? ⇒ [t]

Note: In future versions of WebAssembly, this scheme may be extended to support multiple results or more general result types.

6.4.3 Function Types

functype ::= (‘func’ t1:*func(param) t2:*func(result) ‘)’ ⇒ [t1] → [t2]
param ::= (‘param’ id’ t:valtype’) ⇒ t
result ::= (‘result’ t:valtype’) ⇒ t

Abbreviations

Multiple anonymous parameters or results may be combined into a single declaration:

‘(‘param’ valtype’)’ ≡ (‘(‘param’ valtype ’))
‘(‘result’ valtype’)’ ≡ (‘(‘result’ valtype ’))

6.4.4 Limits

limits ::= n:u32 ⇒ {min n, max n}
  | n:u32 m:u32 ⇒ {min n, max m}

6.4.5 Memory Types

memtype ::= lim:limits ⇒ lim

6.4.6 Table Types

tabletype ::= lim:limits et:elemtype ⇒ lim et
  elmentype ::= ‘anyfunc’ ⇒ anyfunc

Note: Additional element types may be introduced in future versions of WebAssembly.
6.4.7 Global Types

\[
\text{globaltype ::= } t : \text{valtype} \Rightarrow \text{const } t \\
\text{ | } (\text{`mut' } t : \text{valtype})' \Rightarrow \text{var } t
\]

6.5 Instructions

Instructions are syntactically distinguished into plain and structured instructions.

\[
\text{instr}_I ::= \text{in:plaininstr}_I \Rightarrow \text{in} \\
\text{ | in:blockinstr}_I \Rightarrow \text{in}
\]

In addition, as a syntactic abbreviation, instructions can be written as S-expressions in folded form, to group them visually.

6.5.1 Labels

Structured control instructions can be annotated with a symbolic label identifier. They are the only symbolic identifiers that can be bound locally in an instruction sequence. The following grammar handles the corresponding update to the identifier context by composing the context with an additional label entry.

\[
\text{label}_I ::= v:id \Rightarrow \{\text{labels } v\} \oplus I \quad \text{(if } v \notin I.\text{labels)} \\
\text{ | } \epsilon \Rightarrow \{\text{labels } \epsilon\} \oplus I
\]

Note: The new label entry is inserted at the beginning of the label list in the identifier context. This effectively shifts all existing labels up by one, mirroring the fact that control instructions are indexed relatively not absolutely.

6.5.2 Control Instructions

Structured control instructions can bind an optional symbolic label identifier. The same label identifier may optionally be repeated after the corresponding end and else pseudo instructions, to indicate the matching delimiters.

\[
\text{blockinstr}_I ::= \text{`block' } I':\text{label}_I \text{ rt:resulrtype } (\text{in:instr}_{I'})^* \text{`end' id}' \Rightarrow \text{block } rt \text{ in' end } \quad \text{(if } \text{id}' = \epsilon \lor \text{id}' = \text{label)} \\
\text{ | `loop' } I':\text{label}_I \text{ rt:resulrtype } (\text{in:instr}_{I'})^* \text{`end' id}' \Rightarrow \text{loop } rt \text{ in' end } \quad \text{(if } \text{id}' = \epsilon \lor \text{id}' = \text{label)} \\
\text{ | `if' } I':\text{label}_I \text{ rt:resulrtype } (\text{in1:instr}_{I'})^* \text{`else' id}'_1 (\text{in2:instr}_{I'})^* \text{`end' id}'_2 \Rightarrow \text{if } rt \text{ in1}' \text{else in2}' \text{end } \quad \text{(if } \text{id}'_1 = \epsilon \lor \text{id}'_1 = \text{label}, \text{id}'_2 = \epsilon \lor \text{id}'_2 = \text{label)}
\]

All other control instruction are represented verbatim.

\[
\text{plaininstr}_I ::= \text{`unreachable'} \Rightarrow \text{unreachable} \\
\text{ | `nop'} \Rightarrow \text{nop} \\
\text{ | `br' } l:\text{labelidx}_I \Rightarrow \text{br } l \\
\text{ | `br_if' } l:\text{labelidx}_I \Rightarrow \text{br_if } l \\
\text{ | `br_table' } l':\text{vec(labelidx}_I) \text{ } l_N:\text{labelidx}_I \Rightarrow \text{br_table } l' \text{ } l_N \\
\text{ | `return'} \Rightarrow \text{return} \\
\text{ | `call' } x:\text{funcidx}_I \Rightarrow \text{call } x \\
\text{ | `call_indirect' } x, l':\text{typeuse}_I \Rightarrow \text{call_indirect } x \quad \text{(if } l' = \{\})
\]

Note: The side condition stating that the identifier context \text{I'} must be empty in the rule for \text{call_indirect} enforces that no identifier can be bound in any \text{param} declaration appearing in the type annotation.
Abbreviations

The ‘else’ keyword of an ‘if’ instruction can be omitted if the following instruction sequence is empty.

\[
'\text{if label resulttype instr} '\text{end}' \equiv '\text{if label resulttype instr} '\text{else} '\text{end}'
\]

6.5.3 Parametric Instructions

\[
\text{plaininstr}_1 ::= \ldots
| \text{’drop’} \Rightarrow \text{drop}
| \text{’select’} \Rightarrow \text{select}
\]

6.5.4 Variable Instructions

\[
\text{plaininstr}_1 ::= \ldots
| \text{’get\_local’ } x:\text{localidx}_1 \Rightarrow \text{get\_local } x
| \text{’set\_local’ } x:\text{localidx}_1 \Rightarrow \text{set\_local } x
| \text{’tee\_local’ } x:\text{localidx}_1 \Rightarrow \text{tee\_local } x
| \text{’get\_global’ } x:\text{globalidx}_1 \Rightarrow \text{get\_global } x
| \text{’set\_global’ } x:\text{globalidx}_1 \Rightarrow \text{set\_global } x
\]

6.5.5 Memory Instructions

The offset and alignment immediates to memory instructions are optional. The offset defaults to 0, the alignment to the storage size of the respective memory access, which is its natural alignment. Lexically, an offset or align
phrase is considered a single \textit{keyword token}, so no \textit{white space} is allowed around the ‘=’.

\[
\begin{align*}
\text{memarg}_N & ::= \ o: \text{offset} \ o: \text{align}_N \quad \Rightarrow \ \{ \text{align} \ n, \ \text{offset} \ o \} \quad \text{(if} \ a = 2^n) \\
\text{offset} & ::= \ 'o: \text{offset}=\'o:u32 \quad \Rightarrow \ o \\
\text{align}_N & ::= \ 'a: \text{align}=\'a:u32 \quad \Rightarrow \ a \\
\text{plaininstr}_j & ::= \ldots \\
\end{align*}
\]

\[
\begin{align*}
\text{plaininstr}_j & ::= \ldots \\
\text{store32} & o: \text{memarg}_4 \quad \Rightarrow \ i32.\text{load} \ m \\
\text{store8} & o: \text{memarg}_4 \quad \Rightarrow \ i64.\text{load} \ m \\
\text{store16} & o: \text{memarg}_4 \quad \Rightarrow \ f32.\text{load} \ m \\
\text{store8} & o: \text{memarg}_4 \quad \Rightarrow \ f64.\text{load} \ m \\
\text{load32} & o: \text{memarg}_4 \quad \Rightarrow \ i32.\text{load8}_s \ m \\
\text{store16} & o: \text{memarg}_4 \quad \Rightarrow \ i32.\text{load8}_u \ m \\
\text{load32} & o: \text{memarg}_4 \quad \Rightarrow \ i32.\text{load16}_s \ m \\
\text{store16} & o: \text{memarg}_4 \quad \Rightarrow \ i32.\text{load16}_u \ m \\
\text{load32} & o: \text{memarg}_4 \quad \Rightarrow \ i32.\text{load32}_s \ m \\
\text{store16} & o: \text{memarg}_4 \quad \Rightarrow \ i32.\text{load32}_u \ m \\
\text{store4} & o: \text{memarg}_4 \quad \Rightarrow \ f32.\text{load} \ m \\
\text{store8} & o: \text{memarg}_4 \quad \Rightarrow \ f64.\text{load} \ m \\
\text{store16} & o: \text{memarg}_4 \quad \Rightarrow \ i32.\text{store8} \ m \\
\text{store32} & o: \text{memarg}_4 \quad \Rightarrow \ i32.\text{store16} \ m \\
\text{load32} & o: \text{memarg}_4 \quad \Rightarrow \ i32.\text{store32} \ m \\
\text{store4} & o: \text{memarg}_4 \quad \Rightarrow \ memory.\text{size} \\
\text{store8} & o: \text{memarg}_4 \quad \Rightarrow \ memory.\text{grow} \\
\end{align*}
\]

6.5.6 Numeric Instructions

\[
\begin{align*}
\text{plaininstr}_j & ::= \ldots \\
\text{const32} & n:i32 \quad \Rightarrow \ i32.\text{const} \ n \\
\text{const64} & n:i64 \quad \Rightarrow \ i64.\text{const} \ n \\
\text{const32} & z:f32 \quad \Rightarrow \ f32.\text{const} \ z \\
\text{const64} & z:f64 \quad \Rightarrow \ f64.\text{const} \ z \\
\end{align*}
\]
| 'i32.clz'  ⇒ i32.clz  | 'i64.clz'  ⇒ i64.clz  |
| 'i32.ctz'  ⇒ i32.ctz  | 'i64.ctz'  ⇒ i64.ctz  |
| 'i32.popcnt'  ⇒ i32.popcnt  | 'i64.popcnt'  ⇒ i64.popcnt  |
| 'i32.add'  ⇒ i32.add  | 'i64.add'  ⇒ i64.add  |
| 'i32.sub'  ⇒ i32.sub  | 'i64.sub'  ⇒ i64.sub  |
| 'i32.mul'  ⇒ i32.mul  | 'i64.mul'  ⇒ i64.mul  |
| 'i32.div_s'  ⇒ i32.div_s  | 'i64.div_s'  ⇒ i64.div_s  |
| 'i32.div_u'  ⇒ i32.div_u  | 'i64.div_u'  ⇒ i64.div_u  |
| 'i32.rem_s'  ⇒ i32.rem_s  | 'i64.rem_s'  ⇒ i64.rem_s  |
| 'i32.rem_u'  ⇒ i32.rem_u  | 'i64.rem_u'  ⇒ i64.rem_u  |
| 'i32.and'  ⇒ i32.and  | 'i64.and'  ⇒ i64.and  |
| 'i32.or'  ⇒ i32.or  | 'i64.or'  ⇒ i64.or  |
| 'i32.xor'  ⇒ i32.xor  | 'i64.xor'  ⇒ i64.xor  |
| 'i32.shl'  ⇒ i32.shl  | 'i64.shl'  ⇒ i64.shl  |
| 'i32.shr_s'  ⇒ i32.shr_s  | 'i64.shr_s'  ⇒ i64.shr_s  |
| 'i32.shr_u'  ⇒ i32.shr_u  | 'i64.shr_u'  ⇒ i64.shr_u  |
| 'i32.rotl'  ⇒ i32.rotl  | 'i64.rotl'  ⇒ i64.rotl  |
| 'i32.rotr'  ⇒ i32.rotr  | 'i64.rotr'  ⇒ i64.rotr  |
| 'f32.abs'  ⇒ f32.abs  | 'f64.abs'  ⇒ f64.abs  |
| 'f32.neg'  ⇒ f32.neg  | 'f64.neg'  ⇒ f64.neg  |
| 'f32.ceil'  ⇒ f32.ceil  | 'f64.ceil'  ⇒ f64.ceil  |
| 'f32.floor'  ⇒ f32.floor  | 'f64.floor'  ⇒ f64.floor  |
| 'f32.trunc'  ⇒ f32.trunc  | 'f64.trunc'  ⇒ f64.trunc  |
| 'f32.nearest'  ⇒ f32.nearest  | 'f64.nearest'  ⇒ f64.nearest  |
| 'f32.sqrt'  ⇒ f32.sqrt  | 'f64.sqrt'  ⇒ f64.sqrt  |
| 'f32.add'  ⇒ f32.add  | 'f64.add'  ⇒ f64.add  |
| 'f32.sub'  ⇒ f32.sub  | 'f64.sub'  ⇒ f64.sub  |
| 'f32.mul'  ⇒ f32.mul  | 'f64.mul'  ⇒ f64.mul  |
| 'f32.div'  ⇒ f32.div  | 'f64.div'  ⇒ f64.div  |
| 'f32.min'  ⇒ f32.min  | 'f64.min'  ⇒ f64.min  |
| 'f32.max'  ⇒ f32.max  | 'f64.max'  ⇒ f64.max  |
| 'f32.copysign'  ⇒ f32.copysign  | 'f64.copysign'  ⇒ f64.copysign  |
| 'f64.abs'   | => f64.abs |
| 'f64.neg'   | => f64.neg |
| 'f64.ceil'  | => f64.ceil |
| 'f64.floor' | => f64.floor |
| 'f64.trunc' | => f64.trunc |
| 'f64.nearest' | => f64.nearest |
| 'f64.sqrt'  | => f64.sqrt |
| 'f64.add'   | => f64.add |
| 'f64.sub'   | => f64.sub |
| 'f64.mul'   | => f64.mul |
| 'f64.div'   | => f64.div |
| 'f64.min'   | => f64.min |
| 'f64.max'   | => f64.max |
| 'f64.copysign' | => f64.copysign |
| 'i32.eqz'   | => i32.eqz |
| 'i32.eq'    | => i32.eq |
| 'i32.ne'    | => i32.ne |
| 'i32.lt_s'  | => i32.lt_s |
| 'i32.lt_u'  | => i32.lt_u |
| 'i32.gt_s'  | => i32.gt_s |
| 'i32.gt_u'  | => i32.gt_u |
| 'i32.le_s'  | => i32.le_s |
| 'i32.le_u'  | => i32.le_u |
| 'i32.ge_s'  | => i32.ge_s |
| 'i32.ge_u'  | => i32.ge_u |
| 'i64.eqz'   | => i64.eqz |
| 'i64.eq'    | => i64.eq |
| 'i64.ne'    | => i64.ne |
| 'i64.lt_s'  | => i64.lt_s |
| 'i64.lt_u'  | => i64.lt_u |
| 'i64.gt_s'  | => i64.gt_s |
| 'i64.gt_u'  | => i64.gt_u |
| 'i64.le_s'  | => i64.le_s |
| 'i64.le_u'  | => i64.le_u |
| 'i64.ge_s'  | => i64.ge_s |
| 'i64.ge_u'  | => i64.ge_u |
| 'f32.eq'    | => f32.eq |
| 'f32.ne'    | => f32.ne |
| 'f32.lt'    | => f32.lt |
| 'f32.gt'    | => f32.gt |
| 'f32.le'    | => f32.le |
| 'f32.ge'    | => f32.ge |
| 'f64.eq'    | => f64.eq |
| 'f64.ne'    | => f64.ne |
| 'f64.lt'    | => f64.lt |
| 'f64.gt'    | => f64.gt |
| 'f64.le'    | => f64.le |
| 'f64.ge'    | => f64.ge |
6.5.7 Folded Instructions

Instructions can be written as S-expressions by grouping them into folded form. In that notation, an instruction is wrapped in parentheses and optionally includes nested folded instructions to indicate its operands.

In the case of block instructions, the folded form omits the ‘end’ delimiter. For if instructions, both branches have to be wrapped into nested S-expressions, headed by the keywords ‘then’ and ‘else’.

The set of all phrases defined by the following abbreviations recursively forms the auxiliary syntactic class foldedinstr. Such a folded instruction can appear anywhere a regular instruction can.

| (plaininstr foldedinstr*) | foldedinstr* plaininstr |
| (‘block’ label resulttype instr*) | ‘block’ label resulttype instr* ‘end’ |
| (‘loop’ label resulttype instr*) | ‘loop’ label resulttype instr* ‘end’ |
| (‘if’ label resulttype foldedinstr (‘then’ instr*) (‘else’ instr2)) | foldedinstr* ‘if’ label resulttype instr* ‘else’ (instr2) ‘end’ |

Note: For example, the instruction sequence

\[(\text{get\_local } \$x) (\text{i32\_const } 2) \text{i32\_add} (\text{i32\_const } 3) \text{i32\_mul}\]

can be folded into

\[(\text{i32\_mul} (\text{i32\_add} (\text{get\_local } \$x) (\text{i32\_const } 2)) (\text{i32\_const } 3))\]

Folded instructions are solely syntactic sugar, no additional syntactic or type-based checking is implied.
6.5.8 Expressions

Expressions are written as instruction sequences. No explicit 'end' keyword is included, since they only occur in bracketed positions.

\[
\text{expr} ::= (\text{in}:\text{instr})^* \Rightarrow \text{in}^* \text{end}
\]

6.6 Modules

6.6.1 Indices

Indices can be given either in raw numeric form or as symbolic identifiers when bound by a respective construct. Such identifiers are looked up in the suitable space of the identifier context \(I\).

\[
\begin{align*}
typeidx_I & ::= \ x:u32 \Rightarrow x \\
funcidx_I & ::= \ x:u32 \Rightarrow x \\
tableidx_I & ::= \ x:u32 \Rightarrow x \\
memidx_I & ::= \ x:u32 \Rightarrow x \\
globalidx_I & ::= \ x:u32 \Rightarrow x \\
localidx_I & ::= \ l:u32 \Rightarrow l \\
labelidx_I & ::= \ l:u32 \Rightarrow l
\end{align*}
\]

6.6.2 Types

Type definitions can bind a symbolic type identifier.

\[
\text{type} ::= (\text{\texttt{\char1t}}} \text{\texttt{type}} \ x \text{\texttt{:}} \text{typeidx}_I) \Rightarrow ft
\]

6.6.3 Type Uses

A type use is a reference to a type definition. It may optionally be augmented by explicit inlined parameter and result declarations. That allows binding symbolic identifiers to name the local indices of parameters. If inline declarations are given, then their types must match the referenced function type.

\[
\begin{align*}
typeuse_I & ::= (\text{\texttt{\char1t}}} \text{\texttt{type}} \ x: \text{typeidx}_I) \Rightarrow x, I' \\
\text{if } I \text{.typedefs}[x] = [t_1^*] \rightarrow [t_2^*] \land I' = \{\text{locals } e\}^n)
\end{align*}
\]

The synthesized attribute of a type use is a pair consisting of both the used type index and the updated identifier context including possible parameter identifiers. The following auxiliary function extracts optional identifiers from parameters:

\[
\text{id('param id ... ')} = \text{id}
\]
Note: Both productions overlap for the case that the function type is \([\cdot] \rightarrow [\cdot]\). However, in that case, they also produce the same results, so that the choice is immaterial.

The well-formedness condition on \(I\) ensures that the parameters do not contain duplicate identifier.

### Abbreviations

A typeuse may also be replaced entirely by inline parameter and result declarations. In that case, a type index is automatically inserted:

\[
(t_1:\text{param})^* (t_2:\text{result})^* \equiv \text{‘(‘type‘ \ x ‘)’ param* result*}
\]

where \(x\) is the smallest existing type index whose definition in the current module is the function type \([t_1] \rightarrow [t_2]\). If no such index exists, then a new type definition of the form

\[
\text{‘(‘type‘ ‘(‘func‘ param* result ‘)‘)’}
\]

is inserted at the end of the module.

Abbreviations are expanded in the order they appear, such that previously inserted type definitions are reused by consecutive expansions.

### 6.6.4 Imports

The descriptors in imports can bind a symbolic function, table, memory, or global identifier.

\[
\begin{align*}
\text{import}_I & \quad ::= \text{‘(‘import‘ mod.name nm:name d:importdesc}_I\ ‘)’ \\
& \quad \Rightarrow \{\text{module mod, name nm, desc d}\}
\end{align*}
\]

\[
\begin{align*}
\text{importdesc}_I & \quad ::= \text{‘(‘func‘ id? \ x, I’:typeuse_I ‘)’} & \quad \Rightarrow \text{func } x \\
& \quad | \text{‘(‘table‘ id? \ tt:tabletype ‘)’} & \quad \Rightarrow \text{table } tt \\
& \quad | \text{‘(‘memory‘ id? \ mt:memtype ‘)’} & \quad \Rightarrow \text{mem } mt \\
& \quad | \text{‘(‘global‘ id? \ gt:globaltype ‘)’} & \quad \Rightarrow \text{global } gt
\end{align*}
\]

### Abbreviations

As an abbreviation, imports may also be specified inline with function, table, memory, or global definitions; see the respective sections.

### 6.6.5 Functions

Function definitions can bind a symbolic function identifier, and local identifiers for its parameters and locals.

\[
\begin{align*}
\text{func}_I & \quad ::= \text{‘(‘func‘ id? \ x, I’:typeuse_I (t:local)* (in:instr_I)* ‘)’} \\
& \quad \Rightarrow \{\text{type } x, \text{locals } t^*, \text{body } in^* \} \text{ end} \\
& \quad \quad \text{ (if } I” = I’ \oplus \{\text{locals id(local)*}\} \text{ well-formed)}
\end{align*}
\]

\[
\text{local} ::= \text{‘(‘local‘ id? \ t:valtype ‘)’} \quad \Rightarrow \ t
\]

The definition of the local identifier context \(I”\) uses the following auxiliary function to extract optional identifiers from locals:

\[
\text{id(‘(‘local‘ id? \ldots ‘)‘)} = id^?
\]

Note: The well-formedness condition on \(I”\) ensures that parameters and locals do not contain duplicate identifiers.
Abbreviations

Multiple anonymous locals may be combined into a single declaration:

```
(( 'local' valtype ' ) ) ≡ (( 'local' valtype ' ) ')
```

Functions can be defined as imports or exports inline:

```
(( 'func' id? (('import' name1 name2 ')') typeuse ')')  
≡ (( 'import' name1 name2 ('func' id' typeuse ')') )
(( 'func' id? ('export' name ')') ... ')')  
≡ (( 'export' name ('func' id') ')') ('func' id' ... ')
  (if id' = id? \ne \epsilon \lor id' fresh)
```

The latter abbreviation can be applied repeatedly, with “…” containing another import or export.

6.6.6 Tables

Table definitions can bind a symbolic table identifier.

```
tableI ::= ('table' id tt:tabletype ') ⇒ {type tt}
```

Abbreviations

An element segment can be given inline with a table definition, in which case its offset is 0 and the limits of the table type are inferred from the length of the given segment:

```
(( 'table' id' element ( 'elem' x':vec(funcidx) ') ') ) ≡
(( 'table' id' n n elementtype ')') ('elem' id' ( 'i32.const' '0' ') vec(funcidx) ')')
  (if id' = id? \ne \epsilon \lor id' fresh)
```

Tables can be defined as imports or exports inline:

```
(( 'table' id' (('import' name1 name2 ')') tabletype ')')  
≡ (( 'import' name1 name2 ('table' id' tabletype ') ') )
(( 'table' id' (('export' name ')') ... ')')  
≡ (( 'export' name ('table' id') ')') ('table' id' ... ')
  (if id' = id? \ne \epsilon \lor id' fresh)
```

The latter abbreviation can be applied repeatedly, with “…” containing another import or export or an inline elements segment.

6.6.7 Memories

Memory definitions can bind a symbolic memory identifier.

```
memI ::= ('memory' id mt:memorytype ') ⇒ {type mt}
```
Abbreviations

A data segment can be given inline with a memory definition, in which case its offset is 0 the limits of the memory type are inferred from the length of the data, rounded up to page size:

\[
\text{'( 'memory' id' ('data' b'n: datastring') ')')} \equiv \\
\text{'( 'memory' id' m m ')')} \equiv \text{\texttt{('data' 'id' ('i32.const '0' ') datastring ')')
\]

(if id = id' \neq e \vee id' fresh, m = ceil(n/64Ki))

Memories can be defined as imports or exports inline:

\[
\text{'( 'memory' id' ('import' name1 name2 ') memtype ')')} \equiv \\
\text{'( 'import' name1 name2 ('memory' id' memtype ') ')}
\]

\[
\text{'( 'memory' id' ('export' name ') ... ')')} \equiv \\
\text{'( 'export' name ('memory' id' ') ')'} \equiv \text{\texttt{('memory' id' ... ')')
\]

(if id = id' \neq e \vee id' fresh)

The latter abbreviation can be applied repeatedly, with “...” containing another import or export or an inline data segment.

6.6.8 Globals

Global definitions can bind a symbolic global identifier.

\[
global \_i := \text{\texttt{('global' id' gt: globaltype e: expr ')')}} \Rightarrow \{ \text{type gt, init e} \}
\]

Abbreviations

Globals can be defined as imports or exports inline:

\[
\text{'( 'global' id' ('import' name1 name2 ') globaltype ')')} \equiv \\
\text{'( 'import' name1 name2 ('global' id' globaltype ') ')'}
\]

\[
\text{'( 'global' id' ('export' name ') ... ')')} \equiv \\
\text{'( 'export' name ('global' id' ') ')'} \equiv \text{\texttt{('global' id' ... ')')
\]

(if id = id' \neq e \vee id' fresh)

The latter abbreviation can be applied repeatedly, with “...” containing another import or export.

6.6.9 Exports

The syntax for exports mirrors their abstract syntax directly.

\[
\text{export}_i := \text{\texttt{('export' nm: name d: exportdesc ')')}} \Rightarrow \{ \text{name nm, desc d} \}
\]

\[
\text{exportdesc}_i := \text{\texttt{('func' x: funcidx ')')}} \Rightarrow \text{func x}
\]

| \text{\texttt{('table' x: tableidx ')')}} \Rightarrow \text{table x} |
| \text{\texttt{('memory' x: memidx ')')}} \Rightarrow \text{mem x} |
| \text{\texttt{('global' x: globalidx ')')}} \Rightarrow \text{global x} |

Abbreviations

As an abbreviation, exports may also be specified inline with function, table, memory, or global definitions; see the respective sections.
6.6.10 Start Function

A start function is defined in terms of its index.

\[
\text{start}_I \ ::= \ ('\text{start } x:funcidx_I ') \ \Rightarrow \ \{ \text{func } x \}
\]

**Note:** At most one start function may occur in a module, which is ensured by a suitable side condition on the module grammar.

6.6.11 Element Segments

Element segments allow for an optional table index to identify the table to initialize.

\[
\text{elem}_I \ ::= \ ('\text{elem } x:tableidx_I \ ('\text{offset } e:expr_I ') \ y:vec(funcidx_I ')') \ \Rightarrow \ \{ \text{table } x, \text{offset } e, \text{init } y^* \}
\]

**Note:** In the current version of WebAssembly, the only valid table index is 0 or a symbolic table identifier resolving to the same value.

**Abbreviations**

As an abbreviation, a single instruction may occur in place of the offset:

\[
\text{instr} \ \equiv \ ('\text{offset } \text{instr}')
\]

Also, the table index can be omitted, defaulting to 0.

\[
('\text{elem} ('\text{offset } \text{expr}_I ') \ldots ') \ \equiv \ ('\text{elem} 0 ('\text{offset } \text{expr}_I ') \ldots ')
\]

As another abbreviation, element segments may also be specified inline with table definitions; see the respective section.

6.6.12 Data Segments

Data segments allow for an optional memory index to identify the memory to initialize. The data is written as a string, which may be split up into a possibly empty sequence of individual string literals.

\[
\text{data}_I \ ::= \ ('\text{data } x:memidx_I \ ('\text{offset } e:expr_I ') \ b*:datastring ') \ \Rightarrow \ \{ \text{data } x', \text{offset } e, \text{init } b^* \}
\]

\[
datastring \ ::= \ (b*:string)^* \ \Rightarrow \ \text{concat}(b*)^*
\]

**Note:** In the current version of WebAssembly, the only valid memory index is 0 or a symbolic memory identifier resolving to the same value.

**Abbreviations**

As an abbreviation, a single instruction may occur in place of the offset:

\[
\text{instr} \ \equiv \ ('\text{offset } \text{instr}')
\]
Also, the memory index can be omitted, defaulting to 0.

\[
\left( ' \text{data} \left( ' \text{offset} \ expr_1 \right) \ldots \right) \equiv \left( ' \text{data} \ 0 \left( ' \text{offset} \ expr_1 \right) \ldots \right)
\]

As another abbreviation, data segments may also be specified inline with memory definitions; see the respective section.

### 6.6.13 Modules

A module consists of a sequence of fields that can occur in any order. All definitions and their respective bound identifiers scope over the entire module, including the text preceding them.

A module may optionally bind an identifier that names the module. The name serves a documentary role only.

**Note:** Tools may include the module name in the name section of the binary format.

```
module ::= \left( \text{module} \ 'id' \ (m:modulefield)* \right) \Rightarrow \bigoplus m^*
```

```
modulefield_f ::= ty:type \Rightarrow \{ types ty \}
  \mid im:import_f \Rightarrow \{ imports im \}
  \mid fn:func_f \Rightarrow \{ funcs fn \}
  \mid ta:table_f \Rightarrow \{ tables ta \}
  \mid me:mem_f \Rightarrow \{ mems me \}
  \mid gl:global_f \Rightarrow \{ globals gl \}
  \mid ex:export_f \Rightarrow \{ exports ex \}
  \mid st:start_f \Rightarrow \{ start st \}
  \mid el:elem_f \Rightarrow \{ elem el \}
  \mid da:data_f \Rightarrow \{ data da \}
```

The following restrictions are imposed on the composition of modules: \( m_1 \oplus m_2 \) is defined if and only if

- \( m_1.\text{start} = \epsilon \lor m_2.\text{start} = \epsilon \)
- \( m_1.\text{funcs} = m_1.\text{tables} = m_1.\text{mems} = m_1.\text{globals} = \epsilon \lor m_2.\text{imports} = \epsilon \)

**Note:** The first condition ensures that there is at most one start function. The second condition enforces that all imports must occur before any regular definition of a function, table, memory, or global, thereby maintaining the ordering of the respective index spaces.

The well-formedness condition on \( I \) in the grammar for module ensures that no namespace contains duplicate identifiers.

The definition of the initial identifier context \( I \) uses the following auxiliary definition which maps each relevant definition to a singular context with one (possibly empty) identifier:

\[
\begin{align*}
\text{idc}( \left( ' \text{type} \ 'id' \ ft:func-type \right) ) &= \{ \text{types (id')}\}, \text{typedefs ft} \\
\text{idc}( \left( ' \text{func} \ 'id' \ldots \right) ) &= \{ \text{funcs (id')}\} \\
\text{idc}( \left( ' \text{table} \ 'id' \ldots \right) ) &= \{ \text{tables (id')}\} \\
\text{idc}( \left( ' \text{memory} \ 'id' \ldots \right) ) &= \{ \text{mems (id')}\} \\
\text{idc}( \left( ' \text{global} \ 'id' \ldots \right) ) &= \{ \text{globals (id')}\} \\
\text{idc}( \left( ' \text{import} \ldots \left( ' \text{func} \ 'id' \ldots \right) \right) ) &= \{ \text{funcs (id')}\} \\
\text{idc}( \left( ' \text{import} \ldots \left( ' \text{table} \ 'id' \ldots \right) \right) ) &= \{ \text{tables (id')}\} \\
\text{idc}( \left( ' \text{import} \ldots \left( ' \text{memory} \ 'id' \ldots \right) \right) ) &= \{ \text{mems (id')}\} \\
\text{idc}( \left( ' \text{import} \ldots \left( ' \text{global} \ 'id' \ldots \right) \right) ) &= \{ \text{globals (id')}\} \\
\text{idc}( \left( ' \ldots \right) ) &= \{ \}
\end{align*}
\]
Abbreviations

In a source file, the toplevel (module ...) surrounding the module body may be omitted.

\[ \text{modulefield}^* \equiv \text{'(' module modulefield ')'} \]
7.1 Embedding

A WebAssembly implementation will typically be embedded into a host environment. An embedder implements the connection between such a host environment and the WebAssembly semantics as defined in the main body of this specification. An embedder is expected to interact with the semantics in well-defined ways.

This section defines a suitable interface to the WebAssembly semantics in the form of entry points through which an embedder can access it. The interface is intended to be complete, in the sense that an embedder does not need to reference other functional parts of the WebAssembly specification directly.

Note: On the other hand, an embedder does not need to provide the host environment with access to all functionality defined in this interface. For example, an implementation may not support parsing of the text format.

In the description of the embedder interface, syntactic classes from the abstract syntax and the runtime’s abstract machine are used as names for variables that range over the possible objects from that class. Hence, these syntactic classes can also be interpreted as types.

Failure of an interface operation is indicated by an auxiliary syntactic class:

\[ error ::= error \]

In addition to the error conditions specified explicitly in this section, implementations may also return errors when specific implementation limitations are reached.

Note: Errors are abstract and unspecific with this definition. Implementations can refine it to carry suitable classifications and diagnostic messages.

7.1.1 Store

\[ \text{init\_store}() : \text{store} \]

1. Return the empty \text{store}. 
```
init_store() = {funcs ϵ, mems ϵ, tables ϵ, globals ϵ}
```

### 7.1.2 Modules

\[
\text{decode\_module(byte\^*) : module | error}
\]

1. If there exists a derivation for the \texttt{byte} sequence \texttt{byte\^*} as a \texttt{module} according to the \texttt{binary grammar for modules}, yielding a \texttt{module} \texttt{m}, then return \texttt{m}.
2. Else, return \texttt{error}.

\[
\begin{align*}
\text{decode\_module(\texttt{b}\^*)} & = \texttt{m} & \text{(if} \texttt{module} \Rightarrow^* \texttt{m;b}\^*) \\
\text{decode\_module(\texttt{b}\^*)} & = \texttt{error} & \text{(otherwise)}
\end{align*}
\]

\[
\text{parse\_module(codepoint\^*) : module | error}
\]

1. If there exists a derivation for the \texttt{source codepoint} sequence \texttt{codepoint\^*} as a \texttt{module} according to the \texttt{text grammar for modules}, yielding a \texttt{module} \texttt{m}, then return \texttt{m}.
2. Else, return \texttt{error}.

\[
\begin{align*}
\text{parse\_module(\texttt{c}\^*)} & = \texttt{m} & \text{(if} \texttt{module} \Rightarrow^* \texttt{m;c}\^*) \\
\text{parse\_module(\texttt{c}\^*)} & = \texttt{error} & \text{(otherwise)}
\end{align*}
\]

\[
\text{validate\_module(module) : error*}
\]

1. If \texttt{module} is \texttt{valid}, then return nothing.
2. Else, return \texttt{error}.

\[
\begin{align*}
\text{validate\_module(\texttt{m})} & = \texttt{ε} & \text{(if} \vdash \texttt{m} : \texttt{extern\texttt{type}^\texttt{*}} \rightarrow \texttt{extern\texttt{type}^\texttt{\texttt{\texttt{*}}}^\texttt{*})} \\
\text{validate\_module(\texttt{m})} & = \texttt{error} & \text{(otherwise)}
\end{align*}
\]

\[
\text{instantiate\_module(store, module, externval\^*) : (store, moduleinst | error)}
\]

1. Try \texttt{instantiate\_module} in \texttt{store} with \texttt{external values externval\^*} as imports:
   1. If it succeeds with a \texttt{module instance moduleinst}, then let \texttt{result} be \texttt{moduleinst}.
   2. Else, let \texttt{result} be \texttt{error}.
2. Return the new store paired with \texttt{result}.

\[
\begin{align*}
\text{instantiate\_module(S, m, ev\^*)} & = (S', F.\texttt{module}) & \text{(if instantiate(S, m, ev\^*)} \rightarrow^* S'; F; \epsilon) \\
\text{instantiate\_module(S, m, ev\^*)} & = (S', \texttt{error}) & \text{(if instantiate(S, m, ev\^*)} \rightarrow^* S'; F; \texttt{trap})
\end{align*}
\]

\textbf{Note:} The store may be modified even in case of an error.
module_imports(module) : (name, name, extertype)*

1. Assert: module is valid with external import types extertype* and external export types extertype′*.
2. Let import* be the imports module.imports.
3. Assert: the length of import* equals the length of extertype*.
4. For each import_i in import* and corresponding extertype_i in extertype*, do:
   1. Let result_i be the triple (import_i.module, import_i.name, extertype_i).
5. Return the concatenation of all result_i, in index order.

module_exports(module) : (name, extertype)*

1. Assert: module is valid with external import types extertype* and external export types extertype′*.
2. Let export* be the exports module.exports.
3. Assert: the length of export* equals the length of extertype′*.
4. For each export_i in export* and corresponding extertype′_i in extertype′*, do:
   1. Let result_i be the pair (export_i.name, extertype′_i).
5. Return the concatenation of all result_i, in index order.

7.1.3 Exports

get_export(moduleinst, name) : external | error

1. Assert: due to validity of the module instance moduleinst, all its export names are different.
2. If there exists an exportinst_i in moduleinst.exports such that name exportinst_i.name equals name, then:
   (a) Return the external value exportinst_i.value.
3. Else, return error.

get_export(m, name) = m.exports[i].value (if m.exports[i].name = name)
get_export(m, name) = error (otherwise)

7.1.4 Functions

alloc_func(store, functype, hostfunc) : (store, funcaddr)

1. Let funcaddr be the result of allocating a host function in store with function type functype and host function code hostfunc.
2. Return the new store paired with funcaddr.

7.1. Embedding
alloc_func(S, ft, code) = (S', a) (if allochostfunc(S, ft, code) = S', a)

Note: This operation assumes that hostfunc satisfies the pre- and post-conditions required for a function instance with type functype.

Regular (non-host) function instances can only be created indirectly through module instantiation.

type_func(store, funcaddr) : functype
2. Assert: the external value func funcaddr is valid with external type func functype.
3. Return functype.
   type_func(S, a) = ft (if S ⊢ func a : func ft)

invoke_func(store, funcaddr, val*) : (store, val* | error)
2. Try invoking the function funcaddr in store with values val* as arguments:
   1. If it succeeds with values val" as results, then let result be val".
   2. Else it has trapped, hence let result be error.
3. Return the new store paired with result.
   invoke_func(S, a, v*) = (S', v") (if invoke(S, a, v*) \rightarrow *S'; F; v")
   invoke_func(S, a, v*) = (S', error) (if invoke(S, a, v*) \rightarrow *S'; F; trap)

Note: The store may be modified even in case of an error.

7.1.5 Tables

alloc_table(store, tabletype) : (store, tableaddr)
1. Let tableaddr be the result of allocating a table in store with table type tabletype.
2. Return the new store paired with tableaddr.
   alloc_table(S, tt) = (S', a) (if allocetable(S, tt) = S', a)

type_table(store, tableaddr) : tabletype
2. Assert: the external value table tableaddr is valid with external type table tabletype.
3. Return tabletype.
   type_table(S, a) = tt (if S ⊢ table a : table tt)
read_table(store, tableaddr, i) : funcaddr? | error

2. Assert: i is a non-negative integer.
3. Let ti be the table instance store.tables[tableaddr].
4. If i is larger than or equal to the length of ti.elem, then return error.
5. Else, return ti.elem[i].

\[
\begin{align*}
\text{read_table}(S, a, i) &= \text{fa}\quad \text{(if } S.\text{tables}[a].\text{elem}[i] = \text{fa}) \\
\text{read_table}(S, a, i) &= \text{error}\quad \text{(otherwise)}
\end{align*}
\]

write_table(store, tableaddr, i, funcaddr?) : store | error

2. Assert: i is a non-negative integer.
3. Let ti be the table instance store.tables[tableaddr].
4. If i is larger than or equal to the length of ti.elem, then return error.
5. Replace ti.elem[i] with the optional function address fa?.
6. Return the updated store.

\[
\begin{align*}
\text{write_table}(S, a, i, \text{fa}) &= S'\quad \text{(if } S' = S \text{ with } \text{tables}[a].\text{elem}[i] = \text{fa}) \\
\text{write_table}(S, a, i, \text{fa}) &= \text{error}\quad \text{(otherwise)}
\end{align*}
\]

size_table(store, tableaddr) : i32

2. Return the length of store.tables[tableaddr].elem.

\[
\text{size_table}(S, a) = n\quad \text{(if } |S.\text{tables}[a].\text{elem}| = n)
\]

grow_table(store, tableaddr, n) : store | error

2. Assert: n is a non-negative integer.
3. Try growing the table instance store.tables[tableaddr] by n elements:
   (a) If it succeeds, return the updated store.
   (b) Else, return error.

\[
\begin{align*}
\text{grow_table}(S, a, n) &= S'\quad \text{(if } S' = S \text{ with } \text{tables}[a] = \text{growtable}(S.\text{tables}[a], n)) \\
\text{grow_table}(S, a, n) &= \text{error}\quad \text{(otherwise)}
\end{align*}
\]
### 7.1.6 Memories

**alloc_mem(store, memtype) : (store, memaddr)**

1. Let `memaddr` be the result of *allocating a memory in* `store` with *memory type* `memtype`.
2. Return the new store paired with `memaddr`.
   
   $\text{alloc}\_\text{mem}(S, mt) = (S', a)$  
   (if $\text{alloc}\_\text{mem}(S, mt) = S'$, $a$)

**type_mem(store, memaddr) : memtype**

2. Assert: the external value `mem memaddr` is *valid* with external type `mem memtype`.
3. Return `memtype`.
   
   $\text{type}\_\text{mem}(S, a) = mt$  
   (if $S \vdash \text{mem } a : \text{mem } mt$)

**read_mem(store, memaddr, i) : byte | error**

2. Assert: `i` is a non-negative integer.
3. Let `mi` be the *memory instance* `store.mems[memaddr]`.
4. If `i` is larger than or equal to the length of `mi.data`, then return `error`.
5. Else, return the byte `mi.data[i]`.
   
   $\text{read}\_\text{mem}(S, a, i) = b$  
   (if $S.\text{mems}[a].\text{data}[i] = b$)
   
   $\text{read}\_\text{mem}(S, a, i) = \text{error}$  
   (otherwise)

**write_mem(store, memaddr, i, byte) : store | error**

2. Assert: `i` is a non-negative integer.
3. Let `mi` be the *memory instance* `store.mems[memaddr]`.
4. If `i` is larger than or equal to the length of `mi.data`, then return `error`.
5. Replace `mi.data[i]` with `byte`.
6. Return the updated store.
   
   $\text{write}\_\text{mem}(S, a, i, b) = S'$  
   (if $S' = S$ with `mems[a].data[i] = b`)
   
   $\text{write}\_\text{mem}(S, a, i, b) = \text{error}$  
   (otherwise)

**size_mem(store, memaddr) : i32**

2. Return the length of `store.mems[memaddr].data` divided by the page size.
   
   $\text{size}\_\text{mem}(S, a) = n$  
   (if $|S.\text{mems}[a].\text{data}| = n \cdot 64\text{Ki}$)
grow_mem(store, memaddr, n) : store | error

2. Assert: n is a non-negative integer.
3. Try growing the memory instance store.mems[memaddr] by n pages:
   (a) If it succeeds, return the updated store.
   (b) Else, return error.

grow_mem(S, a, n) = S' (if S' = S with mems[a] = growmem(S.mems[a], n))
grow_mem(S, a, n) = error (otherwise)

7.1.7 Globals

alloc_global(store, globaltype, val) : (store, globaladdr)

1. Let globaladdr be the result of allocating a global in store with global type globaltype and initialization value val.
2. Return the new store paired with globaladdr.

alloc_global(S, gt, v) = (S', a) (if allocglobal(S, gt, v) = S', a)

type_global(store, globaladdr) : globaltype

2. Assert: the external value global globaladdr is valid with external type global globaltype.
3. Return globaltype.

type_global(S, a) = gt (if S ⊨ global a : global gt)

read_global(store, globaladdr) : val

2. Let gi be the global instance store.globals[globaladdr].
3. Return the value gi.value.

read_global(S, a) = v (if S.globals[a].value = v)

write_global(store, globaladdr, val) : store | error

2. Let gi be the global instance store.globals[globaladdr].
3. If gi.mut is not var, then return error.
4. Replace gi.value with the value val.
5. Return the updated store.

write_global(S, a, v) = S' (if S.globals[a].mut = var ∧ S' = S with globals[a].value = v)
write_global(S, a, v) = error (otherwise)
7.2 Implementation Limitations

Implementations typically impose additional restrictions on a number of aspects of a WebAssembly module or execution. These may stem from:

- physical resource limits,
- constraints imposed by the embedder or its environment,
- limitations of selected implementation strategies.

This section lists allowed limitations. Where restrictions take the form of numeric limits, no minimum requirements are given, nor are the limits assumed to be concrete, fixed numbers. However, it is expected that all implementations have “reasonably” large limits to enable common applications.

Note: A conforming implementation is not allowed to leave out individual features. However, designated subsets of WebAssembly may be specified in the future.

7.2.1 Syntactic Limits

Structure

An implementation may impose restrictions on the following dimensions of a module:

- the number of types in a module
- the number of functions in a module, including imports
- the number of tables in a module, including imports
- the number of memories in a module, including imports
- the number of globals in a module, including imports
- the number of element segments in a module
- the number of data segments in a module
- the number of imports to a module
- the number of exports from a module
- the number of parameters in a function type
- the number of results in a function type
- the number of locals in a function
- the size of a function body
- the size of a structured control instruction
- the number of structured control instructions in a function
- the nesting depth of structured control instructions
- the number of label indices in a br_table instruction
- the length of an element segment
- the length of a data segment
- the length of a name
- the range of code points in a name
If the limits of an implementation are exceeded for a given module, then the implementation may reject the validation, compilation, or instantiation of that module with an embedder-specific error.

Note: The last item allows embedders that operate in limited environments without support for Unicode\(^{47}\) to limit the names of imports and exports to common subsets like ASCII\(^{48}\).

### Binary Format

For a module given in binary format, additional limitations may be imposed on the following dimensions:

- the size of a module
- the size of any section
- the size of an individual function’s code
- the number of sections

### Text Format

For a module given in text format, additional limitations may be imposed on the following dimensions:

- the size of the source text
- the size of any syntactic element
- the size of an individual token
- the nesting depth of folded instructions
- the length of symbolic identifiers
- the range of literal characters (code points) allowed in the source text

#### 7.2.2 Validation

An implementation may defer validation of individual functions until they are first invoked.

If a function turns out to be invalid, then the invocation, and every consecutive call to the same function, results in a trap.

Note: This is to allow implementations to use interpretation or just-in-time compilation for functions. The function must still be fully validated before execution of its body begins.

#### 7.2.3 Execution

Restrictions on the following dimensions may be imposed during execution of a WebAssembly program:

- the number of allocated module instances
- the number of allocated function instances
- the number of allocated table instances
- the number of allocated memory instances
- the number of allocated global instances

---

\(^{47}\) [http://www.unicode.org/versions/latest/](http://www.unicode.org/versions/latest/)

WebAssembly Specification, Release 1.0

- the size of a table instance
- the size of a memory instance
- the number of frames on the stack
- the number of labels on the stack
- the number of values on the stack

If the runtime limits of an implementation are exceeded during execution of a computation, then it may terminate that computation and report an embedder-specific error to the invoking code.

Some of the above limits may already be verified during instantiation, in which case an implementation may report exceedance in the same manner as for syntactic limits.

Note: Concrete limits are usually not fixed but may be dependent on specifics, interdependent, vary over time, or depend on other implementation- or embedder-specific situations or events.

7.3 Validation Algorithm

The specification of WebAssembly validation is purely declarative. It describes the constraints that must be met by a module or instruction sequence to be valid.

This section sketches the skeleton of a sound and complete algorithm for effectively validating code, i.e., sequences of instructions. (Other aspects of validation are straightforward to implement.)

In fact, the algorithm is expressed over the flat sequence of opcodes as occurring in the binary format, and performs only a single pass over it. Consequently, it can be integrated directly into a decoder.

The algorithm is expressed in typed pseudo code whose semantics is intended to be self-explanatory.

7.3.1 Data Structures

The algorithm uses two separate stacks: the operand stack and the control stack. The former tracks the types of operand values on the stack, the latter surrounding structured control instructions and their associated blocks.

```
type val_type = I32 | I64 | F32 | F64

type opd_stack = stack(val_type | Unknown)

type ctrl_stack = stack(ctrl_frame)

type ctrl_frame = {
  label_types : list(val_type)
  end_types : list(val_type)
  height : nat
  unreachable : bool
}
```

For each value, the operand stack records its value type, or Unknown when the type is not known.

For each entered block, the control stack records a control frame with the type of the associated label (used to type-check branches), the result type of the block (used to check its result), the height of the operand stack at the start of the block (used to check that operands do not underflow the current block), and a flag recording whether the remainder of the block is unreachable (used to handle stack-polymorphic typing after branches).

Note: In the presentation of this algorithm, multiple values are supported for the result types classifying blocks and labels. With the current version of WebAssembly, the list could be simplified to an optional value.
For the purpose of presenting the algorithm, the operand and control stacks are simply maintained as global variables:

```plaintext
var opds : opd_stack
var ctrls : ctrl_stack
```

However, these variables are not manipulated directly by the main checking function, but through a set of auxiliary functions:

```plaintext
func push_opd(type : val_type | Unknown) =
opds.push(type)

func pop_opd() : val_type | Unknown =
if (opds.size() = ctrls[0].height && ctrls[0].unreachable) return Unknown
error_if(opds.size() = ctrls[0].height)
return opds.pop()

func pop_opd(expect : val_type | Unknown) : val_type | Unknown =
let actual = pop_opd()
if (actual = Unknown) return expect
if (expect = Unknown) return actual
error_if(actual /= expect)
return actual

func push_opds(types : list(val_type)) =
foreach (t in types) push_opd(t)

func pop_opds(types : list(val_type)) =
foreach (t in reverse(types)) pop_opd(t)
```

Pushing an operand simply pushes the respective type to the operand stack.

Popping an operand checks that the operand stack does not underflow the current block and then removes one type. But first, a special case is handled where the block contains no known operands, but has been marked as unreachable. That can occur after an unconditional branch, when the stack is typed polymorphically. In that case, an unknown type is returned.

A second function for popping an operand takes an expected type, which the actual operand type is checked against. The types may differ in case one of them is Unknown. The more specific type is returned.

Finally, there are accumulative functions for pushing or popping multiple operand types.

Note: The notation stack[i] is meant to index the stack from the top, so that ctrls[0] accesses the element pushed last.

The control stack is likewise manipulated through auxiliary functions:

```plaintext
func push_ctrl(label : list(val_type), out : list(val_type)) =
let frame = ctrl_frame(label, out, opds.size(), false)
ctrls.push(frame)

func pop_ctrl() : list(val_type) =
error_if(ctrls.is_empty())
let frame = ctrls[0]
pop_opds(frame.end_types)
error_if(opds.size() /= frame.height)
ctrs.pop()
return frame.end_types

func unreachable() =
opds.resize(ctrls[0].height)
ctrls[0].unreachable := true
```

Pushing a control frame takes the types of the label and result values. It allocates a new frame record recording them along with the current height of the operand stack and marks the block as reachable.

7.3. Validation Algorithm
Popping a frame first checks that the control stack is not empty. It then verifies that the operand stack contains the right types of values expected at the end of the exited block and pops them off the operand stack. Afterwards, it checks that the stack has shrunk back to its initial height.

Finally, the current frame can be marked as unreachable. In that case, all existing operand types are purged from the operand stack, in order to allow for the stack-polymorphism logic in pop_opd to take effect.

**Note:** Even with the unreachable flag set, consecutive operands are still pushed to and popped from the operand stack. That is necessary to detect invalid examples like (unreachable (i32.const i64.add)). However, a polymorphic stack cannot underflow, but instead generates Unknown types as needed.

### 7.3.2 Validation of Opcode Sequences

The following function shows the validation of a number of representative instructions that manipulate the stack. Other instructions are checked in a similar manner.

**Note:** Various instructions not shown here will additionally require the presence of a validation context for checking uses of indices. That is an easy addition and therefore omitted from this presentation.

```rust
func validate(opcode) =
switch (opcode)
case (i32.add)
   pop_opd(i32)
   pop_opd(i32)
   push_opd(i32)

case (drop)
   pop_opd()

case (select)
   pop_opd(i32)
   let t1 = pop_opd()
   let t2 = pop_opd(t1)
   push_opd(t2)

case (unreachable)
   unreachable()

case (block t*)
   push_ctrl([t*], [t*])

case (loop t*)
   push_ctrl([], [t*])

case (if t*)
   pop_opd(i32)
   push_ctrl([t*], [t*])

case (end)
   let results = pop_ctrl()
   push_opds(results)

case (else)
   let results = pop_ctrl()
   push_ctrl(results, results)

case (br n)
```

(continues on next page)
error_if(ctrls.size() < n)
pop_opds(ctrls[n].label_types)
unreachable()

**case** (br_if n)
  error_if(ctrls.size() < n)
pop_opd(i32)
pop_opds(ctrls[n].label_types)
push_opds(ctrls[n].label_types)

**case** (br_table n* m)
  error_if(ctrls.size() < m)
  foreach (n in n*)
    error_if(ctrls.size() < n || ctrls[n].label_types != ctrls[m].label_types)
pop_opd(i32)
pop_opds(ctrls[m].label_types)
unreachable()

**Note:** It is an invariant under the current WebAssembly instruction set that an operand of Unknown type is never duplicated on the stack. This would change if the language were extended with stack operators like *dup*. Under such an extension, the above algorithm would need to be refined by replacing the Unknown type with proper type variables to ensure that all uses are consistent.

7.4 Custom Sections

This appendix defines dedicated custom sections for WebAssembly’s binary format. Such sections do not contribute to, or otherwise affect, the WebAssembly semantics, and like any custom section they may be ignored by an implementation. However, they provide useful meta data that implementations can make use of to improve user experience or take compilation hints.

Currently, only one dedicated custom section is defined, the name section.

7.4.1 Name Section

The name section is a custom section whose name string is itself ‘name’. The name section should appear only once in a module, and only after the data section.

The purpose of this section is to attach printable names to definitions in a module, which e.g. can be used by a debugger or when parts of the module are to be rendered in text form.

**Note:** All names are represented in Unicode⁴⁹ encoded in UTF-8. Names need not be unique.

Subsections

The data of a name section consists of a sequence of subsections. Each subsection consists of a

- a one-byte subsection id,
- the u32 size of the contents, in bytes,
- the actual contents, whose structure is depended on the subsection id.

⁴⁹ http://www.unicode.org/versions/latest/
namesec ::= section0(namedata)
namedata ::= n:name namesubsection* (if n = 'name')
namesubsection_N(B) ::= N:byte size:u32 B (if size = ||B||)

The following subsection ids are used:

<table>
<thead>
<tr>
<th>Id</th>
<th>Subsection</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>module name</td>
</tr>
<tr>
<td>1</td>
<td>function names</td>
</tr>
<tr>
<td>2</td>
<td>local names</td>
</tr>
</tbody>
</table>

Name Maps

A name map assigns names to indices in a given index space. It consists of a vector of index/name pairs in order of increasing index value. Each index must be unique, but the assigned names need not be.

\[
\text{namemap} ::= \text{vec(nameassoc)} \\
\text{nameassoc} ::= \text{idx name}
\]

An indirect name map assigns names to a two-dimensional index space, where secondary indices are grouped by primary indices. It consists of a vector of primary index/name map pairs in order of increasing index value, where each name map in turn maps secondary indices to names. Each primary index must be unique, and likewise each secondary index per individual name map.

\[
\text{indirectnamemap} ::= \text{vec(indirectnameassoc)} \\
\text{indirectnameassoc} ::= \text{idx namemap}
\]

Module Names

The module name subsection has the id 0. It simply consists of a single name that is assigned to the module itself.

\[
\text{modulenamesubsec} ::= \text{namesubsection}_0(name)
\]

Function Names

The function name subsection has the id 1. It consists of a name map assigning function names to function indices.

\[
\text{funcnamesubsec} ::= \text{namesubsection}_1(namemap)
\]

Local Names

The local name subsection has the id 2. It consists of an indirect name map assigning local names to local indices grouped by function indices.

\[
\text{localnamesubsec} ::= \text{namesubsection}_2(indirectnamemap)
\]
7.5 Soundness

The type system of WebAssembly is sound, implying both type safety and memory safety with respect to the WebAssembly semantics. For example:

- All types declared and derived during validation are respected at runtime; e.g., every local or global variable will only contain type-correct values, every instruction will only be applied to operands of the expected type, and every function invocation always evaluates to a result of the right type (if it does not trap or diverge).
- No memory location will be read or written except those explicitly defined by the program, i.e., as a local, a global, an element in a table, or a location within a linear memory.
- There is no undefined behavior, i.e., the execution rules cover all possible cases that can occur in a valid program, and the rules are mutually consistent.

Soundness also is instrumental in ensuring additional properties, most notably, encapsulation of function and module scopes: no locals can be accessed outside their own function and no module components can be accessed outside their own module unless they are explicitly exported or imported.

The typing rules defining WebAssembly validation only cover the static components of a WebAssembly program. In order to state and prove soundness precisely, the typing rules must be extended to the dynamic components of the abstract runtime, that is, the store, configurations, and administrative instructions.50

7.5.1 Values and Results

Values and results can be classified by value types and result types as follows.

Values $t.\text{const } c$

- The value is valid with value type $t$.

\[ \vdash t.\text{const } c : t \]

Results $val^*$

- For each value $val_i$ in $val^*$:
  - The value $val_i$ is valid with some value type $t_i$.
- Let $t^*$ be the concatenation of all $t_i$.
- Then the result is valid with result type $[t^*]$.

\[ \vdash val^* : [t^*] \]

Results $\text{trap}$

- The result is valid with result type $[t^*]$, for any sequence $t^*$ of value types.

\[ \vdash \text{trap} : [t^*] \]

7.5.2 Store Validity

The following typing rules specify when a runtime store $S$ is valid. A valid store must consist of function, table, memory, and global instances that are themselves valid, relative to $S$.

To that end, each kind of instance is classified by a respective function, table, memory, or global type. Module instances are classified by module contexts, which are regular contexts repurposed as module types describing the index spaces defined by a module.

**Store $S$**

- Each function instance $\text{funcinst}_i$ in $S.\text{funcs}$ must be valid with some function type $\text{functype}_i$.
- Each table instance $\text{tableinst}_i$ in $S.\text{tables}$ must be valid with some table type $\text{tabletype}_i$.
- Each memory instance $\text{meminst}_i$ in $S.\text{mems}$ must be valid with some memory type $\text{memtype}_i$.
- Each global instance $\text{globalinst}_i$ in $S.\text{globals}$ must be valid with some global type $\text{globaltype}_i$.
- Then the store is valid.

$$
(S \vdash \text{funcinst}_i : \text{functype}_i)^* \quad (S \vdash \text{tableinst}_i : \text{tabletype}_i)^* \\
(S \vdash \text{meminst}_i : \text{memtype}_i)^* \quad (S \vdash \text{globalinst}_i : \text{globaltype}_i)^* \\
S = \{\text{funcs funcinst}^*, \text{tables tableinst}^*, \text{mems meminst}^*, \text{globals globalinst}^*\} \\
\vdash S \text{ ok}
$$

**Function Instances** $\{\text{type functype}, \text{module moduleinst}, \text{code func}\}$

- The function type $\text{functype}$ must be valid.
- The module instance $\text{moduleinst}$ must be valid with some context $C$.
- Under context $C$, the function $\text{func}$ must be valid with function type $\text{functype}$.
- Then the function instance is valid with function type $\text{functype}$.

$$
\vdash \text{functype ok} \quad S \vdash \text{moduleinst} : C \quad C \vdash \text{func} : \text{functype} \\
S \vdash \{\text{type functype}, \text{module moduleinst}, \text{code func}\} : \text{functype}
$$

**Host Function Instances** $\{\text{type functype}, \text{hostcode hf}\}$

- The function type $\text{functype}$ must be valid.
- Let $[t_1^*] \rightarrow [t_2^*]$ be the function type $\text{functype}$.
- For every valid store $S_1$ extending $S$ and every sequence $\text{val}^*$ of values whose types coincide with $t_1^*$:
  - Executing $\text{hf}$ in store $S_1$ with arguments $\text{val}^*$ has a non-empty set of possible outcomes.
  - For every element $R$ of this set:
    * Either $R$ must be $\bot$ (i.e., divergence).
    * Or $R$ consists of a valid store $S_2$ extending $S_1$ and a result $\text{result}$ whose type coincides with $[t_2^*]$.
- Then the function instance is valid with function type $\text{functype}$.

$$
\forall S_1, \text{val}^*, \vdash S_1 \text{ ok} \wedge \vdash S \preceq S_1 \wedge \vdash \text{val}^* : [t_1^*] \implies \\
\text{hf}(S_1; \text{val}^*) \supset \emptyset \wedge \\
\forall R \in \text{hf}(S_1; \text{val}^*), \quad R = \bot \lor \\
\vdash [t_1^*] \rightarrow [t_2^*] \text{ ok} \\
\exists S_2, \text{result}, \vdash S_2 \text{ ok} \wedge \vdash S_1 \preceq S_2 \wedge \vdash \text{result} : [t_2^*] \wedge R = (S_2; \text{result}) \\
S \vdash \{\text{type } [t_1^*] \rightarrow [t_2^*, \text{hostcode hf}] : [t_1^*] \rightarrow [t_2^*] \}$
**Note:** This rule states that, if appropriate pre-conditions about store and arguments are satisfied, then executing the host function must satisfy appropriate post-conditions about store and results. The post-conditions match the ones in the execution rule for invoking host functions.

Any store under which the function is invoked is assumed to be an extension of the current store. That way, the function itself is able to make sufficient assumptions about future stores.

**Table Instances** \( \{ \text{elem } (fa)^n, \max m^? \} \)

- For each optional *function address* \( fa^n \) in the table elements \( (fa^n)^n \):
  - Either \( fa^n \) is empty.
  - Or the *external value* \( \text{func } fa \) must be *valid* with some *external type* \( \text{func } ft \).
- The *limits* \( \{ \min n, \max m^? \} \) must be *valid*.
- Then the table instance is valid with *table type* \( \{ \min n, \max m^? \} \) \( \text{anyfunc} \).

\[
\begin{align*}
(\forall S \vdash \text{func } fa : \text{func } \text{functype})^n & \vdash \{ \min n, \max m^? \} \text{ ok} \\
Theorem & \vdash \{ \text{elem } (fa^n)^n, \max m^? \} : \{ \min n, \max m^? \} \text{ anyfunc}
\end{align*}
\]

**Memory Instances** \( \{ \text{data } b^n, \max m^? \} \)

- The *limits* \( \{ \min n, \max m^? \} \) must be *valid*.
- Then the memory instance is valid with *memory type* \( \{ \min n, \max m^? \} \).

\[
\begin{align*}
Theorem & \vdash \{ \text{data } b^n, \max m^? \} : \{ \min n, \max m^? \}
\end{align*}
\]

**Global Instances** \( \{ \text{value } (t.\text{const } c), \text{mut } \text{mut} \} \)

- The global instance is valid with *global type* \( \text{mut } t \).

\[
\begin{align*}
Theorem & \vdash \{ \text{value } (t.\text{const } c), \text{mut } \text{mut} \} : \text{mut } t
\end{align*}
\]

**Export Instances** \( \{ \text{name } \text{name}, \text{value } \text{externval} \} \)

- The *external value* \( \text{externval} \) must be *valid* with some *external type* \( \text{externtype} \).
- Then the export instance is valid.

\[
\begin{align*}
Theorem & \vdash \text{externval} : \text{externtype} \\
Theorem & \vdash \{ \text{name } \text{name}, \text{value } \text{externval} \} \text{ ok}
\end{align*}
\]
Module Instances `moduleinst`

- Each function type `functype_i` in `moduleinst.types` must be valid.
- For each function address `funcaddr_i` in `moduleinst.funcaddrs`, the external value `func funcaddr_i` must be valid with some external type `functype_i`.
- For each table address `tableaddr_i` in `moduleinst.tableaddrs`, the external value `table tableaddr_i` must be valid with some external type `tabletype_i`.
- For each memory address `memaddr_i` in `moduleinst.memaddrs`, the external value `mem memaddr_i` must be valid with some external type `memtype_i`.
- For each global address `globaladdr_i` in `moduleinst.globaladdrs`, the external value `global globaladdr_i` must be valid with some external type `globaltype_i`.
- Each export instance `exportinst_i` in `moduleinst.exports` must be valid.
- For each export instance `exportinst_i` in `moduleinst.exports`, the name `exportinst_i.name` must be different from any other name occurring in `moduleinst.exports`.
- Let `functype'*` be the concatenation of all `functype_i` in order.
- Let `tabletype'*` be the concatenation of all `tabletype_i` in order.
- Let `memtype'*` be the concatenation of all `memtype_i` in order.
- Let `globaltype'*` be the concatenation of all `globaltype_i` in order.
- Then the module instance is valid with `context { types functype*, funcs functype'*, tables tabletype*, mems memtype*, globals globaltype* }`.

```
(S ⊢ func funcaddr : func functype)*
(S ⊢ table tableaddr : table tabletype)*
(S ⊢ mem memaddr : mem memtype)*
(S ⊢ global globaladdr : global globaltype)*
(S ⊢ exportinst ok)*
(exportinst.name)* disjoint
```

7.5.3 Configuration Validity

To relate the WebAssembly type system to its execution semantics, the typing rules for instructions must be extended to configurations `S;T`, which relates the store to execution threads.

Configurations and threads are classified by their result type. In addition to the store `S`, threads are typed under a return type `resulttype`, which controls whether and with which type a return instruction is allowed. This type is absent (⊥) except for instruction sequences inside an administrative frame instruction.

Finally, frames are classified with frame contexts, which extend the module contexts of a frame’s associated module instance with the locals that the frame contains.

Configurations `S;T`

- The store `S` must be valid.
• Under no allowed return type, the thread $T$ must be valid with some result type $\{t\}$. Then the configuration is valid with the result type $\{t\}$.

$$
\frac{S \vdash \text{ok} \quad S; \epsilon \vdash T : \{t\}}{S; T : \{P\}}
$$

**Threads $F; \text{instr}^*$**

• Let resulttype$^2$ be the current allowed return type.
• The frame $F$ must be valid with a context $C$.
• Let $C'$ be the same context as $C$, but with return set to resulttype$^2$.
• Under context $C'$, the instruction sequence $\text{instr}^*$ must be valid with some type $[] \rightarrow \{t\}$.
• Then the thread is valid with the result type $\{t\}$.

$$
\frac{S \vdash F : C \quad S; C, \text{resulttype}^2 \vdash \text{instr}^* : [] \rightarrow \{t\}}{S; \text{resulttype}^2 \vdash F; \text{instr}^* : \{P\}}
$$

**Frames $\{\text{locals val}^*, \text{module moduleinst}\}$**

• The module instance moduleinst must be valid with some module context $C$.
• Each value val in val$^*$ must be valid with some value type $t_i$.
• Let $t^*$ the concatenation of all $t_i$ in order.
• Let $C'$ be the same context as $C$, but with the value types $t^*$ prepended to the locals vector.
• Then the frame is valid with frame context $C'$.

$$
\frac{S \vdash \text{moduleinst} : C \quad (\vdash \text{val} : t^*)}{S \vdash \{\text{locals val}^*, \text{module moduleinst}\} : (C, \text{locals } t^*)}
$$

### 7.5.4 Administrative Instructions

Typing rules for administrative instructions are specified as follows. In addition to the context $C$, typing of these instructions is defined under a given store $S$. To that end, all previous typing judgements $C \vdash \text{prop}$ are generalized to include the store, as in $S; C \vdash \text{prop}$, by implicitly adding $S$ to all rules – $S$ is never modified by the pre-existing rules, but it is accessed in the extra rules for administrative instructions given below.

**trap**

• The instruction is valid with type $\{t^*_1\} \rightarrow \{t^*_2\}$, for any sequences of value types $t^*_1$ and $t^*_2$.

$$
S; C \vdash \text{trap} : \{t^*_1\} \rightarrow \{t^*_2\}
$$
invoke `funcaddr`

- The external function value `func funcaddr` must be valid with external function type `func([t_1] → [t_2])`.
- Then the instruction is valid with type `[t_1] → [t_2]`.

\[
S \vdash \text{func }\funcaddr : \func([t_1] \rightarrow [t_2]) \\
S; C \vdash \text{invoke funcaddr } : [t_1] \rightarrow [t_2]
\]

`init_elem tableaddr o x^n`

- The external table value `table tableaddr` must be valid with some external table type `table limits anyfunc`.
- The index `o + n` must be smaller than or equal to `limits.min`.
- The module instance `moduleinst` must be valid with some context `C`.
- Each function index `x_i` in `x^n` must be defined in the context `C`.
- Then the instruction is valid.

\[
S \vdash \text{table tableaddr } : \text{table limits anyfunc} \quad o + n \leq \text{limits.min} \\
S; C \vdash \text{init_elem tableaddr } o x^n \text{ ok}
\]

`init_data memaddr o b^n`

- The external memory value `mem memaddr` must be valid with some external memory type `mem limits`.
- The index `o + n` must be smaller than or equal to `limits.min` divided by the page size 64 Ki.
- Then the instruction is valid.

\[
S \vdash \text{mem memaddr } : \text{mem limits} \quad o + n \leq \text{limits.min} \cdot 64 \text{ Ki} \\
S; C \vdash \text{init_data memaddr } o b^n \text{ ok}
\]

`label_{instr_0} instr^* end`

- The instruction sequence `instr_0` must be valid with some type `[t_1] → [t_2]`.
- Let `C'` be the same context as `C`, but with the result type `[t_1]` prepended to the labels vector.
- Under context `C'`, the instruction sequence `instr^*` must be valid with `[] → [t_2]`.
- Then the compound instruction is valid with type `[] → [t_2]`.

\[
S; C \vdash instr_0 : [t_1] \rightarrow [t_2] \\
S; C, labels [t_1] \vdash instr^* : [] \rightarrow [t_2] \\
S; C \vdash label_{instr_0} instr^* end : [] \rightarrow [t_2]
\]

`frame_n(F) instr^* end`

- Under the return type `[t^n]`, the thread `F; instr^*` must be valid with result type `[t^n]`.
- Then the compound instruction is valid with type `[] → [t^n]`.

\[
S; t^n \vdash F; instr^* : [t^n] \\
S; C \vdash frame_n(F) instr^* end : [] \rightarrow [t^n]
\]
7.5.5 Store Extension

Programs can mutate the store and its contained instances. Any such modification must respect certain invariants, such as not removing allocated instances or changing immutable definitions. While these invariants are inherent to the execution semantics of WebAssembly instructions and modules, host functions do not automatically adhere to them. Consequently, the required invariants must be stated as explicit constraints on the invocation of host functions. Soundness only holds when the embedder ensures these constraints.

The necessary constraints are codified by the notion of store extension: a store state $S'$ extends state $S$, written $S \preceq S'$, when the following rules hold.

Note: Extension does not imply that the new store is valid, which is defined separately above.

Store $S$

- The length of $S.funs$ must not shrink.
- The length of $S.tables$ must not shrink.
- The length of $S.mems$ must not shrink.
- The length of $S.globals$ must not shrink.
- For each function instance $funcinst_i$ in the original $S.funs$, the new function instance must be an extension of the old.
- For each table instance $tableinst_i$ in the original $S.tables$, the new table instance must be an extension of the old.
- For each memory instance $meminst_i$ in the original $S.mems$, the new memory instance must be an extension of the old.
- For each global instance $globalinst_i$ in the original $S.globals$, the new global instance must be an extension of the old.

\[
\begin{align*}
S_1.funs &= funcinst^*_1 & S_2.funs &= funcinst^*_1 \cdot funcinst^*_2 & \quad (funcinst_1 \preceq funcinst_1')^* \\
S_1.tables &= tableinst^*_1 & S_2.tables &= tableinst^*_1 \cdot tableinst^*_2 & \quad (tableinst_1 \preceq tableinst_1')^* \\
S_1.mems &= meminst^*_1 & S_2.mems &= meminst^*_1 \cdot meminst^*_2 & \quad (meminst_1 \preceq meminst_1')^* \\
S_1.globals &= globalinst^*_1 & S_2.globals &= globalinst^*_1 \cdot globalinst^*_2 & \quad (globalinst_1 \preceq globalinst_1')^* \\
\end{align*}
\]

\[\quad \vdash S_1 \preceq S_2\]

Function Instance $funcinst$

- A function instance must remain unchanged.

\[\quad \vdash funcinst \preceq funcinst\]

Table Instance $tableinst$

- The length of $tableinst.elem$ must not shrink.
- The value of $tableinst.max$ must remain unchanged.

\[\quad n_1 \leq n_2 \quad \vdash \{elem (fa_1)^{n_1}, max \ m\} \preceq \{elem (fa_2)^{n_2}, max \ m\}\]
Memory Instance \textit{meminst}

- The length of \textit{meminst}.data must not shrink.
- The value of \textit{meminst}.max must remain unchanged.

\[
\frac{\text{\textit{data}}} \leq n_{1} \leq n_{2} \quad \implies \quad \{\text{\textit{data} } b_{1}, \text{\textit{max} } m\} \leq \{\text{\textit{data} } b_{2}, \text{\textit{max} } m\}
\]

Global Instance \textit{globalinst}

- The mutability \textit{globalinst}.mut must remain unchanged.
- The value type of the value \textit{globalinst}.value must remain unchanged.
- If \textit{globalinst}.mut is \textit{const}, then the value \textit{globalinst}.value must remain unchanged.

\[
\frac{\text{mut} = \text{var} \lor c_{1} = c_{2} \quad \implies \quad \{\text{\textit{value}} (t.\text{const} c_{1}), \text{\textit{mut} } \text{mut}\} \leq \{\text{\textit{value}} (t.\text{const} c_{2}), \text{\textit{mut} } \text{mut}\}}
\]

7.5.6 Theorems

Given the definition of \textit{valid configurations}, the standard soundness theorems hold.\textsuperscript{52}

\textbf{Theorem (Preservation).} If a \textit{configuration} \(S; T\) is \textit{valid} with \textit{result type} \([t^*]\) (i.e., \(\vdash S; T : [t^*]\)), and steps to \(S'; T'\) (i.e., \(S; T \leftrightarrow S'; T'\)), then \(S'; T'\) is a \textit{valid} configuration with the same \textit{result type} (i.e., \(\vdash S'; T' : [t^*]\)). Furthermore, \(S'\) is an \textit{extension} of \(S\) (i.e., \(\vdash S \leq S'\)).

A \textit{terminal thread} is one whose sequence of \textit{instructions} is a \textit{result}. A \textit{terminal configuration} is a \textit{configuration} whose thread is \textit{terminal}.

\textbf{Theorem (Progress).} If a \textit{configuration} \(S; T\) is \textit{valid} (i.e., \(\vdash S; T : [t^*]\)) for some \textit{result type} \([t^*]\), then either it is \textit{terminal}, or it can step to some \textit{configuration} \(S'; T'\) (i.e., \(S; T \leftrightarrow S'; T'\)).

From Preservation and Progress the soundness of the WebAssembly type system follows directly.

\textbf{Corollary (Soundness).} If a \textit{configuration} \(S; T\) is \textit{valid} (i.e., \(\vdash S; T : [t^*]\)) for some \textit{result type} \([t^*]\), then it either diverges or takes a finite number of steps to reach a \textit{terminal configuration} \(S'; T'\) (i.e., \(S; T \leftrightarrow *S'; T'\)) that is valid with the same \textit{result type} (i.e., \(\vdash S' ; T' : [t^*]\)) and where \(S'\) is an \textit{extension} of \(S\) (i.e., \(\vdash S \leq S'\)).

In other words, every thread in a \textit{valid configuration} either runs forever, traps, or terminates with a \textit{result} that has the expected \textit{type}. Consequently, given a \textit{valid store}, no \textit{computation} defined by \textit{instantiation} or \textit{invocation} of a \textit{valid module} can “crash” or otherwise (mis)\textit{behave} in ways not covered by the \textit{execution} semantics given in this \textit{specification}.

\textsuperscript{52}A machine-verified version of the formalization and soundness proof is described in the following article: Conrad Watt. Mechanising and Verifying the WebAssembly Specification. Proceedings of the 7th ACM SIGPLAN Conference on Certified Programs and Proofs (CPP 2018). ACM 2018.
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